# MHD turbulence in the solar corona and solar wind

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## Waves, turbulence, low-frequency fluctuations

Consider the 3D MHD equations,

$$\begin{split} \mathbf{u} &= \mathbf{u}(x,y,z,t) = \text{plasma velocity} \\ \mathbf{B} &= \mathbf{B}(x,y,z,t) = \text{magnetic field} \\ \rho(\frac{\partial \mathbf{u}}{\partial t} + \mathbf{u} \cdot \nabla \mathbf{u}) = -\nabla p + \mathbf{J} \times \mathbf{B} + \rho \nu \nabla^2 \mathbf{u} + \mathbf{f}_u(t) \end{split}$$

$$\frac{\partial \mathbf{B}}{\partial t} = \nabla \times (\mathbf{u} \times \mathbf{B}) + \eta \nabla^2 \mathbf{B} + \mathbf{f}_b(t)$$

 $\mathbf{J} = \nabla \times \mathbf{B} = \text{current density}, \quad \nabla \cdot \mathbf{B} = 0 \quad , \quad \nabla \cdot \mathbf{u} = 0$ 

And we will assume also a background magnetic field  $\mathbf{B}_0$ , so  $\mathbf{B} = \mathbf{B}_0 + \mathbf{b}$ .

We numerically (DNS) solve the MHD equations using a pseudospectral code. The fields are evolved in k-space, and we add forcing terms  $\mathbf{f}_k^u(t)$  and  $\mathbf{f}_k^b(t)$  to achieve a steady state. The forcing terms are narrow in k-space  $(1 \le k \le 2)$  and include a memory part and a random part. A component of the forcing is of the form:

$$\alpha_{i+1} = m\alpha_i + \sqrt{1 - m^2}r_{i+1}$$

with  $0 \le m \le 1$  the memory parameter and  $r_i$  a (uniform) random number.

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It can be seen that

$$< \alpha_n \alpha_{n+l} > \to m^l, \quad \text{when} \quad n \to \infty$$

By constructing a (discrete) time series with  $t_n = n\Delta t$ ,

$$< \alpha(t)\alpha(t+\tau_f) > \rightarrow e^{-t/\tau_f}$$

with  $\tau_f = l\Delta t$ ,  $m = 1 - \Delta t/\tau_f$ . So the forcing can be made to have a fixed chosen correlation time  $\tau_f$ . We numerically (DNS) solve the MHD equations using a pseudospectral code. The fields are evolved in k-space, and we add forcing terms  $\mathbf{f}_k^u(t)$  and  $\mathbf{f}_k^b(t)$  to achieve a steady state. The forcing terms are narrow in k-space  $(1 \le k \le 2)$  and include a memory part and a random part. A component of the forcing is of the form:

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We use units of length  $L_0 = 1/2\pi$  size of the box, that is  $L_0 = 1$ , and  $u_0 = \langle b^2 \rangle^{1/2}$   $(t = 0) = \langle u^2 \rangle^{1/2}$  (t = 0) = 1, and  $t_0 = L_0/u_0 = 1$ . We chose  $\tau_f = 1$ .

We consider **probes** inside the box, where we can measure magnetic and velocity fluctuations,  $\mathbf{b}(x, y, z, t)$ ,  $\mathbf{u}(x, y, z, t)$  as a function of time.



Dmitruk & Matthaeus, Phys. Plasmas 16, 1, 2009.

#### Time series



#### Frequency spectra



Recall Alfven waves, satisfy,

$$w = \mathbf{k} \cdot \mathbf{B_0} = k_{\parallel} B_0$$



Here  $B_0 = 8$  and we see the peaks at multiples of  $B_0$ . Also plotted with light line the spectrum in the case of linear ideal MHD (i.e., only waves).



We define the Signal to Noise Ratio,

$$SNR = \log_{10} \left[ \frac{P(w_0)}{P_0(w_0)} \right].$$

and the Wave Power Ratio,

WPR = 
$$\frac{\int_{w_1}^{w_2} [P(w) - P_0(w)] dw}{\int_{w>0} P(w) dw}$$

SNR = 0, 0.3, 0.6, 1.5, 3.1 for  $B_0=0, 1, 2, 8, 16$ WPR = 0, 0.1, 0.13, 0.03, 0.02 for  $B_0=0, 1, 2, 8, 16$ 

Although waves can be clearly distinguished (large SNR ratio), most of the power (WPR ratio) it is on eddies (turbulent fluctuations).

We can also look at the frequency spectrum of individual modes in k-space,



And the real and imaginary parts of a mode  $b_k$ , which for the case of a wave should be a circle



## Low-frequency fluctuations, 1/f noise

Look at low frequency fluctuations (Dmitruk & Matthaeus, Phys. Rev. E 76, 036305, 2007)



see solar wind observations in Matthaeus & Goldstein, Phys. Rev. Lett. 57, 495, 1986





Consider hydrodynamics (3D HD)  $\rightarrow$  no  $1/f \parallel$ 



Other systems with low frequency fluctuations: MHD2D, HD2D





Frequency spectra of individual modes

Ideal MHD ( $\eta = \nu = 0$ ) with non-zero magnetic helicity,  $H_m < \mathbf{a} \cdot \mathbf{b} >$ , where  $\nabla \times \mathbf{a} = \mathbf{b}$  is the potential vector. No DC field (i.e.  $B_0 = 0$ ).

Time behavior of the lowest k mode







Correlation function  $\langle b(t_0)b(t_0+t) \rangle$ 

Lack of single correlation time  $\rightarrow 1/f \parallel$ 

Phase space behavior of modes in complex plane,  $\mathbf{k} = (1, 0, 0)$ 



 $\mathbf{k} = (2, 0, 0)$ 



We also consider MHD and HD inside a sphere, with or without rotation  $\Omega$ ,

$$\begin{split} \frac{\partial \mathbf{u}}{\partial t} + \boldsymbol{\omega} \times \mathbf{u} + 2 \mathbf{\Omega} \times \mathbf{u} &= -\frac{1}{\rho} \nabla \mathcal{P} + \mathbf{j} \times \mathbf{B} \\ \frac{\partial \mathbf{B}}{\partial t} &= \nabla \times (\mathbf{u} \times \mathbf{B}) \end{split}$$

with null boundary conditions,  $\mathbf{B} \cdot \hat{n} = 0\mathbf{u} \cdot \hat{n}$  at the radius R = 1 of the sphere.



We use a Galerkin spectral code, with Chandrasekar-Kendall functions in the sphere (Dmitruk, Mininni, Pouquet, Servidio, Matthaeus, Phys. Rev. E 2011)



Ideal MHD in the sphere, with rotation



Ideal HD in the sphere, with rotation





$$\tau_k = l_k / u_k = (k u_k)^{-1}$$

So, for k = 1, we get  $\tau_k = t_0 = 1$ . Following Kolmogorov scaling,  $u_k \sim k^{-1/3}$  we can get

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where b(k), u(q), b(p) are generic Fourier mode amplitudes, with the constraint that k = p + q.

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# A nice example: geomagnetic field reversals



We solve ideal MHD equations inside a rotating sphere, and consider the dynamics of the magnetic dipole moment

$$\mu = \frac{1}{2} \int \mathbf{r} \times \mathbf{j} \, dV$$



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We found **reversals** !! These are long-time fluctuations...

Magnetic dipole 1/f frequency spectrum



Waiting time between reversals is compatible with geological observations (Cande-Kent 95).

