

# Expansion Method, its general properties and some applications

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*arXiv:1308.4832: collaboration with L. Andrianopoli,  
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# Contents

**I) Introduction and motivations**

**II) S-expansion method**

**III) Some applications**

**IV) Results and conclusions**



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# Introduction and motivations

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- 2) A  $G$  invariant polynomial of order  $n$  is a multilinear map

$$\langle \dots \rangle : \mathcal{G}^n \rightarrow \mathbb{C}$$

which satisfy the invariant condition

$$\forall \mathbf{T}_A \in \mathcal{G}, g \in G, \langle \mathbf{T}_1, \dots, \mathbf{T}_n \rangle = \langle g\mathbf{T}_1g^{-1}, \dots, g\mathbf{T}_ng^{-1} \rangle$$



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- 3) A gauge connection one form  $\mathbf{A} = A^A \mathbf{T}_A$  and its asociated strength field  $\mathbf{F} = d\mathbf{A} + \mathbf{A} \wedge \mathbf{A}$



## Examples:

Yang-Mills Theories:

$$\begin{aligned}\mathcal{L}_{\text{YM}}^{(d)}(A) &= \langle F \wedge * F \rangle, \\ &= F^A \wedge * F^B \langle T_A, T_B \rangle\end{aligned}$$

or a Chern-Simons Theories in  $d = 3$ :

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First example:  
*I.E. Segal*  
(1951)

### Physics Theories

Special Theory of  
Relativity

$(1/c \rightarrow 0)$

Newtonian  
Mechanics

### Symmetry Group

Poincaré's Group

?

Galileo's group

During the second half of the 20th century appeared in the literature:

Mechanism	Example
1. Contraction	(Anti)de-Sitter $\longrightarrow$ Poincaré
2. Deformation	Galileo $\longrightarrow$ Poincaré
3. Extension	Poincaré $\longrightarrow$ Super-Poincaré



During the second half of the 20th century appeared in the literature:

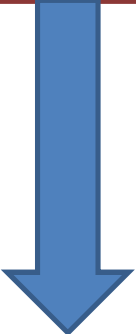
## Mechanism

## Example

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We focus on its generalizations (particularly one called **S-expansion**)

# Brief history of these methods



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Ex:  $ISO(3,1)$  from  $SO(3,2)$

$$[M_{ab}, M_{cd}] = g_{ac}M_{bd} - g_{bc}M_{ad} - g_{ad}M_{bc} + g_{bd}M_{ac}$$

$$a, c = 1, \dots, 5$$

Defining  $M_{5\mu} = RP_{\mu}$  with  $\mu, \nu = 1, \dots, 4$  it leads to

$$[P_{\mu}, P_{\nu}] = \frac{1}{R^2} [M_{5\mu}, M_{5\nu}] = \frac{1}{R^2} g_{55} M_{\mu\nu}$$

$$[M_{\mu\nu}, P_{\rho}] = \frac{1}{R} [M_{\mu\nu}, M_{5\rho}] = \frac{1}{R} (-g_{\mu\rho} M_{\nu 5} + g_{\nu\rho} M_{\mu 5})$$

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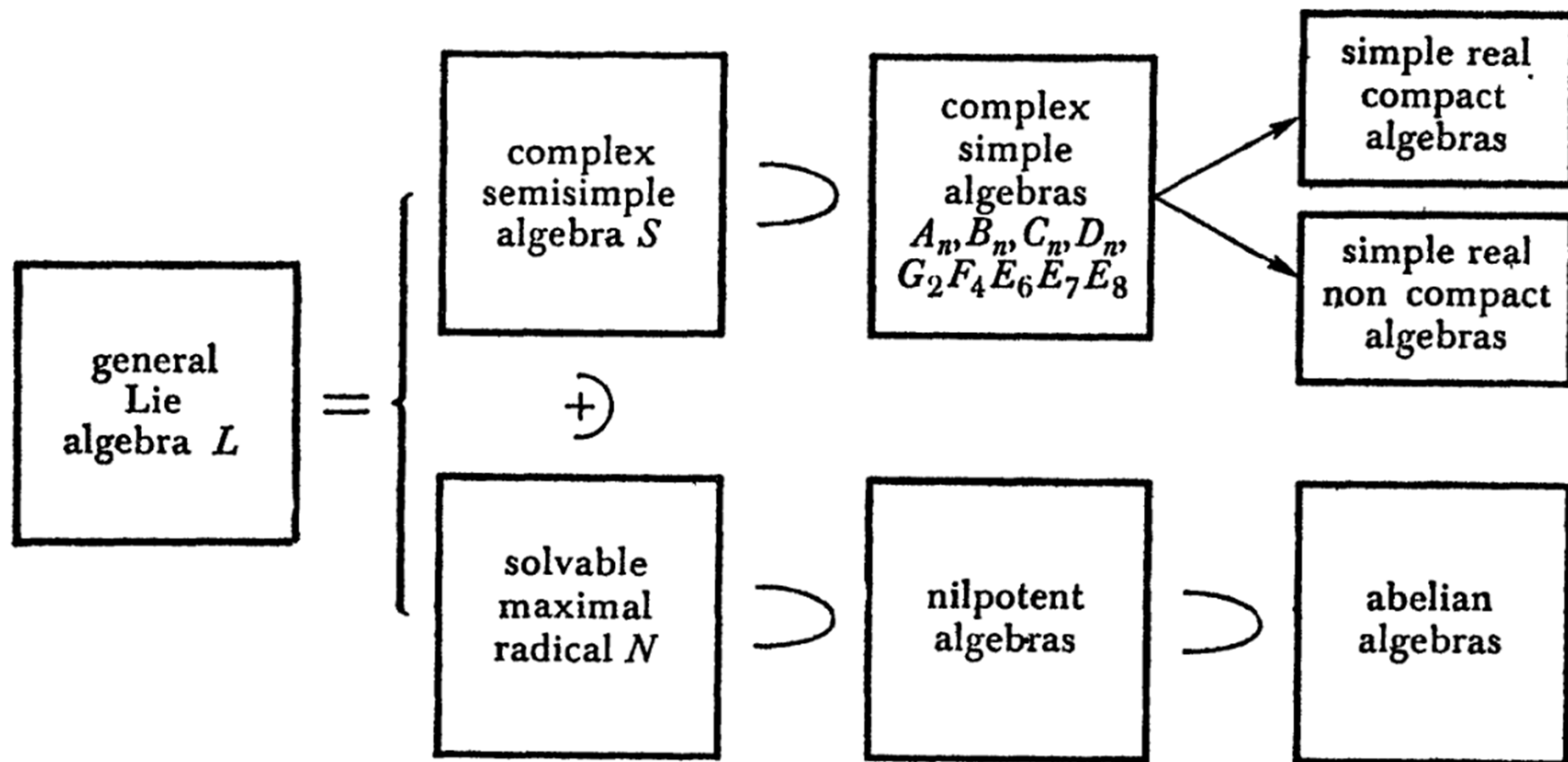
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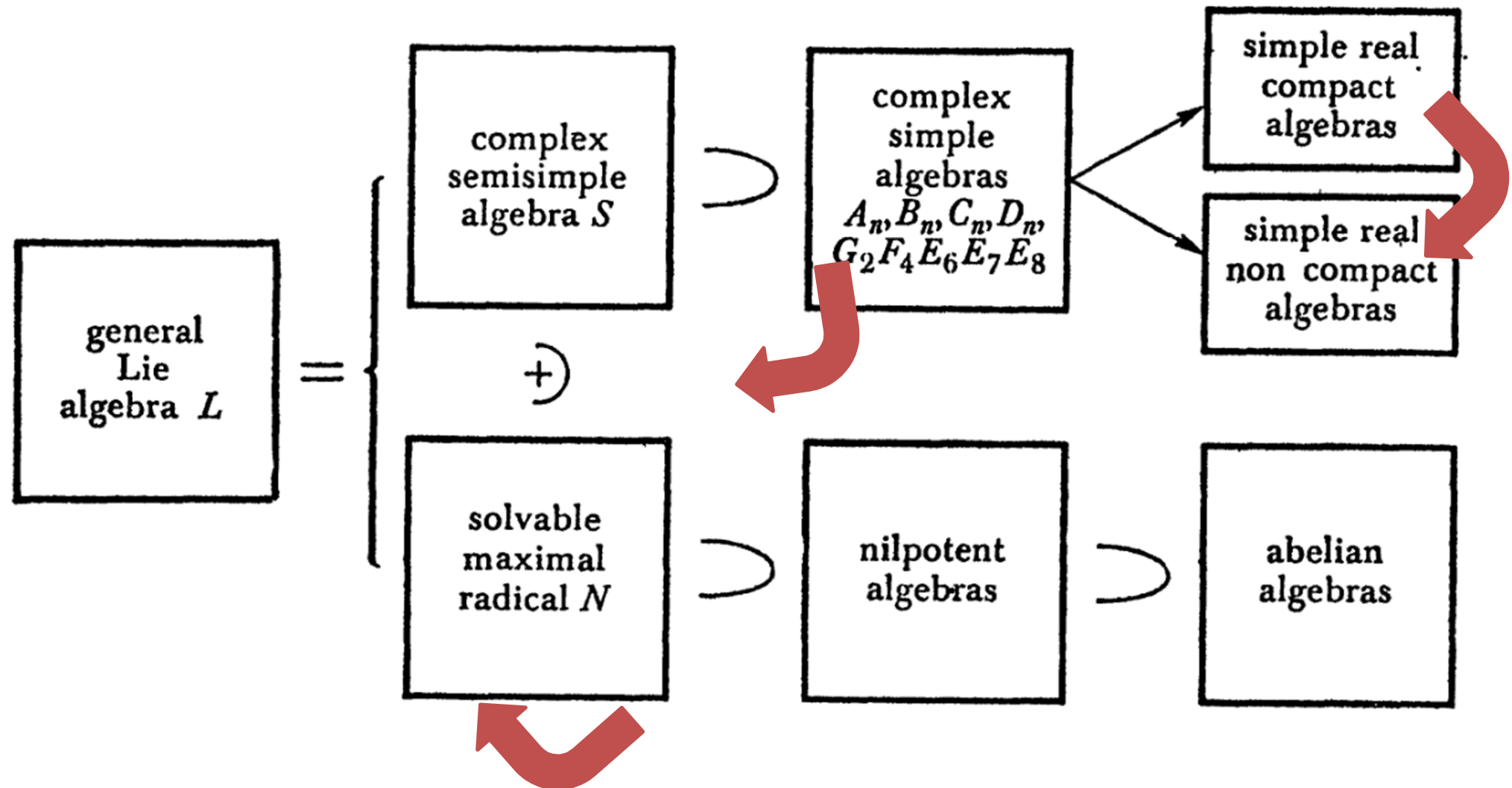
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# Classification of Lie algebras



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Many physical applications have been appeared by using this methods.



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This motivates the following question:

Given two algebras

$A$  and  $B$

Can these algebras be related by some contraction or expansion method?

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## S-expansion method

Here we review the main characteristics of the method.  
For further details, see the original article:

[1] F. Izaurieta, E. Rodríguez, P. Salgado, J.Math.Phys.47:123512,2006  
*arXiv: 0606215*



# S-expansion method



## Ingredients:

- 1) A Lie algebra  $\mathcal{G}$  with basis  $\{\mathbf{T}_A\}_{A=1}^{\dim \mathcal{G}}$
- 2) A finite abelian semigroup  $S = \{\lambda_\alpha\}_{\alpha=1}^n$   
(there is a composition law  $\lambda_\alpha \lambda_\beta$  which is closed and asociative)

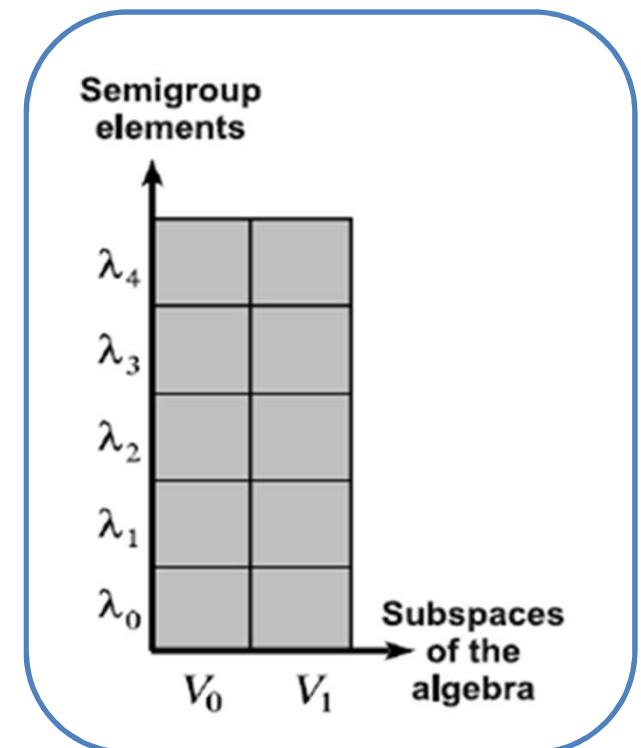
# S-expansion method

Steps:

I) Construction of  $\mathcal{G}_S = S \otimes \mathcal{G}$  with basis  $\{\mathbf{T}_{(A,\alpha)} = \lambda_\alpha \otimes \mathbf{T}_A\}$  and define the induced Lie product:

$$[\mathbf{T}_{(A,\alpha)}, \mathbf{T}_{(B,\beta)}] = \lambda_\alpha \lambda_\beta \otimes [\mathbf{T}_A, \mathbf{T}_B]$$

*First result:*  $\mathcal{G}_S = S \otimes \mathcal{G}$  is a Lie algebra, called the **expanded algebra**

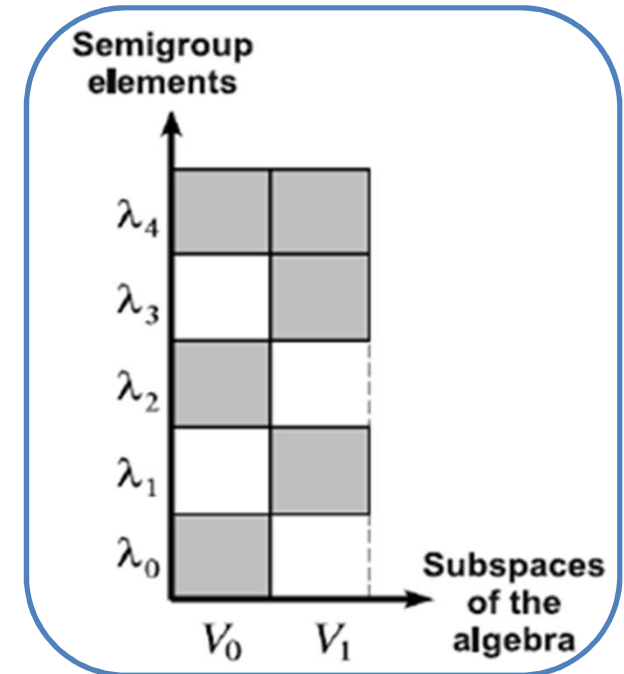




## S-expansion method

II) Suppose that  $\mathcal{G} = \bigoplus_{p \in I} V_p$ ,  $S = \bigcup_{p \in I} S_p$   
 satisfying respectively:

$$[V_p, V_q] \subset \bigoplus_{r \in i(p,q)} V_r \quad \text{and} \quad S_p \times S_q \subset \bigcup_{r \in i(p,q)} V_r$$



Perform the following construction  $\mathcal{G}_{S,R} = \bigoplus_{p \in I} S_p \otimes V_p$

*Second result:*  $\mathcal{G}_{S,R}$  is a subalgebra called the **resonant subalgebra**



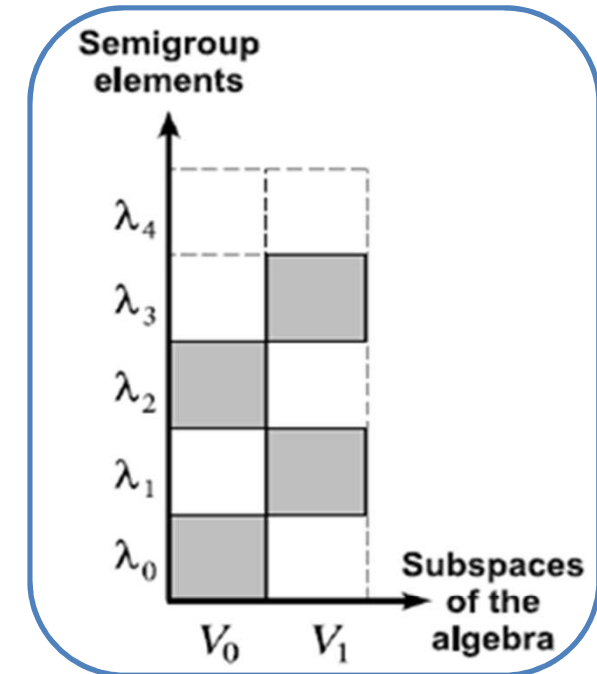


## S-expansion method

III) Suppose that there is an element  $0_S$  which satisfies  $0_S \lambda_\alpha = 0_S \forall \lambda_\alpha \in S$

*Third result:* the sector  $0_S \otimes \mathcal{G}$  can be removed from the expanded algebra to obtain the so called **reduced algebra**.

**Observation:** Steps II and III are independent, but can also be applied simultaneously.

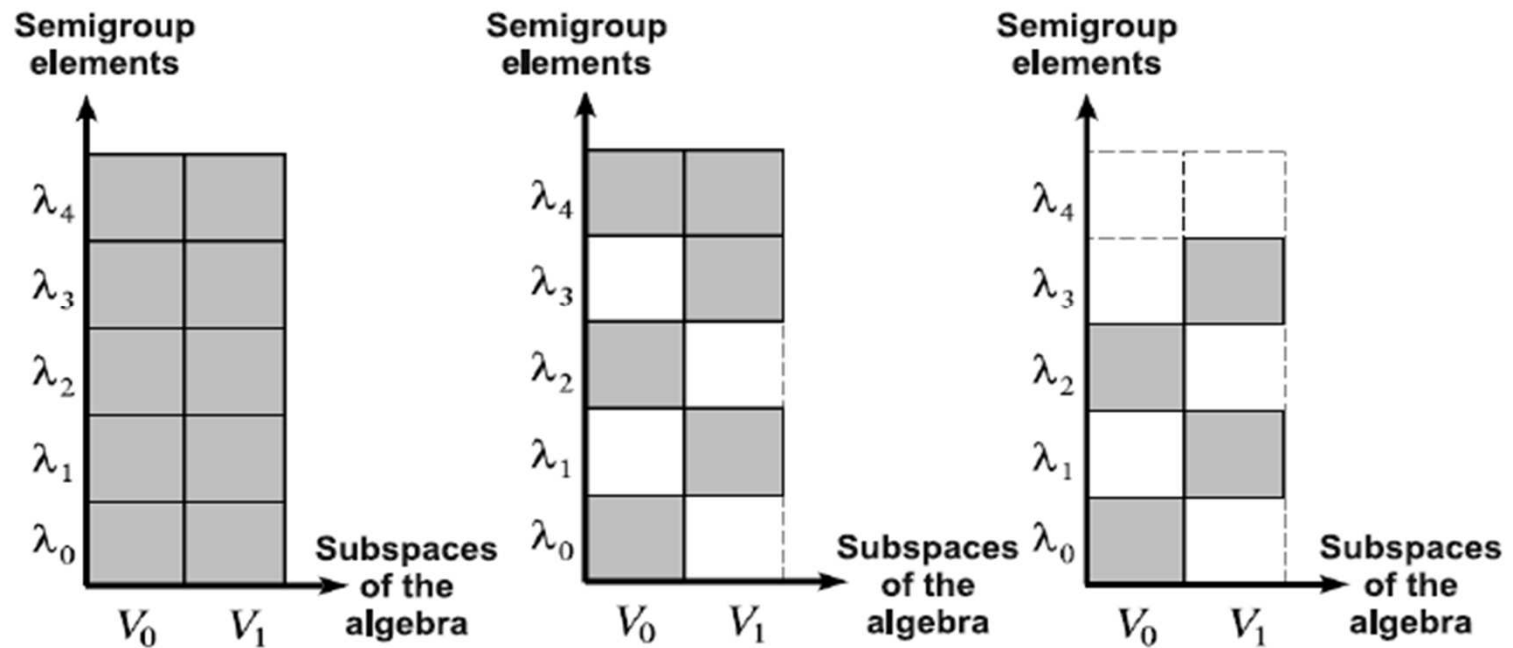




## S-expansion

In general the S-expansion method consist in a serie of steps:

- Obtain the S-expanded algebra
- Find the (resonant) subalgebras
- Perform a reduction.





## S-expansion method

- ➔ Inönü-Wigner contraction,
- ➔ its generalizations (Weimar-Woods contractions),
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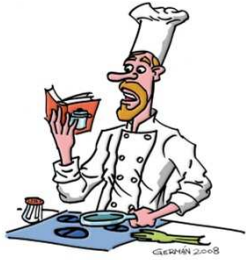
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$$S_E^{(N)} = \{\lambda_0, \lambda_1, \dots, \lambda_N, \lambda_{N+1}\} \text{ with}$$

$$\lambda_\alpha \lambda_\beta = \lambda_{\alpha+\beta}, \text{ if } \alpha + \beta < N + 1$$

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$$S = S_0 \cup S_1 \text{ with } \left\{ \begin{array}{l} S_0 = \{\lambda_{2m}, \text{ with } m = 0, \dots, [\frac{N}{2}]\} \cup \{\lambda_{N+1}\} \\ S_1 = \{\lambda_{2m+1}, \text{ with } m = 0, \dots, [\frac{N-1}{2}]\} \cup \{\lambda_{N+1}\} \\ S_0 \times S_0 \subset S_0 \\ S_0 \times S_1 \subset S_1 \\ S_1 \times S_1 \subset S_0 \end{array} \right.$$





## S-expansion method

Example: Inönü-Wigner contraction as an  $S_E^{(1)}$ -expansion

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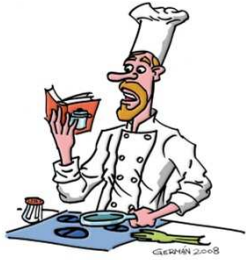
Consider the semigroup  $S_E^{(1)} = \{\lambda_0, \lambda_1, \lambda_2\}$  with

$$\begin{aligned} \lambda_\alpha \lambda_\beta &= \lambda_{\alpha+\beta}, \text{ if } \alpha + \beta < 2 \\ \lambda_\alpha \lambda_\beta &= \lambda_2, \quad \text{if } \alpha + \beta \geq 2 \end{aligned}$$

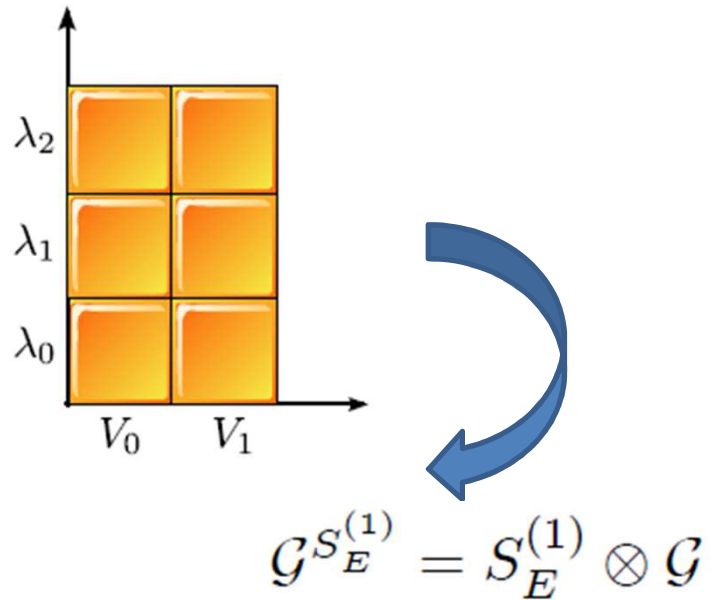
$$S_E^{(1)} = S_0 \cup S_1$$

$$\left\{ \begin{aligned} S_0 &= \{\lambda_0, \lambda_2\} \\ S_1 &= \{\lambda_1, \lambda_2\} \\ S_0 \times S_0 &\subset S_0 \\ S_0 \times S_1 &\subset S_1 \\ S_1 \times S_1 &\subset S_0 \end{aligned} \right.$$



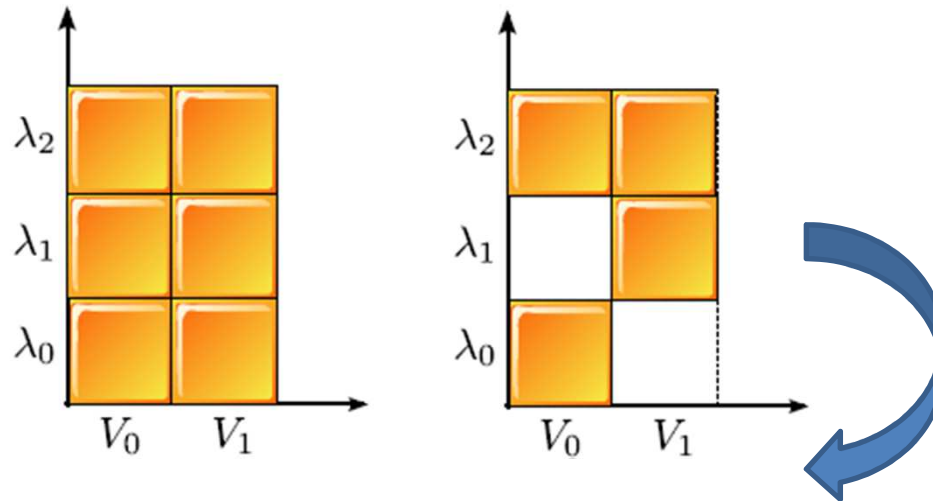


## S-expansion method





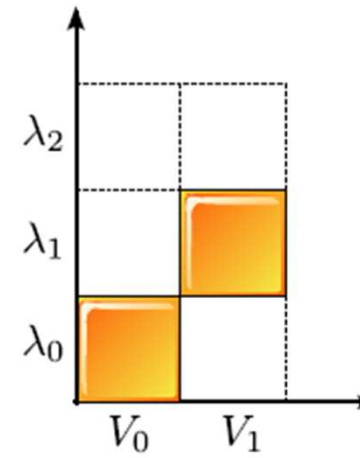
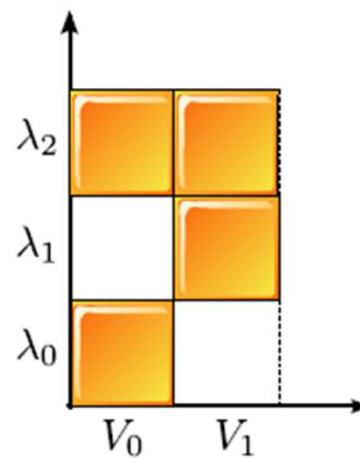
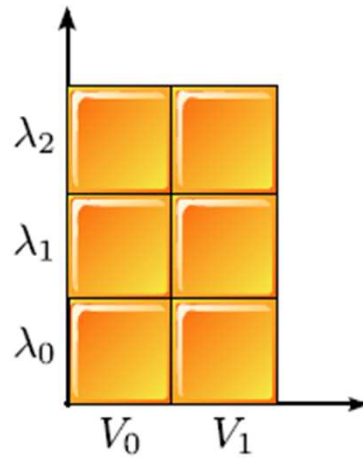
# S-expansion method



$$\mathcal{G}_R^{S_E^{(1)}} = (S_0 \otimes V_0) \oplus (S_1 \otimes V_1)$$



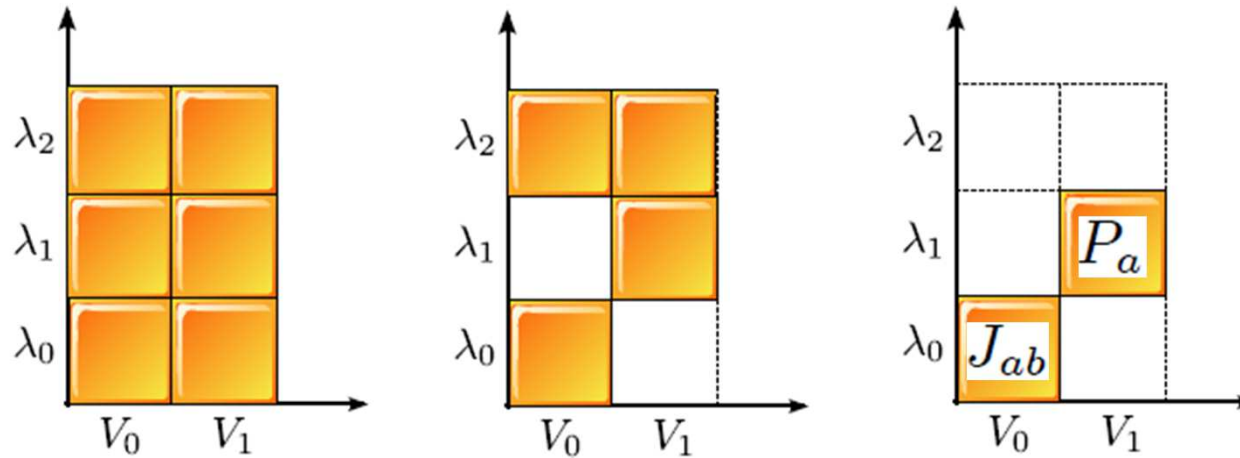
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$$\mathcal{G}_{R,\text{red}}^{S_E^{(1)}} = [(S_0 \otimes V_0) \oplus (S_1 \otimes V_1)]_{\text{red}}$$



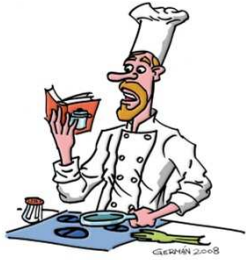
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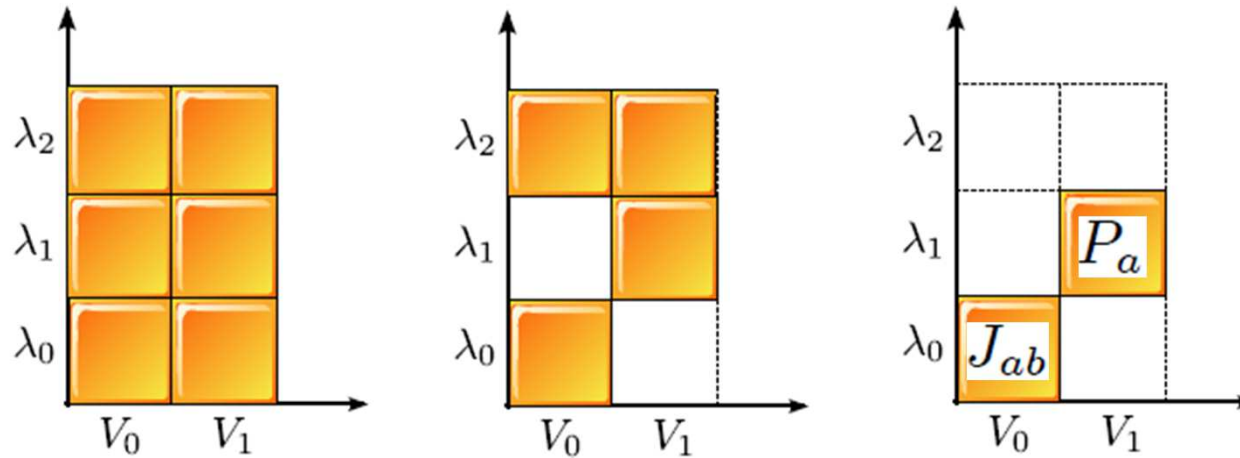
$$J_{ab} = \lambda_0 \otimes \bar{J}_{ab}$$

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$$\mathcal{G}_{R,\text{red}}^{S_E^{(1)}} = [(S_0 \otimes V_0) \oplus (S_1 \otimes V_1)]_{\text{red}} = \langle \{ \lambda_0 \bar{J}_{ab}, \lambda_1 \bar{P}_a \} \rangle = \langle \{ J_{ab}, P_a \} \rangle$$



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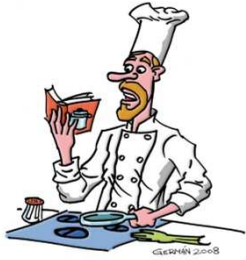
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$$[J_{ab}, P_c] = \lambda_0 \lambda_1 \otimes [\bar{J}_{ab}, \bar{P}_c] \sim \lambda_1 \bar{P}_c \sim P_c$$

$$[P_a, P_b] = \lambda_1 \lambda_1 \otimes [\bar{P}_a, \bar{P}_b] \sim \lambda_2 \bar{J}_{ab} \sim 0$$

IW contraction.



# S-expansion method

Example: The  $\mathcal{B}$  algebra

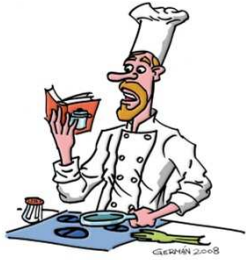
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Is easy to check that  $S = S_0 \cup S_1$  satisfy

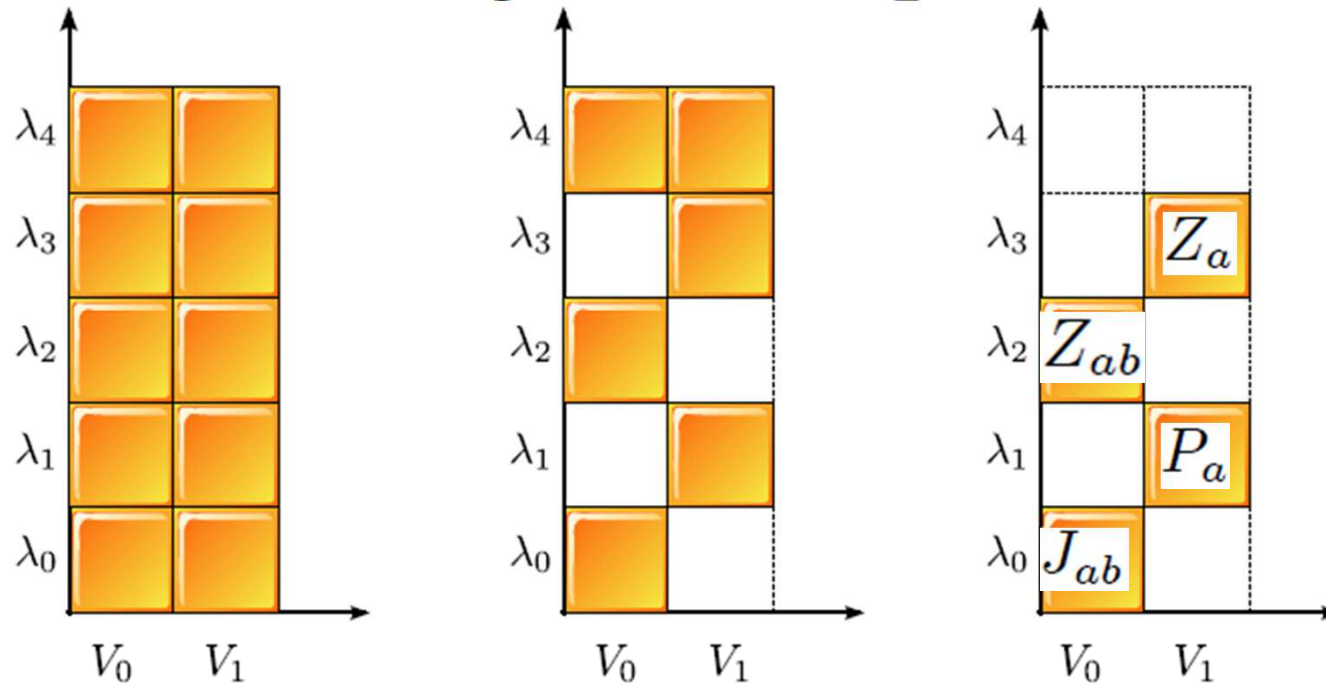
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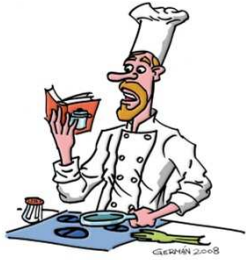
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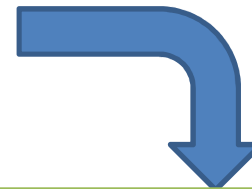


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$$\mathcal{B} = \{J_{ab}, Z_{ab}, P_a, Z_a\}$$

$$[\mathbf{T}_{(A,\alpha)}, \mathbf{T}_{(B,\beta)}] = \lambda_\alpha \lambda_\beta \otimes [\mathbf{T}_A, \mathbf{T}_B]$$



$$\begin{aligned} [P_a, P_b] &= Z_{ab} , & [J_{ab}, P_c] &= P_a \eta_{bc} - P_b \eta_{ac} , \\ [J_{ab}, J_{cd}] &= -J_{ac} \eta_{bd} + J_{bc} \eta_{ad} - J_{bd} \eta_{ac} + J_{ad} \eta_{bc} , \\ [Z_a, Z_b] &= [Z_{ab}, Z_c] = [Z_{ab}, Z_{cd}] = [P_a, Z_b] = 0 , \\ [Z_{ab}, P_c] &= [J_{ab}, Z_c] = Z_a \eta_{bc} - Z_b \eta_{ac} , \\ [J_{ab}, Z_{cd}] &= -Z_{ac} \eta_{bd} + Z_{bc} \eta_{ad} - Z_{bd} \eta_{ac} + Z_{ad} \eta_{bc} . \end{aligned}$$

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II) S-expansion method

**III) Some applications**

IV) Results and conclusions



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For further details about CS theories see [2].

[2] J. Zanelli, *arXiv: 0502193*





# Applications in Chern-Simons Theories

## 1) CS action for the M algebra:

In ref. [3] the **M algebra** is obtained from the **Osp(32/1) algebra** using the *dAIPV-expansion* method.

[3] J. A. de Azcárraga, J. M. Izquierdo, M. Picón, O. Varela, Nucl. Phys. B **662** (2003) 185 *arXiv: 0212347*

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- on [*arXiv: 0606225*] it is shown that the **supertrace is not a good choice**





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- the S-expansion procedure provide **an invariant tensor, different from the supertrace**, which leads to a theory with a richer structure.
- the S-expansion method **does not solve** the problem of classifying all invariant tensors for non-semisimple algebras, it **at least gives invariant tensors different from the supertrace** that are useful for the construction of the mentioned gauge theories of gravity.



# Applications in Chern-Simons Theories

## 2) Dual formulation:

A dual formulation of S-expansion method is given in [5].  
permits to perform the expansion at the level of the Lagrangian.

[5] F. Izaurieta, A. Pérez, E. Rodríguez, P. Salgado, Jour.Math. Phys.  
**50** 7 073511 (2009) *arXiv: 0903.4712*



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As an example, this permit to obtain **3D CS AdS** gravity from *exotic gravity* (because  $SO(2,2)$  can be regarded as an expansion of  $SO(2,1)$ )

[5] F. Izaurieta, A. Pérez, E. Rodríguez, P. Salgado, Jour.Math. Phys. **50** 7 073511 (2009) *arXiv: 0903.4712*



# Applications in Chern-Simons Theories

## 3) Standard General Relativity from CS theories in $d = 5$

In ref. [6] it was observed that

$$L_{\text{AdS}}^{(5)} = \kappa \varepsilon_{abcde} \left( \frac{1}{5\ell^5} e^a e^b e^c e^d e^e + \frac{2}{3\ell^3} R^{ab} e^c e^d e^e + \right. \\ \left. + \frac{1}{\ell} R^{ab} R^{cd} e^e \right).$$

does not leave E-H term alone in any limit of the  $\ell$  parameter!

[6] J. D. Edelstein, M. Hassaine, R. Troncoso, J. Zanelli, Phys. Lett. B **640** (2006) 278. *arXiv: 0605174*



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does not leave E-H term alone in any limit of the  $\ell$  parameter!

➡ It was proposed to construct a CS action for an **expansion of AdS** symmetry in  $D=5$  and to study if there is a connection with GR.

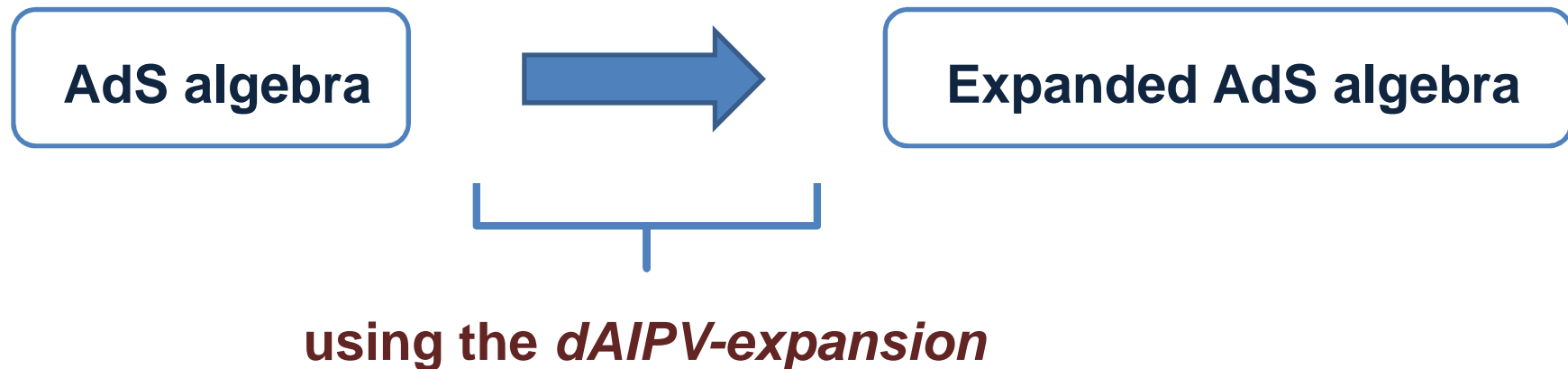
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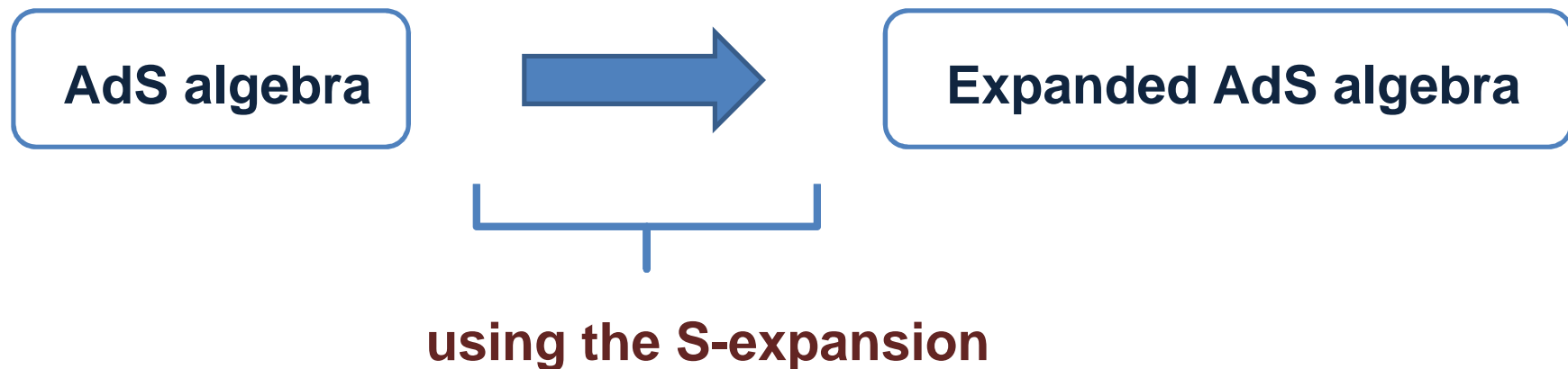
- Equations of motion impose too restrictive conditions on the geometry and,
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Therefore using the *dAIPV-expansion* method does not permit to connect a CS theory with 5D GR.

# Applications in Chern-Simons Theories

## 3) Standard General Relativity from CS theories in $d = 5$

The same idea was followed in ref. [7], but using *S-expansion*



[7] F. Izaurieta, P. Minning, A. Pérez, E. Rodríguez and P. Salgado, Phys. Lett. B **678** (2009) 213 *arXiv: 0905.2187*

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## 3) Standard General Relativity from CS theories in $d = 5$

### *Result:*

A CS action constructed in terms of the connection

$$A \rightarrow \tilde{A} = e^a P_a + \frac{1}{2} \omega^{ab} J_{ab} + h^a Z_a + \frac{1}{2} \kappa^{ab} Z_{ab} .$$

valuated in the algebra  $\mathcal{B}$  introduced before is given by

$$L_{\text{CS}}^{(5)} = \alpha_1 \ell^2 \varepsilon_{abcde} R^{ab} R^{cd} e^e + \alpha_3 \varepsilon_{abcde} \left( \frac{2}{3} R^{ab} e^c e^d e^e + \right. \\ \left. + 2\ell^2 k^{ab} R^{cd} T^e + \ell^2 R^{ab} R^{cd} h^e \right)$$



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➡ This action leads to GR in the critic limit  $\ell = 0$  .



# Applications in Chern-Simons Theories

## 4) Cosmological and Black hole solutions

In refs. [8,9] there were found a *black hole* and a *cosmological solution* for the Chern-Simons theory constructed in terms of the  $\mathcal{B}$  algebra.

[8] C. A. C. Quinzacara and P. Salgado, Phys. Rev. D **85**, 124026 (2012)

[9] F. Gomez, P. Minning, and P. Salgado, Phys. Rev. D **84**, 063506 (2011)



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# General properties of the expansion methods of Lie algebras

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# General properties of the expansion methods of Lie algebras

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- all of them can be considered as a particular case of an *S-expansion* with a semigroup of the family:

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Expansions with **other semigroups** can generate algebras that cannot be reached nor by any *contraction* neither by a *dAIPV expansion*.

# General properties of the expansion methods of Lie algebras

An example is given in [10].

[10] R. Caroca, I. Kondrashuk, N. Merino and F. Nadal, J. Phys. A: Math. Theor. 46 (2013) 225201 (24pp), *arXiv: 1104.3541*

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## Bianchi spaces and their three-dimensional isometries as $S$ -expansions of two-dimensional isometries

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**Principal Idea:** can be related 2 and 3-dimensional isometries?

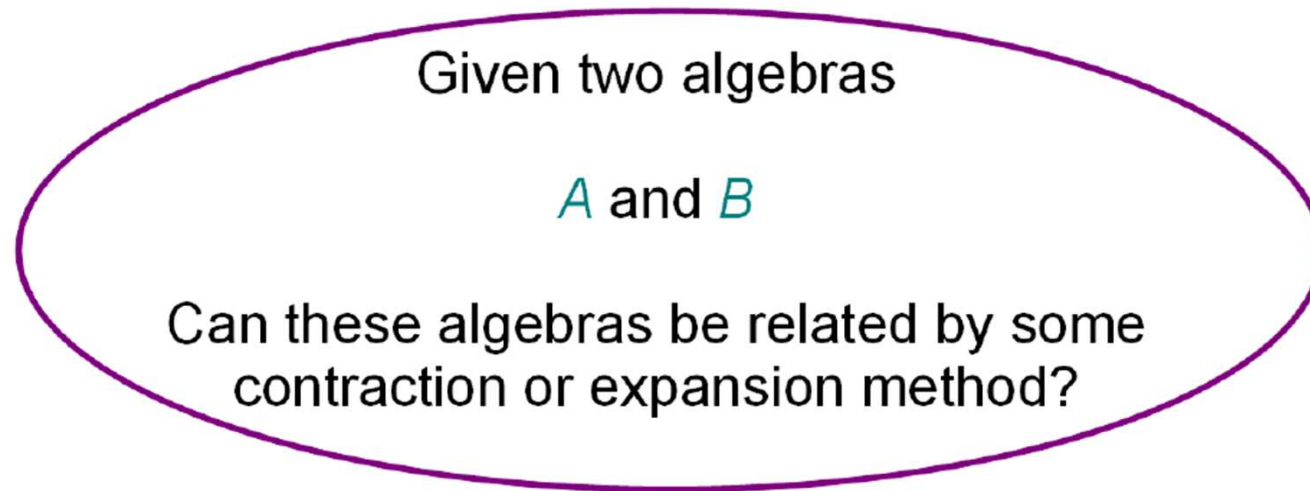
Considering the two set of algebras:  $[X_1, X_2] = 0$  and  $[X_1, X_2] = X_1$

Group	Algebra
→ type I	$[X_1, X_2] = [X_1, X_3] = [X_2, X_3] = 0$
→ type II	$[X_1, X_2] = [X_1, X_3] = 0, [X_2, X_3] = X_1$
→ type III	$[X_1, X_2] = [X_2, X_3] = 0, [X_1, X_3] = X_1$
type IV	$[X_1, X_2] = 0, [X_1, X_3] = X_1, [X_2, X_3] = X_1 + X_2$
→ type V	$[X_1, X_2] = 0, [X_1, X_3] = X_1, [X_2, X_3] = X_2$
type VI	$[X_1, X_2] = 0, [X_1, X_3] = X_1, [X_2, X_3] = hX_2,$ where $h \neq 0, 1$
type VII <sub>1</sub>	$[X_1, X_2] = 0, [X_1, X_3] = X_2, [X_2, X_3] = -X_1$
type VII <sub>2</sub>	$[X_1, X_2] = 0, [X_1, X_3] = X_2, [X_2, X_3] = -X_1 + hX_2,$ where $h \neq 0$ ( $0 < h < 2$ ).
type VIII	$[X_1, X_2] = X_1, [X_1, X_3] = 2X_2, [X_2, X_3] = X_3$
type IX	$[X_1, X_2] = X_3, [X_2, X_3] = X_1, [X_3, X_1] = X_2$



# General properties of the expansion methods of Lie algebras

Therefore, to answer the general question (given in *Introduction*):



we need to consider the **complete family of abelian semigroups**.

# General properties of the expansion methods of Lie algebras

We need to consider the *history about finite semigroup*:

order	$Q = \#$ semigroups	
1	1	
2	4	
3	18	
4	126	[Forsythe '54]
5	1,160	[Motzkin, Selfridge '55]
6	15,973	[Plemmons '66]
7	836,021	[Jurgensen, Wick '76]
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# General properties of the expansion methods of Lie algebras

We have developed a procedure to answer that question in [11].

[11] L. Andrianopoli, N. Merino, F. Nadal, M. Trigiant, *General properties of the S-expansion method*, J. Phys. A: Math. Theor. 46 (2013) 365204 (33pp) [arXiv:1308.4832](https://arxiv.org/abs/1308.4832)

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## General properties of the expansion methods of Lie algebras

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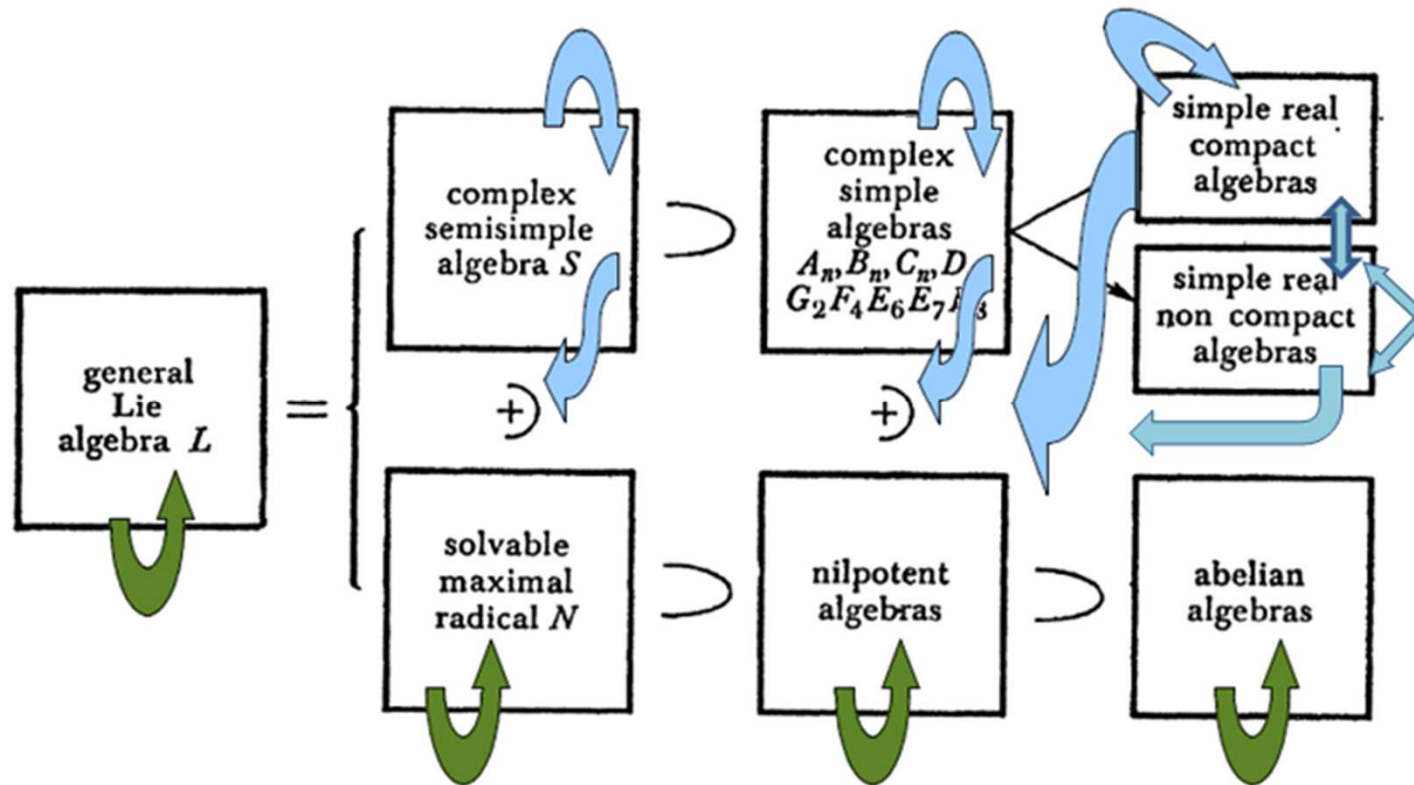
Properties preserved by the action of the  $S$ -expansion process

Original $\mathcal{G}$	Expanded $\mathcal{G}_S$	Resonant $\mathcal{G}_{S,R}$	Reduced $\mathcal{G}_{S,R}^{\text{red}}$
Abelian	Abelian	Abelian	Abelian
Solvable	Solvable	Solvable	Solvable
Nilpotent	Nilpotent	Nilpotent	Nilpotent
Compact	Arbitrary	Arbitrary	Arbitrary
Semisimple $\mathcal{G} = S$	Arbitrary $\mathcal{G}_S = N_{\text{exp}} \uplus S_{\text{exp}}$	Arbitrary $\mathcal{G}_{S,R} = N_{\text{exp},R} \uplus S_{\text{exp},R}$	Arbitrary $\mathcal{G}_{S,R}^{\text{red}} = N_{\text{exp},R}^{\text{red}} \uplus S_{\text{exp},R}^{\text{red}}$
Arbitrary $\mathcal{G} = N \uplus S$	Arbitrary $\mathcal{G}_S = N_{\text{exp}} \uplus S_{\text{exp}}$	Arbitrary $\mathcal{G}_{S,R} = N_{\text{exp},R} \uplus S_{\text{exp},R}$	Arbitrary $\mathcal{G}_{S,R}^{\text{red}} = N_{\text{exp},R}^{\text{red}} \uplus S_{\text{exp},R}^{\text{red}}$



# General properties of the expansion methods of Lie algebras

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- iii) to establish the isomorphism of an arbitrary semigroup with one of those classified in the literature and





# General properties of the expansion methods of Lie algebras

2) Then, by implementing computer programs to perform expansion with any semigroup (up to order 6 ).

order	$Q = \#$ semigroups	
1	1	
2	4	
3	18	
4	126	[Forsythe '54]
5	1,160	[Motzkin, Selfridge '55]
6	15,973	[Plemmons '66]
7	836,021	[Jurgensen, Wick '76]
8	1,843,120,128	[Sato, Yama, Tokizawa '94]
9	52,989,400,714,478	[Distler, Kelsey, Mitchell '09]

Those programs allow us:

- i) to study all resonant decomposition of a semigroup,
- ii) identify those with a zero element,
- iii) to establish the isomorphism of an arbitrary semigroup with one of those classified in the literature and
- iv) To study further conditions for some specific problem

## Final remarks

As mentioned in

Nesterenko M. 2012 S-expansions of three dimensional Lie algebras  
*arXiv:1212.1820*

it would be interesting to know whether S-expansions fit the classification of solvable Lie algebras of a fixed dimension by means of S-expansions of simple (semisimple) Lie algebras of the same dimension.

The theoretical results proposed in this work could be useful in solving that problem.





## Final remarks

The S-expansion method have already been extended to the case of other mathematical structures (*higher order Lie algebras, Loop algebras*)

Caroca R, Merino N and Salgado P 2009 *S-Expansion of higher-order Lie algebras* J. Math. Phys. 50 013503

Caroca R, Merino N, Pérez A and Salgado P 2009 *Generating higher order Lie algebras by expanding Maurer-Cartan forms* J. Math. Phys. 50 123527

Caroca R, Merino N, Salgado P and Valdivia O 2011 *Generating infinite-dimensional algebras from loop algebras by expanding Maurer–Cartan forms* J. Math. Phys. 52 043519



## Final remarks

We think that this mathematical tool could be useful other gauge theories such as *Yang-Mills theory*, *Wess-Zumino models*, *higher spin theories*, *gauge/gravity duality*, etc.



Thanks you for your attention



# Implementing computer programs

## History about finite semigroup programs:

### HANDBOOK OF FINITE SEMIGROUP PROGRAMS

John A Hildebrant

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# Implementing computer programs

## History about finite semigroup programs:

For example, for  $n=2$  the program com.f gives the following list:

$$\begin{array}{c|cc} S^1_{(2)} & \lambda_1 & \lambda_2 \\ \hline \lambda_1 & \lambda_1 & \lambda_1 \\ \lambda_2 & \lambda_1 & \lambda_1 \end{array} , \begin{array}{c|cc} S^2_{(2)} & \lambda_1 & \lambda_2 \\ \hline \lambda_1 & \lambda_1 & \lambda_1 \\ \lambda_2 & \lambda_1 & \lambda_2 \end{array} , \begin{array}{c|cc} S^4_{(2)} & \lambda_1 & \lambda_2 \\ \hline \lambda_1 & \lambda_1 & \lambda_2 \\ \lambda_2 & \lambda_2 & \lambda_1 \end{array}$$

**Principal Idea:** can be related 2 and 3-dimensional isometries?

Considering the two set of algebras:  $[X_1, X_2] = 0$  and  
 $[X_1, X_2] = X_1$

Group	Algebra
→ type I	$[X_1, X_2] = [X_1, X_3] = [X_2, X_3] = 0$
→ type II	$[X_1, X_2] = [X_1, X_3] = 0, \quad [X_2, X_3] = X_1$
→ type III	$[X_1, X_2] = [X_2, X_3] = 0, \quad [X_1, X_3] = X_1$
type IV	$[X_1, X_2] = 0, \quad [X_1, X_3] = X_1, \quad [X_2, X_3] = X_1 + X_2$
→ type V	$[X_1, X_2] = 0, \quad [X_1, X_3] = X_1, \quad [X_2, X_3] = X_2$
type VI	$[X_1, X_2] = 0, \quad [X_1, X_3] = X_1, \quad [X_2, X_3] = hX_2,$ where $h \neq 0, 1$
type VII <sub>1</sub>	$[X_1, X_2] = 0, \quad [X_1, X_3] = X_2, \quad [X_2, X_3] = -X_1$
type VII <sub>2</sub>	$[X_1, X_2] = 0, \quad [X_1, X_3] = X_2, \quad [X_2, X_3] = -X_1 + hX_2,$ where $h \neq 0$ ( $0 < h < 2$ ).
type VIII	$[X_1, X_2] = X_1, \quad [X_1, X_3] = 2X_2, \quad [X_2, X_3] = X_3$
type IX	$[X_1, X_2] = X_3, \quad [X_2, X_3] = X_1, \quad [X_3, X_1] = X_2$

# Checking with computer programs

## Isomorphisms and consistency of the procedure

Algebra	Semigroup used
Type I	many semigroups
Type II	$S_{(4)}^{10}, S_{(4)}^{12}$
Type III	$S_{(4)}^{13}, S_{(4)}^{28}, S_{(4)}^{42}, S_{(4)}^{43}, S_{(4)}^{44}, S_{(4)}^{45}$ and $S_{(4)}^{64}$
Type V	$S_{(4)}^{42}$

isomorphic to			isomorphism
$S_{N1}$	$\Longleftrightarrow$	$S_{(4)}^{44}$	$(\lambda_4 \lambda_1 \lambda_2 \lambda_3)$
$S_{N2}$	$\Longleftrightarrow$	$S_{(4)}^{12}$	$(\lambda_4 \lambda_3 \lambda_2 \lambda_1)$
$S_{N3}$	$\Longleftrightarrow$	$S_{(4)}^{42}$	$(\lambda_4 \lambda_1 \lambda_3 \lambda_2)$
$S_E^{(2)}$	$\Longleftrightarrow$	$S_{(4)}^{43}$	$(\lambda_4 \lambda_3 \lambda_2 \lambda_1)$
$S_K^{(3)}$	$\Longleftrightarrow$	$S_{(4)}^{45}$	$(\lambda_4 \lambda_2 \lambda_1 \lambda_3)$