The excursion set approach

Halo abundances Halo clustering/bias





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Why study halos?

- Cluster counts contain information about volume and about how gravity won/lost compared to expansion
- Probe geometry and expansion history of Universe, and nature of gravity

Massive halo = Galaxy cluster (Simpler than studying galaxies? Less gastrophysics?)

But wait... We should be doing this in the MAITIAL fluctuation field!



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Simplification because...

- Everything local
- Evolution determined by cosmology (competition between gravity and expansion)
- Statistics determined by initial fluctuation field: for Gaussian, specified by initial power-spectrum P(k)
- Nearly universal in scaled units: $\delta_c(z)/\sigma(m)$ where $\sigma^2(m) = \langle \delta_m^2 \rangle = \int dk/k \ k^3 P(k)/2\pi^2 \ W^2(kR_m) \ m \propto R_m^3$
- Fact that only very fat cows are spherical is a detail (crucial for precision cosmology); in excursion set approach, mass-dependent barrier height increases with distance along walk

Spherical evolution model

• 'Collapse' depends on initial over-density Δ_i ; same for all initial sizes

 Critical density depends on cosmology

 Final objects all have same density, whatever their initial sizes

•Collapsed objects called halos are

~ 200× denser than critical (background?!),















Assume a spherical herd of spherical cows...

Initial spatial distribution within patch (at z~1000)





...stochastic (initial conditions Gaussian random field); study 'forest' of merger history 'trees'.

...encodes information about subsequent 'merger history' of object

(Mo & White 1996; Sheth 1996)

Spherical evolution mapping ...

 $(R_{initial}/R)^3 = Mass/(\rho_{com}Volume) =$

$$1 + \delta \approx (1 - \delta_0 / \delta_{sc})^{-\delta sc}$$

... can be inverted:

 $(\delta_0/\delta_{sc}) \approx 1 - (M/\rho_{com}V)^{-1/\delta sc}$

N.B. For any V, there is a curve $\delta_0(M|V)$.

Moving barriers: The Nonlinear PDF



Correlations with environment







Large scale clustering/bias (from the peak-background split)

$$1 + \delta_{h}(v | \delta_{0}, S_{0}) = f(v | \delta_{0}, S_{0}) / f(v)$$
$$= 1 + b_{1}(v)\delta_{0} + \dots$$

- b(v) directly from (derivatives of) f(v) means halo abundances predict halo clustering
- b(v) increases with v

→ top-heavy mass function in dense regions: $n(m|\delta_0) = n(m)(1 + b(m)\delta_0 + ...) \neq n(m)(1+\delta_0)$ → massive halos (i.e. larger v) more clustered: $<\delta_h\delta_0 > = b_1(v) < \delta_0^2 > + ...$ (Almost) universal mass function and halo bias

See Paranjape et al (2013) for recent progress in modeling this from first principles

See Castorina et al. (2014) for ν 's



 Structure at a given time, and, more importantly, growth of structure, provides sharp constraints on models



The Halo Mass Function

- •Small halos collapse/virialize first
- Can also model halo spatial distribution
 Massive halos more strongly clustered





Study of random walks with correlated steps

Cosmological constraints from large scale structures

Models of halo abundances and clustering: Gravity in an expanding universe

Use knowledge of initial conditions (CMB) to make inferences about late-time, nonlinear structures

Hierarchical clustering in GR



= the persistence of memory