

Lecture 4

Model Selection & Development

Joe Zuntz

Evidence

Model Selection

- Given two models, how can we compare them?
- Simplest approach = compare ML
 - Does not include uncertainty or Occam's Razor
- Recall that all our probabilities have been conditional on the model, as in Bayes:

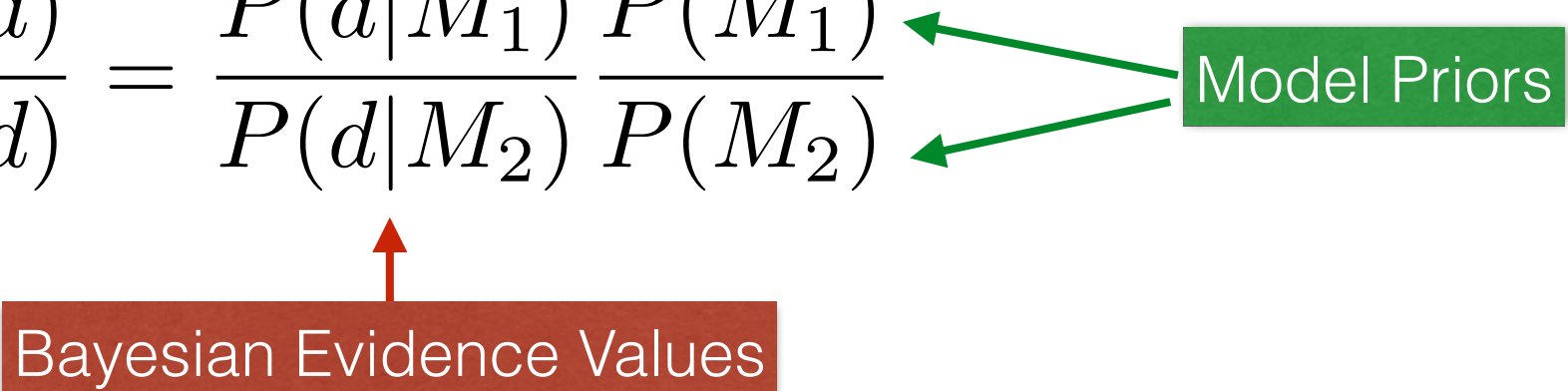
$$P(p|M) = \frac{P(d|pM)P(p|M)}{P(d|M)}$$

Model Selection: Bayesian Evidence

- Can use Bayes Theorem again, on model level:

$$P(M|d) = \frac{P(d|M)P(M)}{P(d)}$$

- Only really meaningful when comparing models.
Bayes Factor B:

$$\frac{P(M_1|d)}{P(M_2|d)} = \frac{P(d|M_1)}{P(d|M_2)} \frac{P(M_1)}{P(M_2)}$$


Bayesian Evidence Values

Model Priors

Model Selection: Bayesian Evidence

- Likelihood of parameters within model:

$$P(d|pM)$$

- Evidence of model:

$$P(d|p)$$

Model Selection: Bayesian Evidence

- Evidence is the bit we ignored before when doing parameter estimation
- Given by an integral over prior space

$$P(d|M) = \int P(d|pM)P(p|M)dp$$

- Hard to evaluate - posterior usually small compared to prior

Model Selection: Evidence Approximations

- Nice evidence approximations for some cases:
 - Savage-Dickey Density ratio
(for when one model is a subset of another)
 - Akaike information criterion AIC
Bayesian information criterion BIC
Work in various circumstances

Savage Dickey

- Applies to two models where M_1 is restricted version of M_2
 - e.g $M_1 = \text{LCDM}$ $\underline{\Omega} = \{\Omega_m, \Omega_b, \dots\}$ with $w = -1$
 $M_2 = w\text{CDM}$

$$P(d|\underline{\Omega}, M_1) = P(d|\underline{\Omega}, w = -1, M_2)$$

- with separable priors

$$P(\underline{\Omega}|w = -1, M_2) = P(\underline{\Omega}, M_1)$$

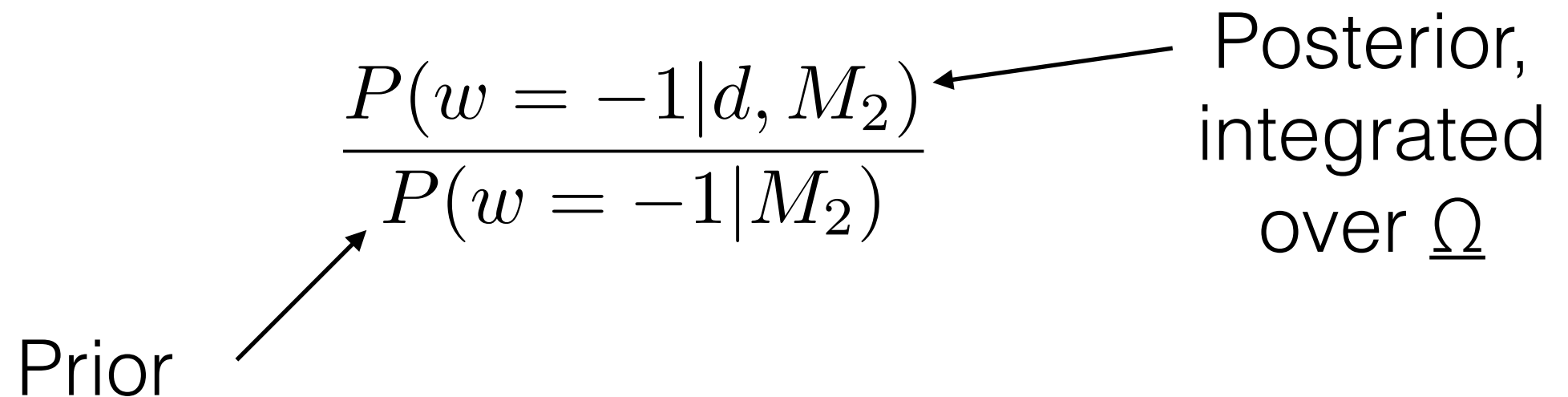
Savage Dickey

- In this case, Bayes factor given by

$$\frac{P(w = -1 | d, M_2)}{P(w = -1 | M_2)}$$

Prior

Posterior,
integrated
over $\underline{\Omega}$



Model Selection: Nested Sampling

$$\begin{aligned}\int L(\theta)p(\theta)d\theta &= \int L(X)dX \\ &\approx \sum L_i \delta X_i \\ dX &\equiv P(\theta)d\theta\end{aligned}$$

X = remaining prior volume

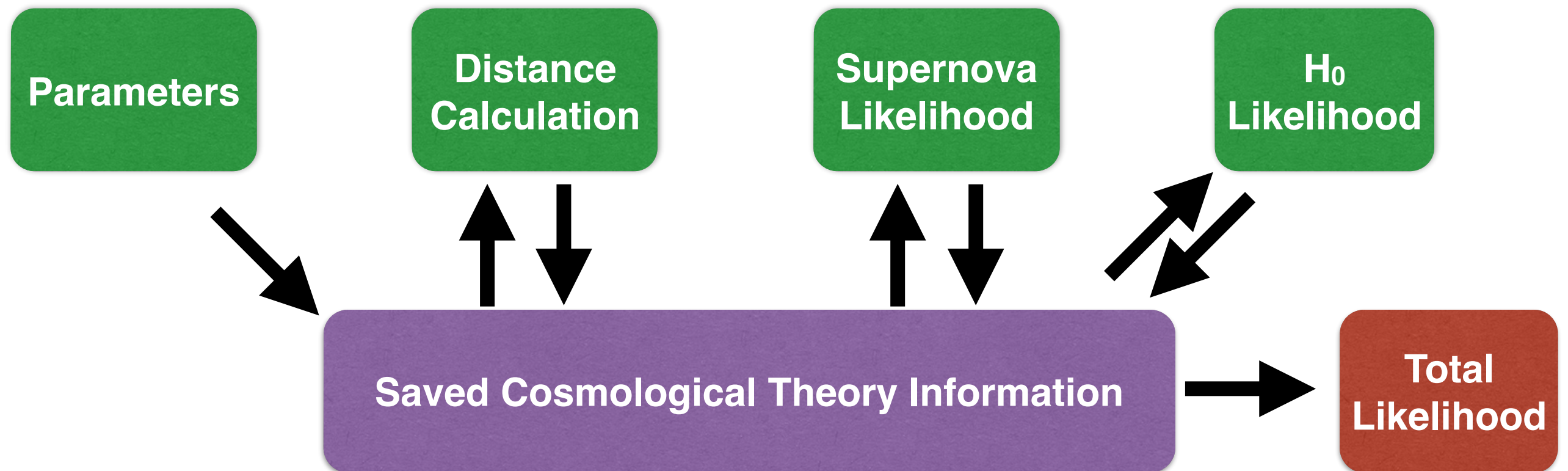
Model Selection: Nested Sampling

- Also uses ensemble of live points
 - Computes constraints as well as evidence
- Each iteration, replace lowest likelihood point with one higher up, sampled from prior
- Multinest software is extremely clever
 - C, F90, Python bindings

Multineest Example

```
> cosmosis demos/demo9.ini
```

```
> postprocess -o plots -p demo9 demos/demo9.ini  
--extra demos/extra9.py
```



<https://bitbucket.org/joezuntz/cosmosis/wiki/Demo9>

More Samplers

Importance Sampling

- Re-sampling from re-weighted existing samples
 - Changed prior / likelihood
 - New data

$$\begin{aligned} E[f(x)] &= \int P_1(x) f(x) dx \approx \frac{1}{N} \sum_{\text{Chain 1}} f(x_i) \\ &= \int \left(\frac{P_1(x)}{P_2(x)} f(x) \right) P_2(x) dx \approx \frac{1}{N} \sum_{\text{Chain 2}} f(x_i) \frac{P_1(x_i)}{P_2(x_i)} \end{aligned}$$

Importance Sampling

- i.e.
 - Take a chain you sampled from some distribution P_2
 - Give each sample a weight $P_1(x)/P_2(x)$ for some new distribution P_1
 - Make your histograms, estimates, etc, using these weights

Importance Sampling

- Works better the more similar P_2 is to P_1
- Won't work if P_2 small where P_1 isn't
 - So better for extra data than different data

Gibbs Sampling

- Applicable when have >1 parameters $a, b, c, \dots z$
- And can directly sample from conditional likelihoods:
 $P(a|bcd\dots), P(b|acd\dots), P(c|abd\dots), \dots P(z|abc\dots y)$
- Can be very efficient when possible

Gibbs Sampling

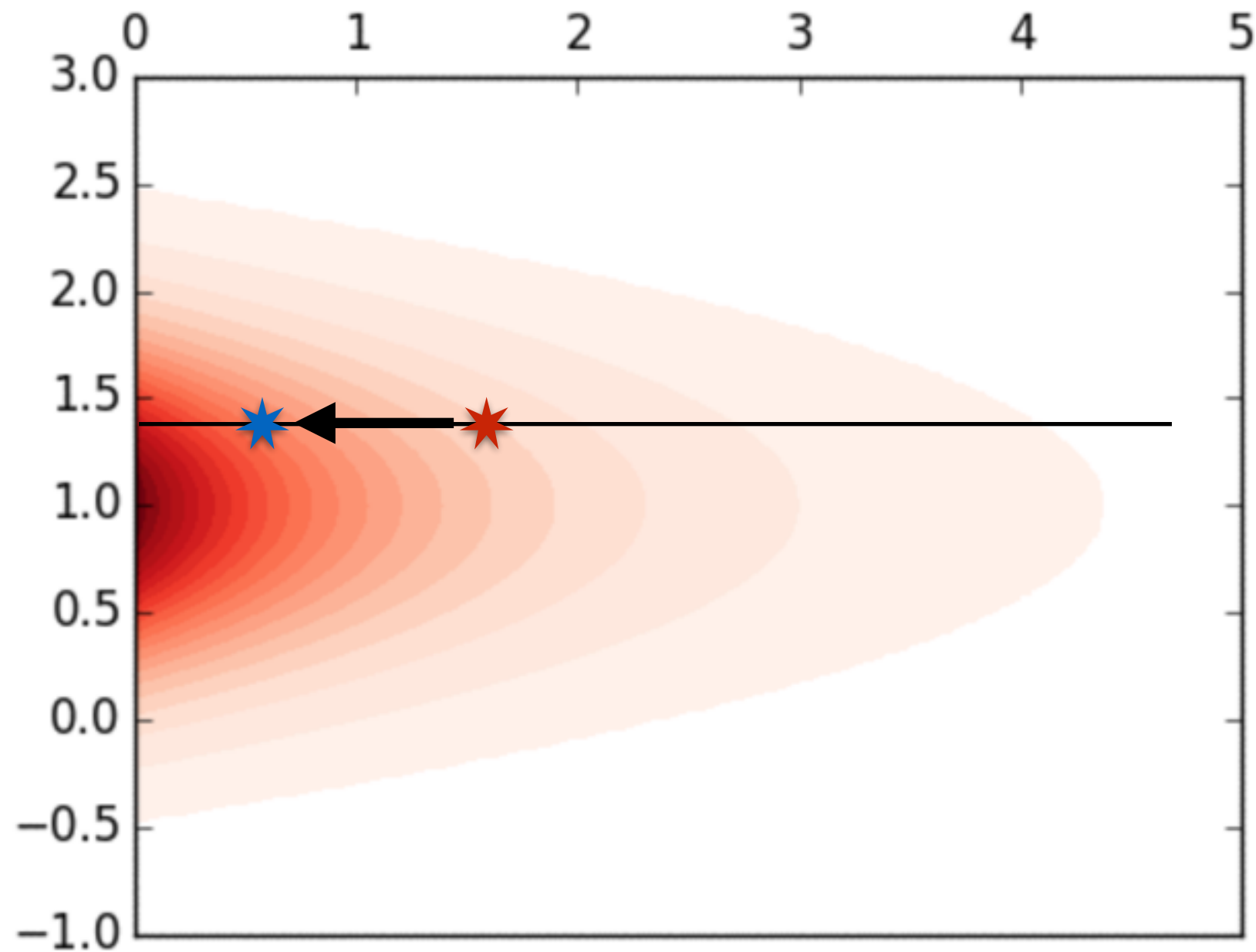
- Very simple algorithm - just each parameter in turn
- 2D version with parameters (a,b):

for $i = 1 \dots$

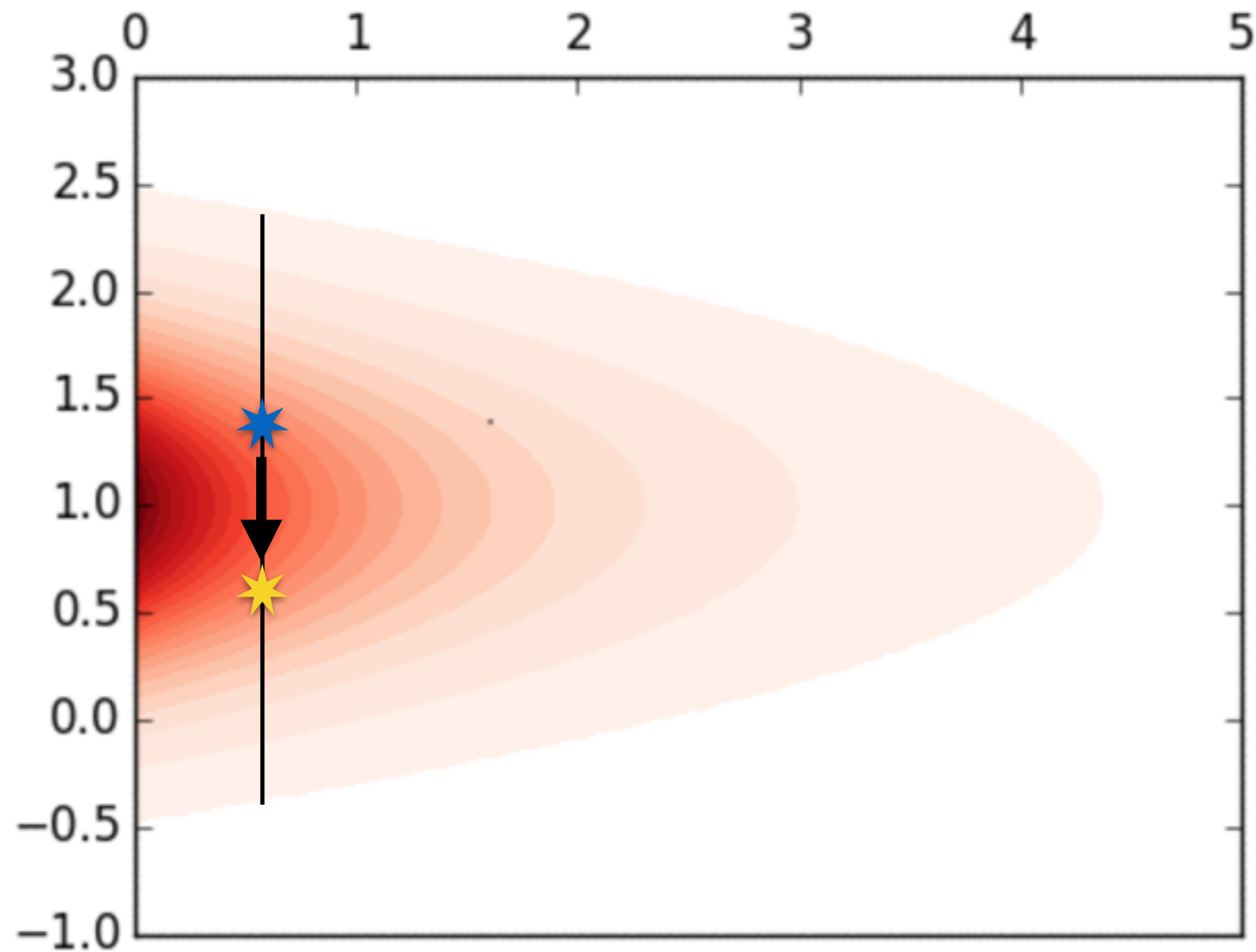
$$a^{i+1} \sim P(a^{i+1} | b^i)$$

$$b^{i+1} \sim P(b^{i+1} | a^{i+1})$$

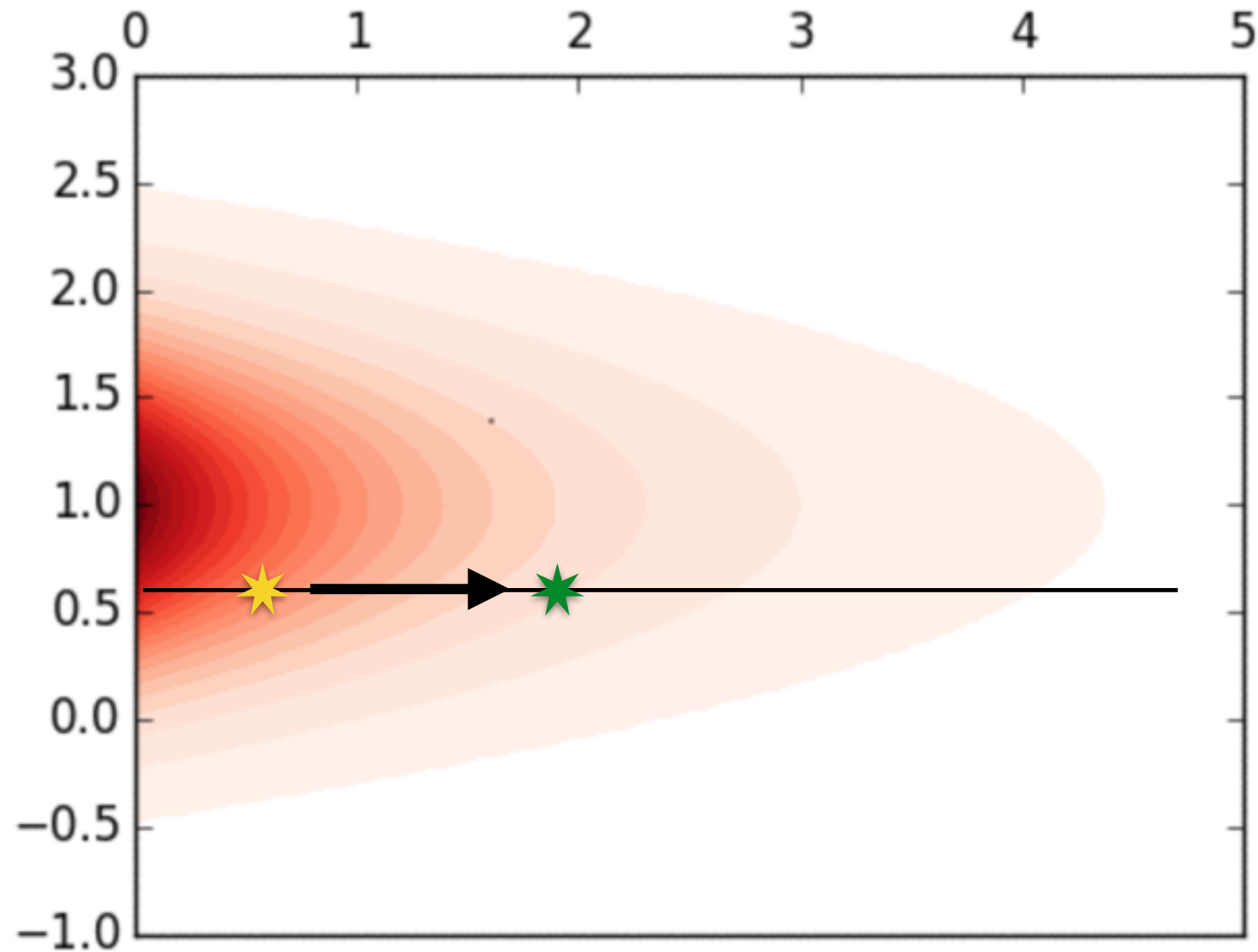
Gibbs Sampling



Gibbs Sampling



Gibbs Sampling



Gibbs Sampling

- Multi-parameter case - not as bad as it looks:

for $i = 1 \dots$

for $k = 1 \dots n_{\text{param}}$

$$x_k^{i+1} \sim P(x_k^{i+1} | x_1^{i+1}, x_2^{i+1}, \dots, x_{k-1}^{i+1}, x_{k+1}^i, x_{k+2}^i, \dots, x_{n_{\text{param}}}^i)$$

- Can also block groups of parameters together and update as vectors

Defining a pipeline run

Pipeline Definition

- Look at demos/demo2.ini

[pipeline]

modules = consistency camb planck bicep

values = demos/values2.ini

- Each module in the list is described lower down -
file path to module and any options for it
- Parameters defined in the “values” file

Building & extending
likelihood pipelines

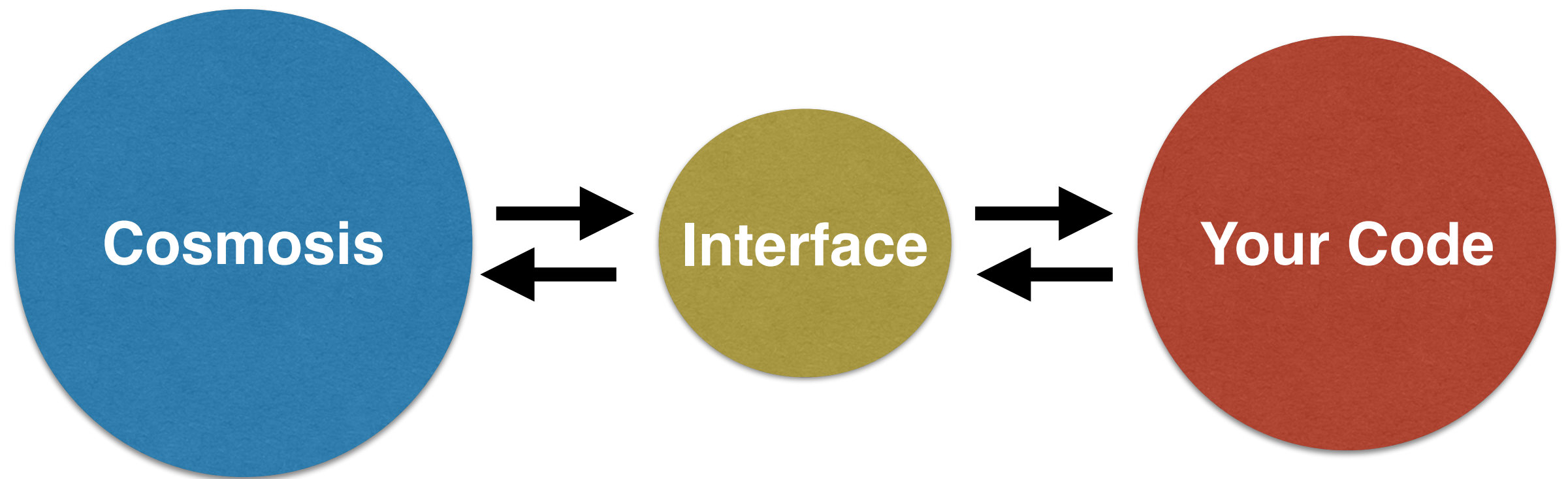
Managing Code

- *Design* before you *write*
- Read about how to code!
- If you don't use version control you are definitely making a mistake.
 - Learn *git*. It's worth it.

Organizing Likelihoods

- Separate theory calculation from likelihood
 - Can replace methods and data independently
- Don't Repeat Yourself (D.R.Y.)
 - Use existing distance calculations, $P(k,z)$, etc.
- Libraries, Libraries, Libraries, Libraries, Libraries,
Libraries, Libraries, Libraries, Libraries, Libraries,
Libraries, Libraries, *Libraries*, **Libraries**, ***Libraries***.

Connecting Code



Creating a cosmosis module

- Given a piece of code implementing your module, we will write an interface connecting it to cosmosis
- Need two functions:
setup, execute
- https://bitbucket.org/joezuntz/cosmosis/wiki/modules_python
- https://bitbucket.org/joezuntz/cosmosis/wiki/modules_c
- https://bitbucket.org/joezuntz/cosmosis/wiki/modules_fortran

Setup

- Cosmology-independent settings and setup
 - e.g. loading data, limits on
- Read settings from ini file

Execute

- Cosmology calculations
- Main module work
- Read inputs (from cosmosis)
- Save outputs (to cosmosis)

Three Groups

- Non-programmers
 - Go through the demos at <https://bitbucket.org/joezuntz/cosmosis>
- Did homework and coded Cepheid likelihood 😊
 - Create likelihood module
- Didn't do homework! 😡
 - Test a new $w(z)$ theory

Creating a Likelihood

- Last time you coded up a likelihood for the LMC and extragalactic Cepheids
- Here's some data!
 LMC <http://bit.ly/1vQ4RTV>
 Ex-gal <http://bit.ly/1tJzRBT>
- Note: there are complexities I skipped when describing this! You'll only get H_0 to a factor of a few.
- Let's turn this into a cosmosis module
- Inputs: `h0`, `alpha`, `beta` in `cosmological_parameters`
- Outputs: `cepheid_like` in `likelihoods`

Testing A New Theory

- Let's constrain the w_0 - w_z parameterisation

$$w(z) = w_0 + w_z z$$

$$\Omega_\Lambda(z) = \Omega_\Lambda(0) (1 + z)^{3(1+w_0-w_z)} \exp(-3w_z z)$$

- Use `scipy.integrate.quad` to do the integration
- Inputs: `h0`, `omega_m`, `w0`, `wz` in `cosmological_parameters`
- Outputs: `z`, `mu` in `distances`

Distance Equations

$$\Omega_{\Lambda}(z) = \Omega_{\Lambda}(0) (1 + z)^{3(1+w_0-w_z)} \exp(-3w_z z)$$

$$\Omega_m(z) = \Omega_m(1 + z)^3$$

$$H(z) = H_0 \sqrt{\Omega_m(z) + \Omega_{\Lambda}(z)}$$

$$D_c(z) = c \int_0^z \frac{1}{H(z')} dz'$$

$$D_L(z) = (1 + z) D_c(z)$$

$$\mu(z) = 5 \log_{10} \frac{D_L}{\text{Mpc}} - 25$$

Example Implementation

<http://nbviewer.ipython.org/gist/joezuntz/d4b82ce5b3010870aa6b>

Getting Started

- Create a new directory under modules/
- Put your code in a file in there
- Create another file in there (same language) to connect to cosmosis
- See the wiki links above for examples of what they look like - adapt these for your code