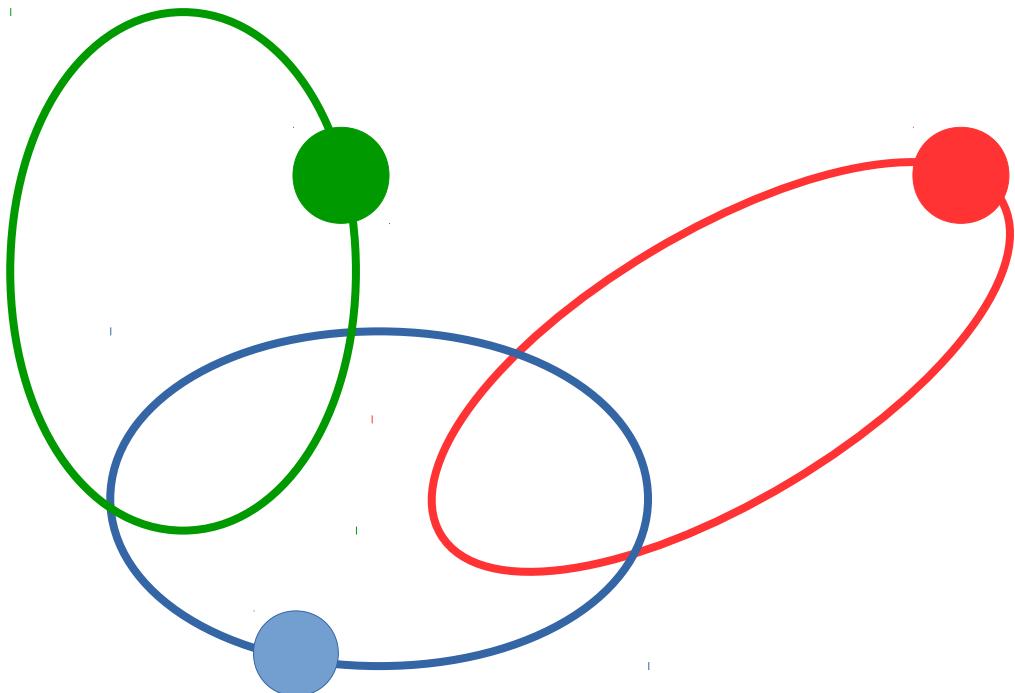


# Workshop on Advanced Techniques for Scientific Programming and Management of Open Source Software Packages

## Gravitation Project

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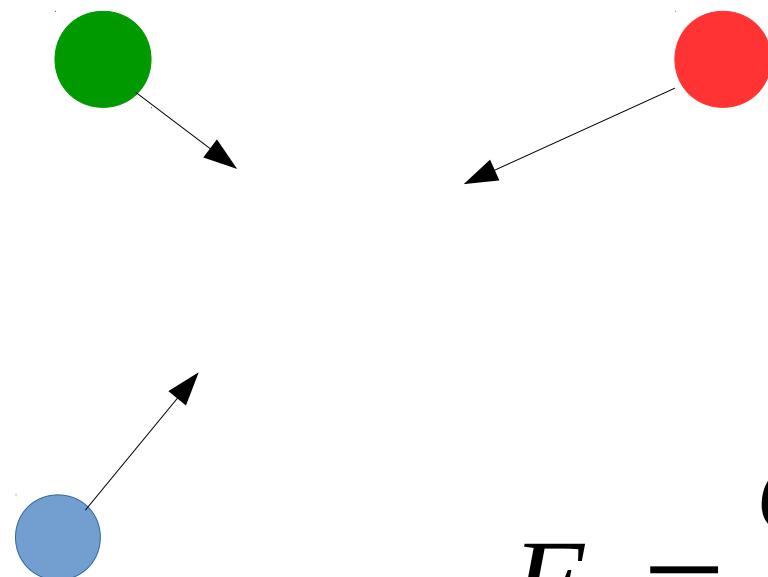
## PROBLEM DESCRIPTION



### MAIN TASK

Compute the movement of  
bodies under gravity forces  
**using collaborative  
techniques**

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$$F_{ij} = \frac{G m_i m_j}{|\vec{x}_i - \vec{x}_j|^2} \frac{\vec{x}_j - \vec{x}_i}{|\vec{x}_i - \vec{x}_j|}$$

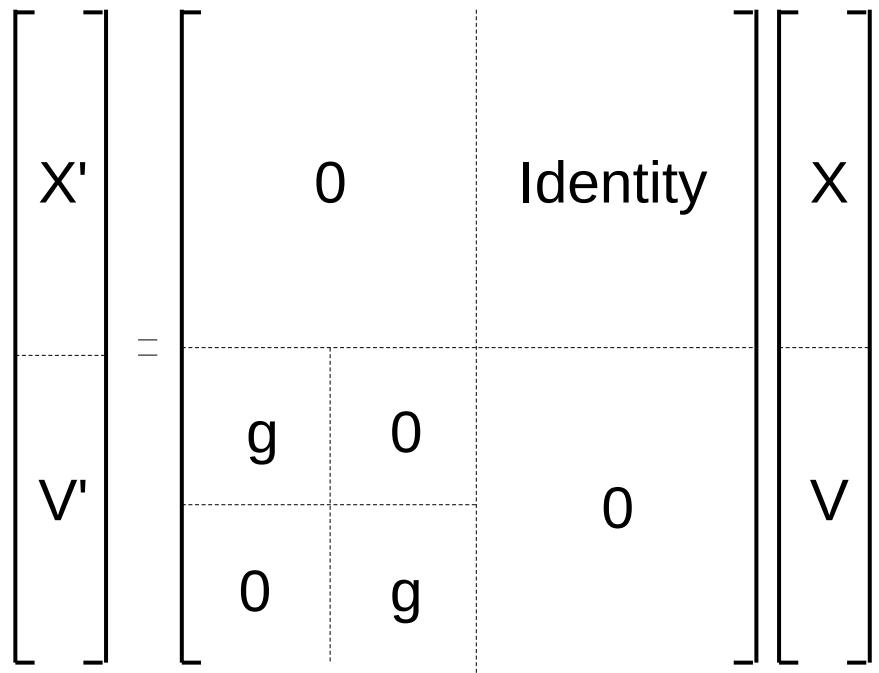
## EQUATION DISCRETIZATION

$$\vec{F}_{ij} = m_i g_{ij} (\vec{x}_j - \vec{x}_i)$$

$$\ddot{\vec{X}}_i = \sum_j g_{ij} (\vec{x}_j - \vec{x}_i)$$

$$\dot{\vec{X}}_i = \vec{v}_i$$

$$\ddot{\vec{V}}_i = \sum_j g_{ij} (\vec{x}_j - \vec{x}_i)$$



## EQUATION DISCRETIZATION

Explicit Euler

$$\vec{\alpha}_{n+1} = \vec{\alpha}_n + \delta t M \vec{\alpha}_n$$

Crank-Nicholson

$$\vec{\alpha}_{n+1} = \vec{\alpha}_n + \frac{\delta t}{2} [M \vec{\alpha}_{n+1} + M \vec{\alpha}_n]$$

Runge – Kutta 4<sup>th</sup> order

$$\vec{\alpha}_{n+1} = \vec{\alpha}_n + \frac{1}{6} (K_1 + 2K_2 + 2K_3 + K_4)$$

$$\begin{bmatrix} X' \\ V' \end{bmatrix} = \begin{bmatrix} 0 & g \\ 0 & g \end{bmatrix} \begin{bmatrix} M \\ \vec{\alpha} \end{bmatrix}$$

Identity

# Gravitation project

## PYTHON + GIT + GITHUB

```
class Gravitation(object):
    """ This is the main gravitation wrapper"""

class Body(object):
    """ Base class for space objects"""

class make_plot(object):
    """Class designed for runtime plotting"""

def main():
    """Main function"""

    usage: Main.py [-h] [--method METHOD] [--tstep TSTEP]
    [--file FILENAME] [--plot] [--profile] [--nsteps NSTEPS]
    [--config][--confile CONFIG_FILE]
```

→ List of bodies  
Time advancement

→ Mass, position,  
velocity

→ Runtime plotting

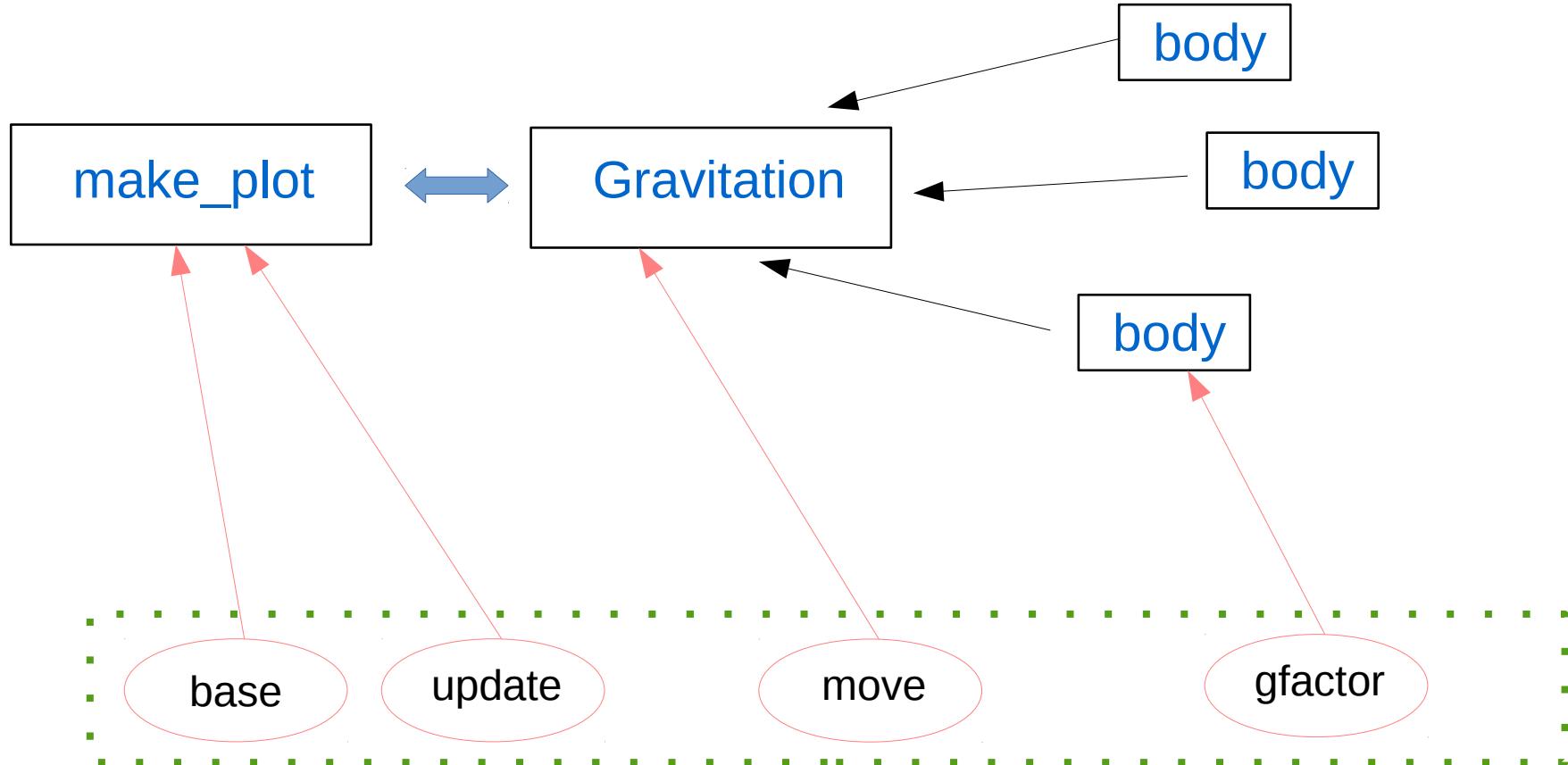
→ Image and video

→ Multi-processing



# Gravitation project

## PYTHON + GIT + GITHUB



**GITHUB** → <https://github.com/fnbellomo/GProject.git>

# Gravitation project

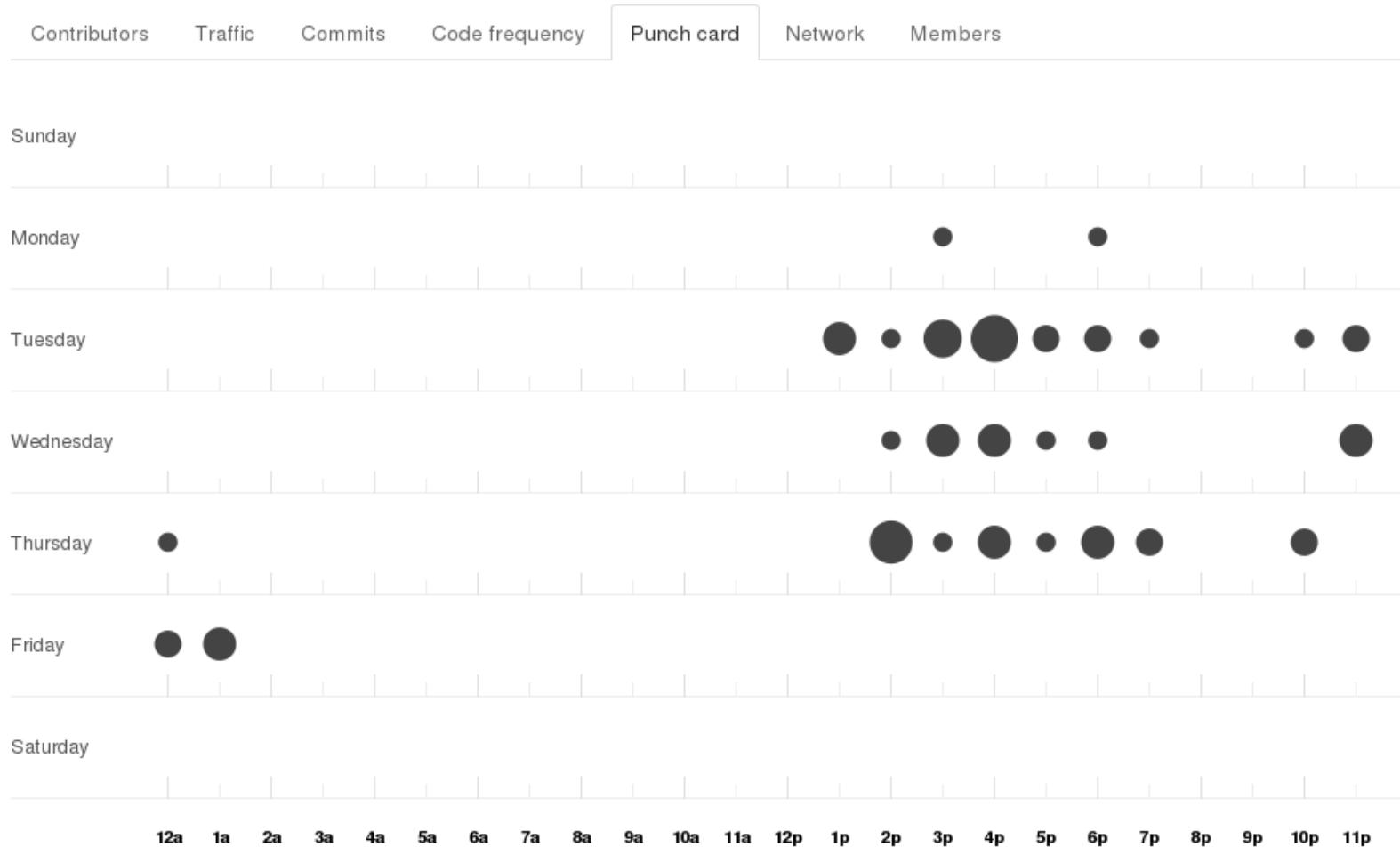
2015 ICTP-SAIFR School - Gravitaion Project — Edit

 77 commits	 1 branch	 0 releases	 3 contributors
  branch: master 			
Merge branch 'master' of https://github.com/fnbellomo/GProject			
 efogliatto authored 6 hours ago			latest commit 9e14d4b2e4
 Gravitation	Write the doc of each method		7 hours ago
 Slides	update slides. add pdf		6 hours ago
 LICENSE	Initial commit		4 days ago
 Main.py	add --mp to use multiprocessing		7 hours ago
 README.md	Install process		6 hours ago
 Results.gnumeric	Add slides		6 hours ago
 config.py	data change		7 hours ago
 ez_setup.py	Install process		6 hours ago
 generate_people.py	add file that generates workshop members		12 hours ago
 setup.py	Install process		6 hours ago



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# Gravitation project



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# Gravitation project

The screenshot shows a Trello board titled "ICTP-Saifr Gravitation Project". The board is private and has three main columns: "To Do", "In Progress", and "Done".

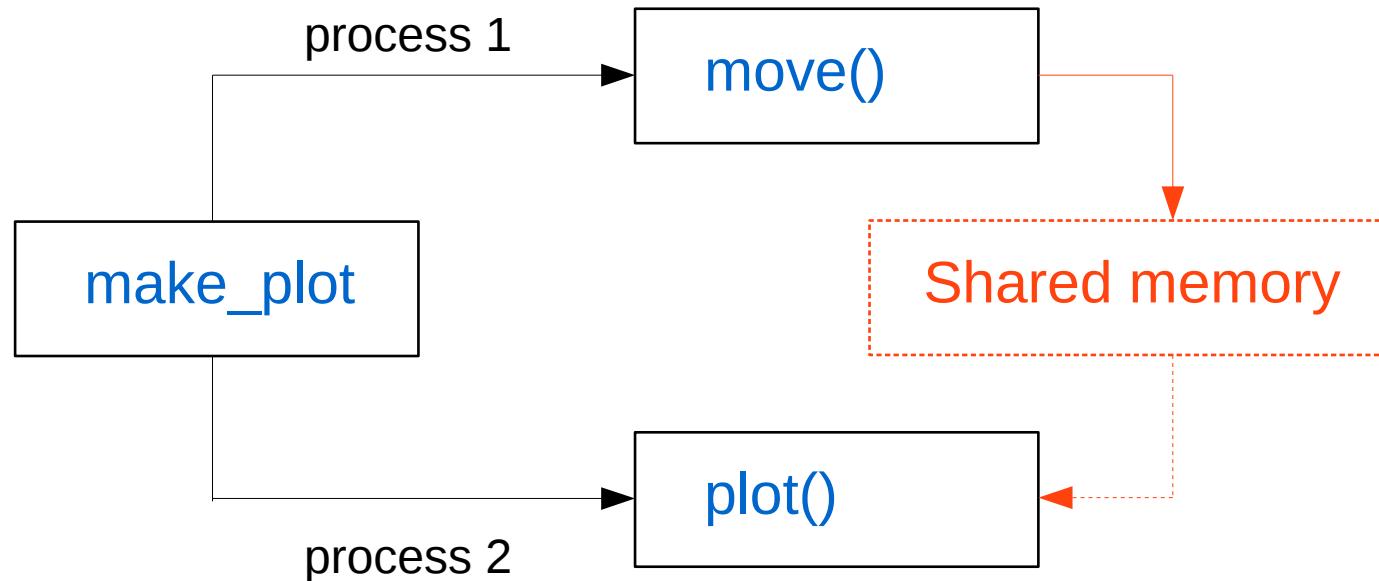
- To Do:** Contains the placeholder "Add a card...".
- In Progress:** Contains three cards:
  - "make a package" (status: FB)
  - "Make documentation:" (status: FB, progress: 3/4)
  - "Make presentations" (status: E)Each card has an "Add a card..." button at the bottom.
- Done:** Contains five cards:
  - "Implement Differential Equation Solvers project" (status: D)
  - "Implement Differential Equation Solvers project" (status: E)
  - "Parallelization Visualization" (status: FB)
  - "Create Visualization Class" (status: FB)
  - "Integrate Classes" (status: E, progress: 2/2, with a user profile picture)
  - "Create class project" (status: E, with a user profile picture)A vertical scrollbar is visible on the right side of the Done column.



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## make\_plot

- First approach: sequential plotting
- Second approach: multi-processing



## LATEST VERSION

A python program that integrates the equation of movement for an arbitrary number of bodies

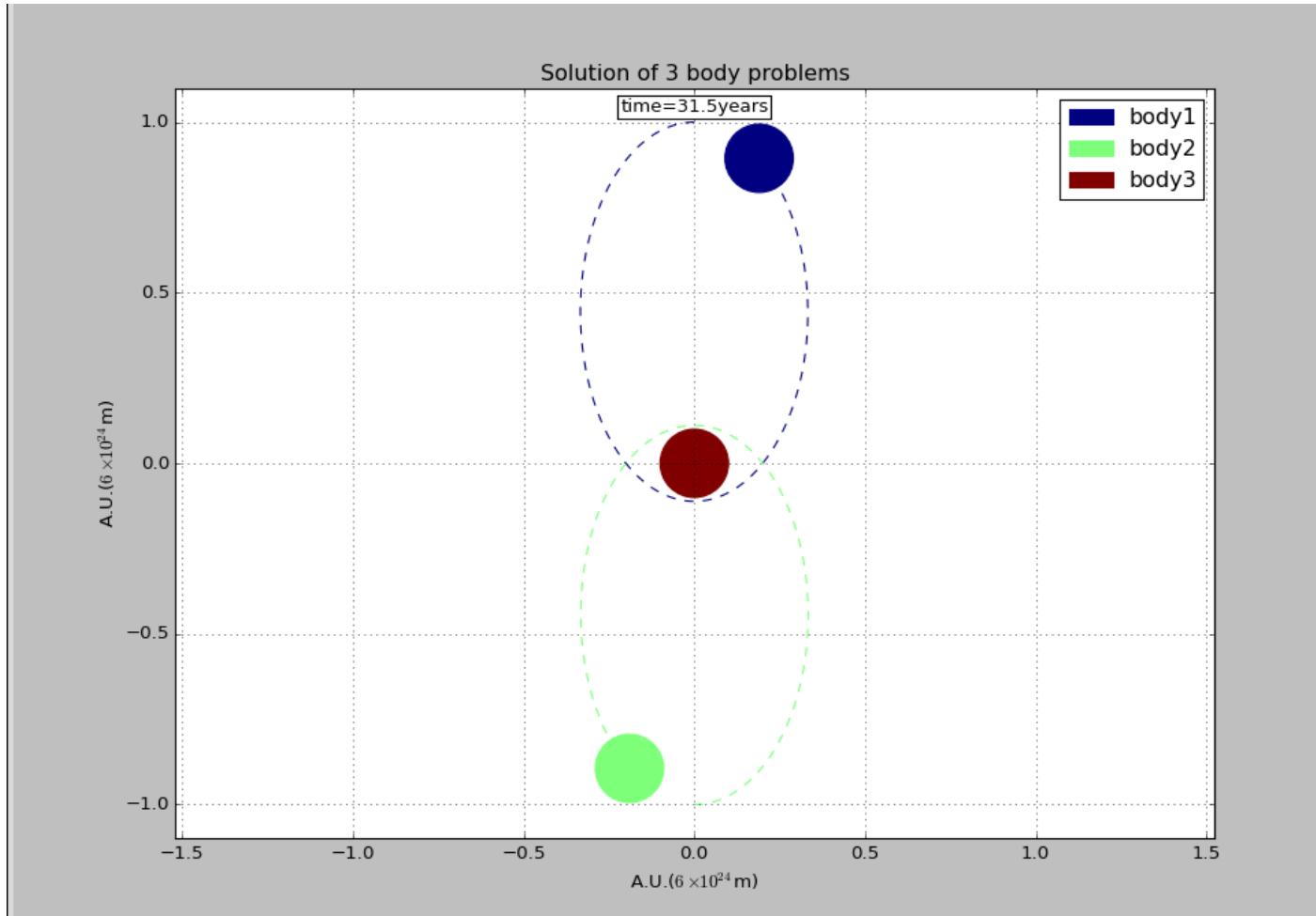
### Main features

- **Collaborative project**
- Command-line options. Reads data and options from file or during runtime
- Several numerical methods: Explicit Euler, Crank-Nicholson, Runge-Kutta4, **adaptive Runge-Kutta**
- Runtime plotting with multiprocessing
- Plot saving for post-processing
- Implements Unit test
- Class documentation with *pydoc*



# Gravitation project

## SOME RESULTS

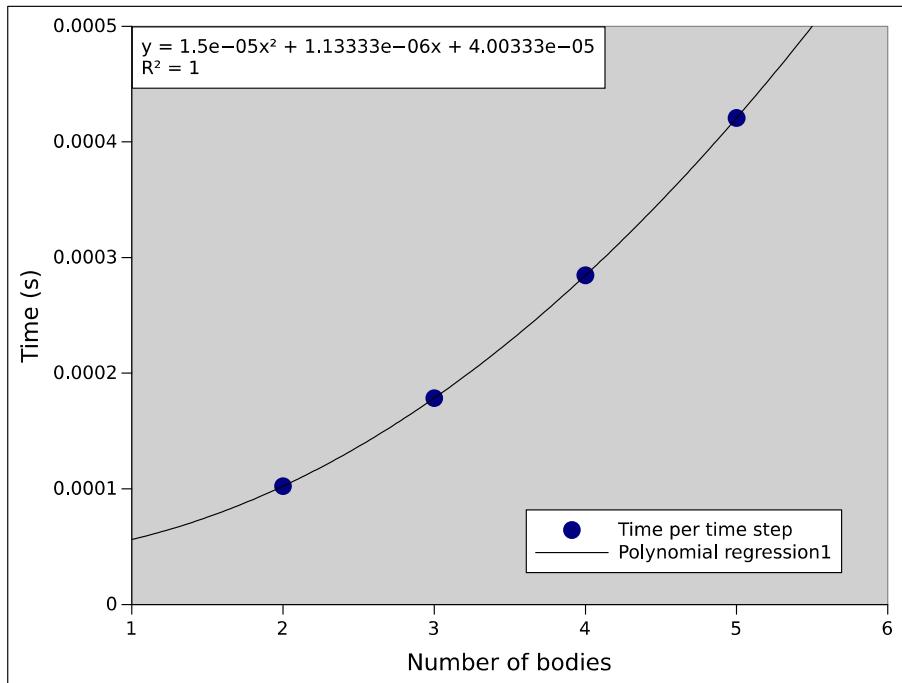
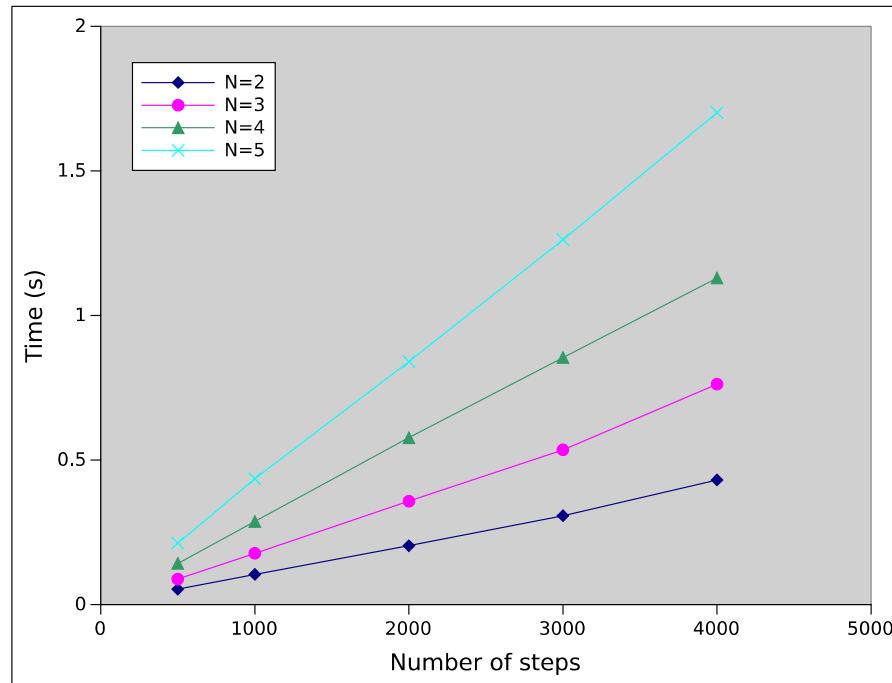


# Gravitation project

## PROFILING

```
import cProfile, pstats
```

```
Pr = cProfile.Profile()  
pr.enable()  
pr.disable()
```



## PROFILING

99039 function calls in 0.535 seconds

Ordered by: standard name

ncalls	tottime	percall	cumtime	percall	filename:lineno(function)
45000	0.223	0.000	0.223	0.000	Body.py:20(gfactor)
3	0.000	0.000	0.000	0.000	Body.py:9(__init__)
3000	0.261	0.000	0.531	0.000	Gravitation.py:107(move)
3000	0.016	0.000	0.018	0.000	Gravitation.py:175(update)
6	0.000	0.000	0.000	0.000	Gravitation.py:8(float_list)
6003	0.001	0.000	0.001	0.000	{len}
3	0.000	0.000	0.000	0.000	{method 'split' of 'str' objects}
12000	0.019	0.000	0.019	0.000	{numpy.core._dotblas.dot}
3	0.000	0.000	0.000	0.000	{numpy.core.multiarray.zeros}
1	0.000	0.000	0.000	0.000	{open}
4	0.000	0.000	0.000	0.000	{print}
30002	0.011	0.000	0.011	0.000	{range}

## INSTALL

### Dependences:

- Numpy
- Matplotlib

### Installation:

```
$ git clone https://github.com/fnbellomo/GProject.git
```

```
$ cd GProyect
```

```
$ sudo python install setup.py
```

# Gravitation project

## DOCUMENTATION (pydoc)

Help on module Body:

**NAME**

Body

**CLASSES**

  builtins.object  
  Body

  class **Body**(builtins.object)  
    | Base class for space bodies.

    This class is responsible for creating objects that would be attracted in the same Gravitational object.  
    The class contains specific information such as position, velocity and mass.

    Methods defined here:

**\_\_init\_\_**(self, obj\_id, obj\_mass, obj\_position, obj\_velocity)  
        Start a Body objects.

        Parameters

        -----  
        obj\_id : str  
            Body name.

        obj\_mass : str  
            Body mass.

        obj\_position : array\_like  
            Position in x and y. [x, y]

        obj\_velocity : array\_like  
            Velocity in x and y. [V\_x, V\_y]



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Management of Open Source Software Packages

## WHAT WE LEARNED?

- Working in collaboration is not easy!
- Implementation of better programming
- Use of Control Version Software

## TO DO

- Rewrite class design
- Split the program into a larger number of independent modules
- Optimize calculations
- Optimize communication between processes

Thanks!

Any questions?