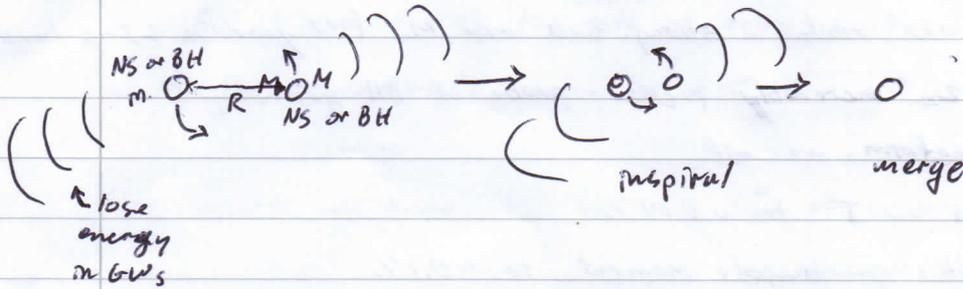
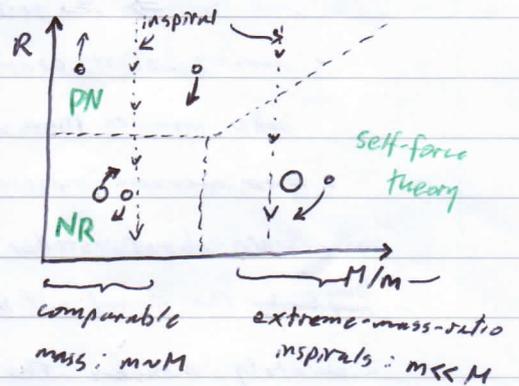


Introduction

Compact binaries: premiere sources of GWs



These binaries come in a few varieties:



Different types are observable by different detectors:

The frequency of a binary is $f \sim \sqrt{\frac{m+M}{R^3}}$

For simplicity, take $R \sim m+M \Rightarrow f \sim \frac{1}{m+M}$ or $f \sim \frac{c^3}{G(m+M)}$ (you can check this has dimension of $1/T$)

Ground-based detectors are sensitive to signals with $f \sim 100 \text{ Hz}$ like LIGO & Virgo $\Rightarrow (M+m) \sim 10^{-2} (c^3/G) \sim 20 M_{\odot}$

~~$f \sim 1 \text{ kHz}$
 $M \sim 10^3 M_{\odot}$
 $\frac{GM}{c^3} \sim 10^3 \text{ s}$
 $\Rightarrow M$~~

Since m and M must be $\gtrsim M_{\odot}$ for a loud enough signal, LIGO can only detect comparable-mass binaries,

~~$\frac{c^3}{G} = \frac{(L/T)^3}{(L^3/M)(1/T)^2} = [M]$~~

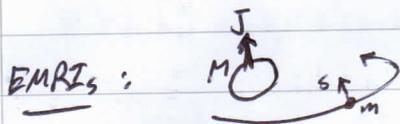
However, LISA, the space-based observatory, will be sensitive to signals with $f \sim 10^{-3} \text{ Hz}$

$\Rightarrow (M+m) \sim 10^5 M_{\odot}$

\Rightarrow LISA can detect comparable-mass binaries where $m \sim M \sim 10^5 M_{\odot}$

and EMRIs with $m \sim M_{\odot}$ and $M \sim 10^5 M_{\odot}$

~~$10^{-3} \text{ Hz} \sim 10^{-3} \text{ s}^{-1}$
 $G \sim 7 \times 10^{-11} \text{ m}^3/\text{kg s}^2$
 $\sim 2.7 \times 10^{-22} \text{ kg}$
 $7 \times 10^{-11} \text{ m}^3 \sim 10^{-22} \text{ kg}$~~



EMRIs: M is a supermassive BH at centre of a galaxy, m is a NS or BH

- orbit is very intricate: highly eccentric, inclined, triperiodic
- m spends $\sim \frac{M}{m} \sim 10^5$ orbits in strong field near M (~ 1 year in LISA band)

\Rightarrow i. precise probe of BH geometry

- from EMRI waveform, we will

- o measure M and J to $\sim 0.01\%$

- o measure BH's quadrupole moment to $\sim 0.1\%$

\Rightarrow ~~test~~ test for deviations from Kerr geometry

- o measure other deviations from GR with order-of-magnitude

better precision than other experiments

- o measure "mass function" $N(M)$

- o learn about stellar dynamics in galactic cores

- But! ... the signal will be buried under noise. To extract it and accurately measure the EMRI's parameters, we need our model of the waveform to agree with the buried signal's phase to $\ll 1$ radian over the EMRI's $\sim 10^5$ cycles

Modeling:

- can't use PN because the system is highly relativistic

- can't use NR " we need so many orbits (also difficult to resolve different length scales)

We use BH perturbation theory / self-force theory:

- expand the metric as $g_{\alpha\beta} = g_{\alpha\beta}^{(0)} + \epsilon h_{\alpha\beta}^{(1)} + \epsilon^2 h_{\alpha\beta}^{(2)} + \mathcal{O}(\epsilon^3)$

where $g_{\alpha\beta}$ is the metric of the large BH, and $\epsilon = m/M$

\swarrow we'll often think of $M \sim \epsilon^0$ and $m \sim \epsilon$

- say m traces out a worldline γ , with coords z^μ , in the Kerr background.

At zeroth order, γ is a geodesic of $g_{\alpha\beta}$

At subleading orders, it will have an EOM $\frac{D^2 z^\alpha}{d\tau^2} = \epsilon f_{(1)}^\alpha + \epsilon^2 f_{(2)}^\alpha + \mathcal{O}(\epsilon^3)$

\swarrow K-covariant acceleration w.r.t $g_{\alpha\beta}$

How high order must we go?

m loses kinetic energy at the rate that GWs carry energy out of the system (from conservation of energy)

$$\Rightarrow \dot{E} \sim \text{GW energy flux} \sim \dot{h} \dot{h} \sim \epsilon^2$$

But $E \sim mv^2 \Rightarrow$ the ^{relative} rate of energy loss is $\dot{E}/E \sim \epsilon$

\Rightarrow the characteristic timescale of the inspiral is $\sim E/\dot{E} \sim 1/\epsilon$ (or M^2/m)

Now suppose we know $f_{(1)}''$ but not $f_{(2)}'' \Rightarrow$ error $\delta \frac{D^2 z''}{dt^2} \sim \epsilon^2$

$$\Rightarrow \text{error } \delta z'' \sim \epsilon^2 t^2$$

\Rightarrow after a time t_{irr} , $\delta z'' \sim \epsilon^2 / \epsilon^2 \sim 1$

In particular, this error occurs in the orbital phase

\Rightarrow it occurs in the GW phase

Since we need $\delta(\text{phase}) \ll 1$, this error is unacceptable

\Rightarrow we need to ~~go to~~ include terms of order ϵ^2 in our calculations (but not ϵ^3)

I'll try to cover most of the core topics involved in ^{EMRI} modeling, from foundations to concrete calculations.

For more info, see the recent review article by Barack & Pound (arXiv:1805.10388)

$$\partial^i \partial_i \bar{h}_{tt}^R = -16\pi \delta^3(x-z) - \partial^i \partial_i \bar{h}_{tt}^P$$

$$\Rightarrow \frac{\partial^i \partial_i \bar{h}_{tt}^R}{r^2} = -\frac{16\pi}{r_0^2} Y_{lm}^*(\theta_0, \phi_0) \delta(r-r_0) - \dots$$

$$\bar{h}_{tt} = \frac{4m}{|x^i - x_p^i|} \Rightarrow \bar{h}_{tt}^{lm} =$$

§

$$\begin{aligned} & \int \varphi^{np} E_{np} [h^{(n)}] dV \\ &= \int \varphi^{np} \partial^i \partial_i h_{np}^{(n)} dV \\ &= \text{lm} \end{aligned}$$

~~...~~

$$\partial^i \partial_i \bar{h}_{tt} = 0 \quad \text{and} \quad \bar{h}_{tt} = \frac{\bar{h}_{tt}^{(l-1)}}{r} + \bar{h}_{tt}^{(0)} + \dots$$

$$E_{np}[h](\varphi) = \int_{\lambda \rightarrow 0}^{\lambda} \text{lm} \int_r$$

$$\bar{h}_{tt}^{(0)} = \frac{4m}{r} + \dots \bar{h}_{tt}^R$$

$$\bar{h}_{ti} = \bar{h}_{ti}^R$$

$$\bar{h}_{ij} = \bar{h}_{ij}^R$$

$$\bar{h}_{tt}^{S,lm} = \frac{16\pi m}{(2l+1) \epsilon_{lm}} Y_{lm}^*(\theta_0, \phi_0) \int_{r_0}^r \frac{r'^2}{r'^{2l+1}}$$

$$r > r_0 : \frac{1}{r} \frac{r_0^2}{r^{2l+1}} \sim \frac{1}{r^{2l+1}}$$

$$\frac{r^2}{r_0^{2l+1}} \theta(r_0-r) + \frac{r_0^2}{r^{2l+1}} \theta(r-r_0)$$

$$r < r_0 : \frac{r^2}{r_0^{2l+1}}$$

⇒

$$\left(\partial_r^2 + \frac{2}{r} \partial_r - \frac{l(l+1)}{r^2} \right) \bar{h}_{tt}^{S,lm} \Big|_{\text{point wise}} = 0 \quad \forall r \neq r_0 \Rightarrow S_{\text{eff}} = 0$$

$$\Rightarrow \left(\partial_r^2 + \frac{2}{r} \partial_r - \frac{l(l+1)}{r^2} \right) \bar{h}_{\text{eff}}^{R,lm} = 0 \quad \forall r$$

$$\Rightarrow \bar{h}_{\text{eff}}^{R,lm} = r^l A_{\text{eff}}^{lm} + \frac{1}{r^{l+1}} B_{\text{eff}}^{lm}$$

regularity at $r=0 \Rightarrow B=0$

decay at $r \rightarrow \infty \Rightarrow A=0$

$$\Rightarrow \bar{h}_{\text{eff}}^R = 0$$