

Adiabatic approximation in Schwarzschild

We'll look at one more thing before getting into the details of self-force theory. Without knowing/calculating the actual self-force, we can implement the adiabatic approximation (in Schwarzschild - not in Kerr; more on this later).

The basic idea:

- i. choose E_0 and l_0 - specifies a geodesic

ii. calculate the GWs at ∞ and at the EH, as sourced by a point mass on the geodesic
 \Rightarrow extract $\dot{E}_{\infty}, \dot{l}_{\infty}, \dot{E}_H, \dot{l}_H$

$$\text{MO}\left(\left(\begin{pmatrix} g \\ \mathbf{E} & \mathbf{l} \end{pmatrix}\right)\right) \xrightarrow{\text{E}} \dot{E}_{\text{initial}}$$

\dot{E} and \mathbf{l} to ∞ \dot{E} and \mathbf{l} down into BH

iii. assume balance laws: $\dot{E}_0 = -\dot{E}_{\infty} - \dot{E}_H$ (this can be proved)
 $\dot{l}_0 = -\dot{l}_{\infty} - \dot{l}_H$ (the actual SF)

iv. use this to update to new E_0 and l_0

v. repeat as many times as desired

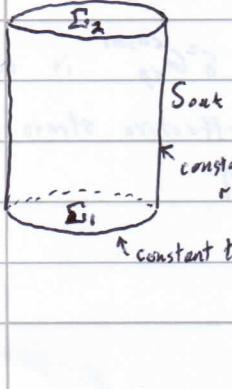
vi. extract phases from $\frac{d\psi^a}{dt} = \Omega_0^a(E_0, l_0)$
 $(\psi^r \text{ and } \phi)$

First task: define \dot{E}_0 and \dot{l}_0 , and \dot{E}_H and \dot{l}_H

Consider a matter stress-energy tensor T^{ab} . We can define the energy

in a spatial region Σ to be $E = -\int_{\Sigma} T^a_{\ b} \xi^b_{(a)} d\Sigma_p$
future-directed volume element

The change in energy between Σ_1 and Σ_2 is



$$E(\Sigma_2) - E(\Sigma_1) = -\int_{\text{Sout}} T^a_{\ b} \xi^b_{(a)} d\Sigma_p$$

Exercise: prove this

outward-directed: $n_a \int \mathbf{r}^a dt d\Omega$

$n_a = \frac{1}{\sqrt{f}} \delta^a_r$ is radial unit vector

$$= -\int T^r_t r^2 dt d\Omega$$

$$= \int (-\int T^r_t r^2 d\Omega) dt$$

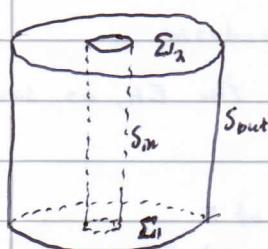
\dot{E}

$$\Rightarrow \dot{E} = -r^2 f \int T_{tr} d\Omega$$

$$\text{Analogously, } L(\Sigma) = \int T^r_{\beta} \hat{z}_{(t)}^\beta d\Gamma_r \quad \text{and} \quad \dot{L} = r^2 f \int T_{r\phi} d\Omega$$

$$\text{So } \dot{E}_{\text{in}} = -\lim_{r \rightarrow \infty} \frac{(r^2 f \int T_{tr} d\Omega)}{S_{\text{out}}} \quad \text{and} \quad \dot{L}_{\text{in}} = \lim_{r \rightarrow \infty} \frac{(r^2 f \int T_{r\phi} d\Omega)}{S_{\text{out}}}$$

If we add an inner boundary around the BH, we get



$$\dot{E}_{\text{in}} = +\lim_{r \rightarrow 2M} \frac{(r^2 f \int T_{tr} d\Omega)}{S_{\text{in}}} \quad \text{and} \quad \dot{L}_{\text{in}} = -\lim_{r \rightarrow 2M} \frac{(r^2 f \int T_{r\phi} d\Omega)}{S_{\text{in}}}$$

This is the E and L carried out of the system by a matter field. What is "Top" for GWs?

Recall, in a vacuum region, $\delta G_{ap}[h] = -\delta^2 G_{ap}[h] + \mathcal{O}(h^3)$

$\Rightarrow -\delta^2 G_{ap}[h]$ is like an effective stress-energy tensor

We can make this more precise: we are interested in how $-\delta^2 G_{ap}$ causes slow changes in the system. For example, the BH absorbs GW energy & angular momentum. This causes $h_{ap}^{(1)}$ to include slowly varying pieces h_{ap}^{SM} or $\underline{\delta M(t)}$ and $h_{ap}^{SJ} \propto \underline{\delta J(t)}$. Also, outside the orbit, the particle $\xrightarrow{\text{perturbations due to small correction}}$ to BH parameters

generates perturbations $\propto \frac{E_0(t)}{r}$ and $\frac{L_0(t)}{r^2}$. In the two-timescale expansion of the EFE, we had $\delta G_{ap}^{(0,kr)}[h^{(0,kr)}] + \delta G_{ap}^{(1,kr)}[h^{(1,kr)}] = -\delta^2 G_{ap}^{(0,kr)}[h^{(0,kr)}]$
 $\delta G_{ap}^{(1,kr)} \sim \underline{\delta M}, \underline{\delta J}, \dot{E}_0, \dot{L}_0$

$\Rightarrow \delta G_{ap}^{(1,kr)}$ describes the system's slow response to $\delta^2 G_{ap}$

\downarrow
neglect $\frac{\partial}{\partial t}$ terms
 $\therefore T_{ap}^{GW} = -\frac{1}{8\pi} \langle \delta^2 G_{ap}^{(0)} \rangle = -\frac{1}{8\pi} \frac{1}{4\pi^2} \int_0^{2\pi} d\psi^r \int_0^{2\pi} d\psi^\phi \delta^2 G_{ap}^{(0)}[h^{(0)}]$

$\Rightarrow -\frac{1}{8\pi} \delta^2 G_{ap}^{(0,0)}$ is the relevant effective stress-energy

Note: recall we wrote $h_{\text{ap}}^{(1)} = \sum_{k \in \mathbb{Z}} h_{\text{ap}}^{(1,k)}(x^A, t) e^{-ikr} \gamma^k$ in the two-timescale expansion.

We can also write the coefficients as $h_{\text{ap}}^{(1,k)}(x^A, J_0''(t))$,

i.e., their slow-time dependence arises from their dependence on the slowly evolving "constants" of motion

(they also contain terms arising from the slow evolution of the large BH's mass and spin, but those terms are not needed at adiabatic order, because they do not contribute to f^T)

This $h_{\text{ap}}^{(1)}$ is not the $h_{\text{ap}}^{(1)}$ sourced by a geodesic orbit.

But, the coefficients $h_{\text{ap}}^{(1,k)}(x^A, J_0''(t))$ are identical, for a given value of J_0'' , to the coefficients in the expansion for a geodesic, $h_{\text{ap}}^{(1)} = \sum_{k \in \mathbb{Z}} h_{\text{ap}}^{(1,k)}(x^A, J_0'') e^{-ikr} \gamma^k$

↑ fixed phases evolve linearly
 with time for a geodesic

Since only the coefficients contribute to the adiabatic evolution, this is what allows us to use the $h_{\text{ap}}^{(1)}$ for a sequence of geodesics.