

# IX Southern-Summer School on Mathematical Biology

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## Lecture III



# Outline

## 1 Competition



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- 1 Competition
- 2 Mathematical Model



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2 Mathematical Model

3 Interpretation!



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- 1 Competition
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- 3 Interpretation!
- 4 Protozoa, ants and plankton!

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- 1 Competition
- 2 Mathematical Model
- 3 Interpretation!
- 4 Protozoa, ants and plankton!
- 5 References



# Competition

- Consider **competition** between two species.
- We say that two species compete if the presence of one of them is detrimental for the other, and vice versa.
- The underlying biological mechanisms can be of two kinds;
  - ▶ **exploitative competition**: both species compete for a limited resource.
    - ★ Its strength depends also on the resource .
  - ▶ **Interference competition**: one of the species actively interferes in the access to resources of the other .
  - ▶ Both types of competition may coexist.



# Models for species in competition

- We are speaking of **inter-specific competition**
- **Intra-specific competition** gives rise to the models like the logistic that we studied in the first lecture.
- In a broad sense we can distinguish two kinds of models for competition:
  - ▶ **implicit**: that do not take into account the dynamics of the resources.
  - ▶ **explicit** where this dynamics is included.

# Mathematical Model

- Let us begin with the simplest case:
  - ▶ **Two species,**
  - ▶ **Implicit completion model,**
  - ▶ **intra-specific competition taken into account.**
- We proceed using the same rationale that was used for the predator-prey system.

# Lotka-Volterra model for competition

Let  $N_1$  and  $N_2$  be the two species in question.

# Lotka-Volterra model for competition

Each of them increases logistically in the absence of the other:

$$\frac{dN_1}{dt} = r_1 N_1 \left[ 1 - \frac{N_1}{K_1} \right]$$

$$\frac{dN_2}{dt} = r_2 N_2 \left[ 1 - \frac{N_2}{K_2} \right]$$

where  $r_1$  and  $r_2$  are the intrinsic growth rates and  $K_1$  and  $K_2$  are the carrying capacities of both species in the absence of the other..

# Lotka-Volterra model for competition

We introduce the mutual detrimental influence of one species on the other:

$$\frac{dN_1}{dt} = r_1 N_1 \left[ 1 - \frac{N_1}{K_1} - aN_2 \right]$$

$$\frac{dN_2}{dt} = r_2 N_2 \left[ 1 - \frac{N_2}{K_2} - bN_1 \right]$$

# Lotka-Volterra model for competition

Or, in the more usual way :

$$\frac{dN_1}{dt} = r_1 N_1 \left[ 1 - \frac{N_1}{K_1} - b_{12} \frac{N_2}{K_1} \right]$$

$$\frac{dN_2}{dt} = r_2 N_2 \left[ 1 - \frac{N_2}{K_2} - b_{21} \frac{N_1}{K_2} \right]$$

# Lotka-Volterra model for competition

Or, in the more usual way:

$$\frac{dN_1}{dt} = r_1 N_1 \left[ 1 - \frac{N_1}{K_1} - \overbrace{b_{12}}^{\downarrow} \frac{N_2}{K_1} \right]$$

$$\frac{dN_2}{dt} = r_2 N_2 \left[ 1 - \frac{N_2}{K_2} - \overbrace{b_{21}}^{\downarrow} \frac{N_1}{K_2} \right]$$

where  $b_{12}$  and  $b_{21}$  are the coefficients that measure the **strength of the competition between the populations**.

## Lotka-Volterra model for competition

This is a Lotka-Volterra type model for competing species. Pay attention to the fact that both interaction terms come in with negative signs. All the constants  $r_1, r_2, K_1, K_2, b_{12}$  and  $b_{21}$  are positive.

$$\frac{dN_1}{dt} = r_1 N_1 \left[ 1 - \frac{N_1}{K_1} - b_{12} \frac{N_2}{K_1} \right]$$

$$\frac{dN_2}{dt} = r_2 N_2 \left[ 1 - \frac{N_2}{K_2} - b_{21} \frac{N_1}{K_2} \right]$$

Let's now try to analyze this system of two differential equations .

# Analyzing the model I

We will first make a change of variables, by simple re-scalings.

$$\frac{dN_1}{dt} = r_1 N_1 \left[ 1 - \frac{N_1}{K_1} - b_{12} \frac{N_2}{K_1} \right]$$

Define:

$$u_1 = \frac{N_1}{K_1}, \quad u_2 = \frac{N_2}{K_2}, \quad \tau = r_1 t$$

$$\frac{dN_2}{dt} = r_2 N_2 \left[ 1 - \frac{N_2}{K_2} - b_{21} \frac{N_1}{K_2} \right]$$

In other words, we are measuring populations in units of their carrying capacities and the time in units of  $1/r_1$ .

## Analyzing the model II

The equations in  
the new variables.

$$\frac{du_1}{d\tau} = u_1 \left[ 1 - u_1 - b_{12} \frac{K_2}{K_1} u_2 \right]$$

$$\frac{du_2}{d\tau} = \frac{r_2}{r_1} u_2 \left[ 1 - u_2 - b_{21} \frac{K_1}{K_2} u_1 \right]$$

## Analyzing the model III

Defining:

$$\frac{du_1}{d\tau} = u_1 [1 - u_1 - a_{12}u_2]$$

$$\frac{du_2}{d\tau} = \rho u_2 [1 - u_2 - a_{21}u_1]$$

$$a_{12} = b_{12} \frac{K_2}{K_1},$$

$$a_{21} = b_{21} \frac{K_1}{K_2}$$

$$\rho = \frac{r_2}{r_1}$$

we get these equations.  
It's a system of nonlinear ordinary differential equations.

We need to study the behavior of their solutions



## Analyzing the model IV

$$\frac{du_1}{d\tau} = u_1 [1 - u_1 - a_{12}u_2]$$

No explicit solutions!

$$\frac{du_2}{d\tau} = \rho u_2 [1 - u_2 - a_{21}u_1]$$

- We will develop a *qualitative* analysis of these equations.
- Begin by finding the points in the  $(u_1 \times u_2)$  plane such that:

$$\frac{du_1}{d\tau} = \frac{du_2}{d\tau} = 0,$$

the **fixed points**.

# Analyzing the model V

- $$\frac{du_1}{d\tau} = 0 \Rightarrow u_1 [1 - u_1 - a_{12}u_2] = 0$$

- $$\frac{du_2}{d\tau} = 0 \Rightarrow u_2 [1 - u_2 - a_{21}u_1] = 0$$

# Analyzing the model V



$$u_1 [1 - u_1 - a_{12}u_2] = 0$$



$$u_2 [1 - u_2 - a_{21}u_1] = 0$$

- These are two algebraic equations for (  $u_1$  e  $u_2$  ).
- We **FOUR** solutions. Four fixed points.

# Fixed points

$$u_1^* = 0$$

$$u_2^* = 0$$

$$u_1^* = 0$$

$$u_2^* = 1$$

$$u_1^* = 1$$

$$u_2^* = 0$$

$$u_1^* = \frac{1 - a_{12}}{1 - a_{12}a_{21}}$$

$$u_2^* = \frac{1 - a_{21}}{1 - a_{12}a_{21}}$$

The relevance of those fixed points depends on their **stability**. Which, in turn, depend on the values of the parameters  $a_{12}$  e  $a_{21}$ . We have to proceed by a phase-space analysis, calculating community matrixes and finding eigenvalues.....take a look at *J.D. Murray (Mathematical Biology)*.

# Stability

If  $a_{12} < 1$  and  $a_{21} < 1$

$$u_1^* = \frac{1 - a_{12}}{1 - a_{12}a_{21}}$$

$$u_2^* = \frac{1 - a_{21}}{1 - a_{12}a_{21}}$$

is **stable**.

If  $a_{12} < 1$  and  $a_{21} > 1$

$$u_1^* = 1 \text{ e } u_2^* = 0$$

is **stable**.

If  $a_{12} > 1$  and  $a_{21} > 1$

$$u_1^* = 1 \text{ e } u_2^* = 0$$

$$u_1^* = 0 \text{ e } u_2^* = 1$$

are **both stable**.

If  $a_{12} > 1$  and  $a_{21} < 1$

$$u_1^* = 0 \text{ e } u_2^* = 1$$

is **stable**.

The stability of the fixed points depends on the values of  $a_{12}$  and  $a_{21}$ .

# Phase space

- To have a more intuitive understanding of the dynamics it is useful to consider the trajectories in the phase space
- For every particular combination of  $a_{12}$  and  $a_{21}$  – but actually depending if they are smaller or greater than 1 – ,we will have a qualitatively different phase portrait.

# Phase Space II

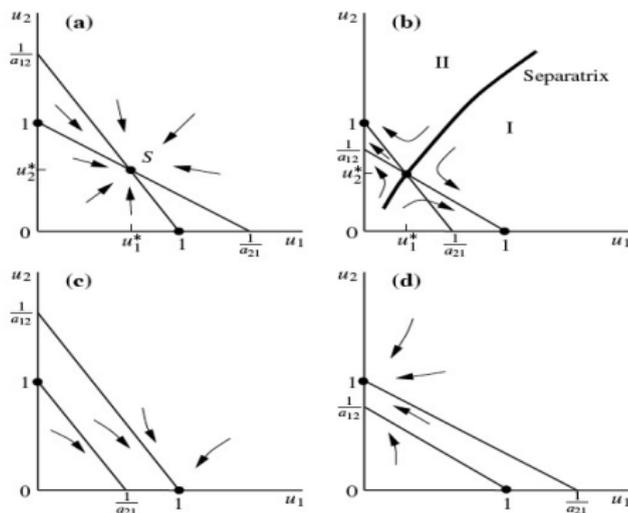


Figura: The four cases. The four different possibilities for the phase portraits.

# Coexistence

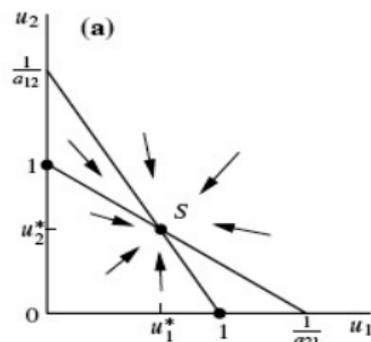


Figura:  $a_{12} < 1$  and  $a_{21} < 1$ . The fixed point  $u_1^*$  and  $u_2^*$  is stable and represents the coexistence of both species. It is a **global attractor**.

# Exclusion

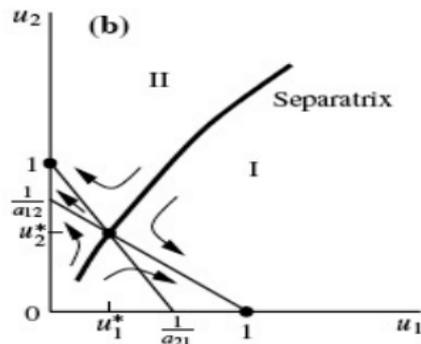


Figura:  $a_{12} > 1$  and  $a_{21} > 1$ . The fixed point  $u_1^*$  and  $u_2^*$  is unstable. The points (1,0) and (0,1) are stable but have *finite basins of attraction*, separated by a *separatrix*. The stable fixed points represent *exclusion* of one of the species.

# Exclusion

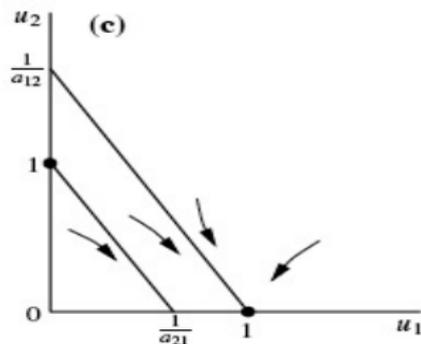


Figura:  $a_{12} < 1$  and  $a_{21} > 1$ . The only stable fixed is  $(u_1 = 1, u_2 = 0)$ . A global attractor. Species (2) is excluded.

# Exclusion

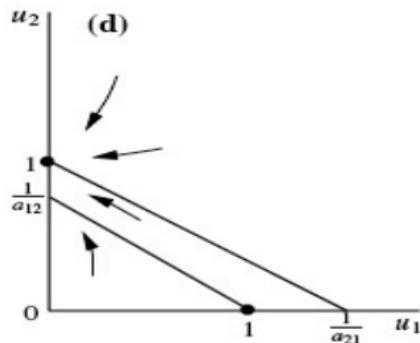


Figura: This case is symmetric to the previous.  $a_{12} > 1$  and  $a_{21} < 1$ . The only stable fixed point is  $(u_1 = 1, u_2 = 0)$ . A global attractor. Species (1) is excluded

# Interpretation of the results

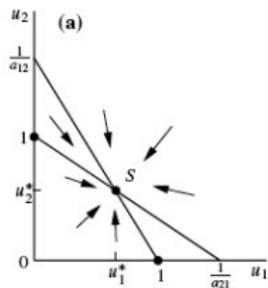
- What is the meaning of these results?
- Let us recall the meaning of  $a_{12}$  and  $a_{21}$ :

$$\frac{du_1}{d\tau} = u_1 [1 - u_1 - a_{12}u_2]$$

$$\frac{du_2}{d\tau} = \rho u_2 [1 - u_2 - a_{21}u_1]$$

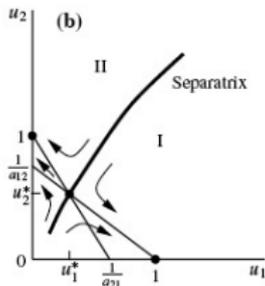
- ▶  $a_{12}$  is a measure of the influence of species 2 on species 1. How detrimental 2 is to 1.
- ▶  $a_{21}$  measures the influence of species 1 on species 2. How detrimental 1 is to 2.
- So, we may translate the results as:
  - ▶  $a_{12} > 1 \Rightarrow$  2 competes strongly with 1 for resources.
  - ▶  $a_{21} > 1 \Rightarrow$  1 competes strongly with 2 for resources.
- This leads us to the following rephrasing of the results :

If  $a_{12} < 1$  and  $a_{21} < 1$   
 The competition is **weak** and both can coexist.



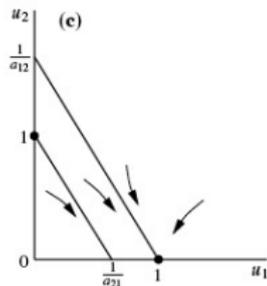
If  $a_{12} > 1$  and  $a_{21} > 1$

The competition is mutually **strong**. One species always excludes the other. Which one "wins" depends on initial conditions.



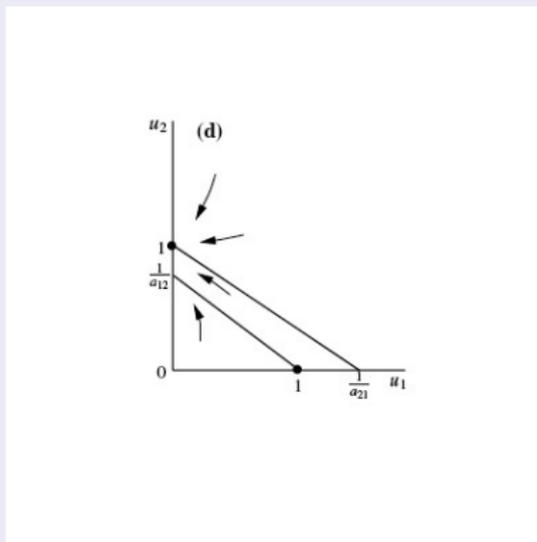
If  $a_{12} < 1$  e  $a_{21} > 1$

Species 1 is not strongly affected by species 2. But species 2 is affected strongly by species 1. Species 2 is eliminated, and species 1 attains its carrying capacity.



Se  $a_{12} > 1$  e  $a_{21} < 1$

This is symmetric to the previous case. Species 1 is eliminated and Species 2 attains its carrying capacity



# Competitive exclusion

- In summary: the mathematical model predicts patterns of exclusion. Strong competition always leads to the exclusion of a species
- Coexistence is only possible with weak competition.
- The fact that a stronger competitor eliminates the weaker one is known as the **competitive exclusion principle**.



*Georgiy F. Gause (1910-1986), Russian biologist, was the first to state the principle of competitive exclusion (1932).*

# Paramecium

The experiences of G.F. Gause were performed with a protozoa group called *Paramecia*.

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# Paramecium

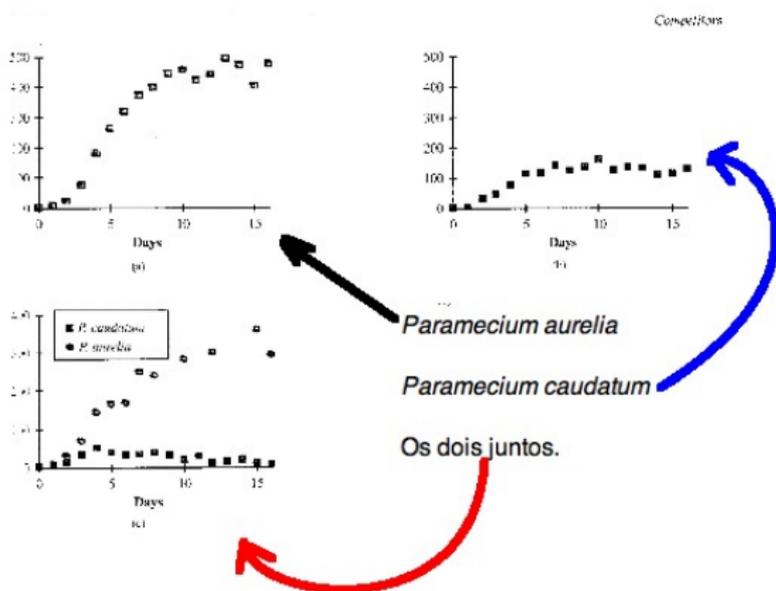
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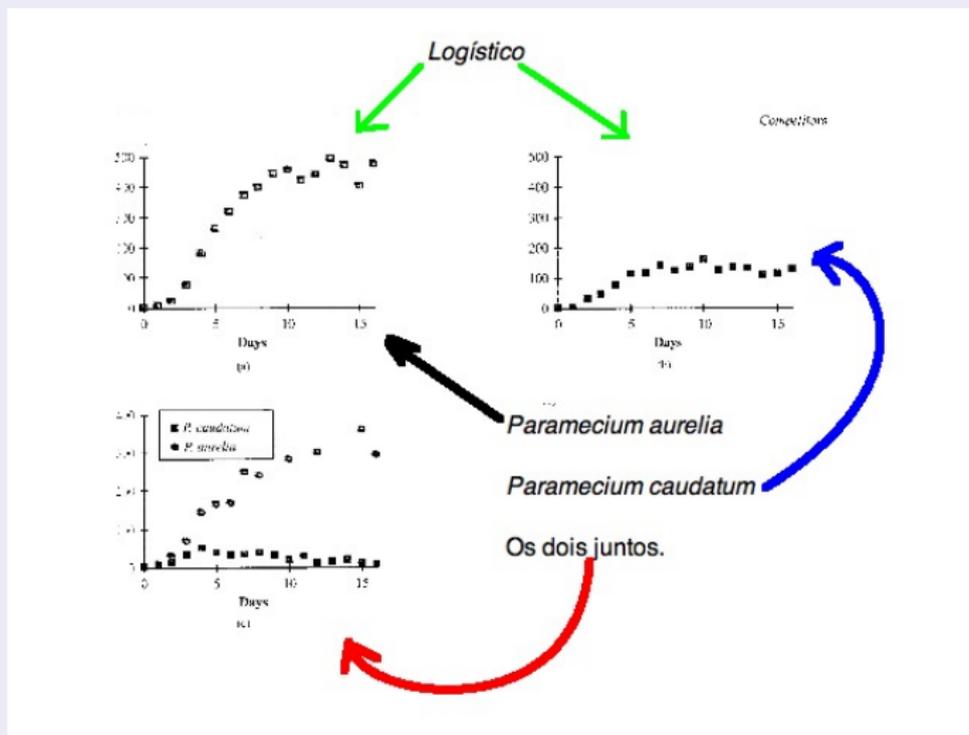
When they grow in the same culture, *P. aurelia* survives and *P. caudatum* is eliminated.



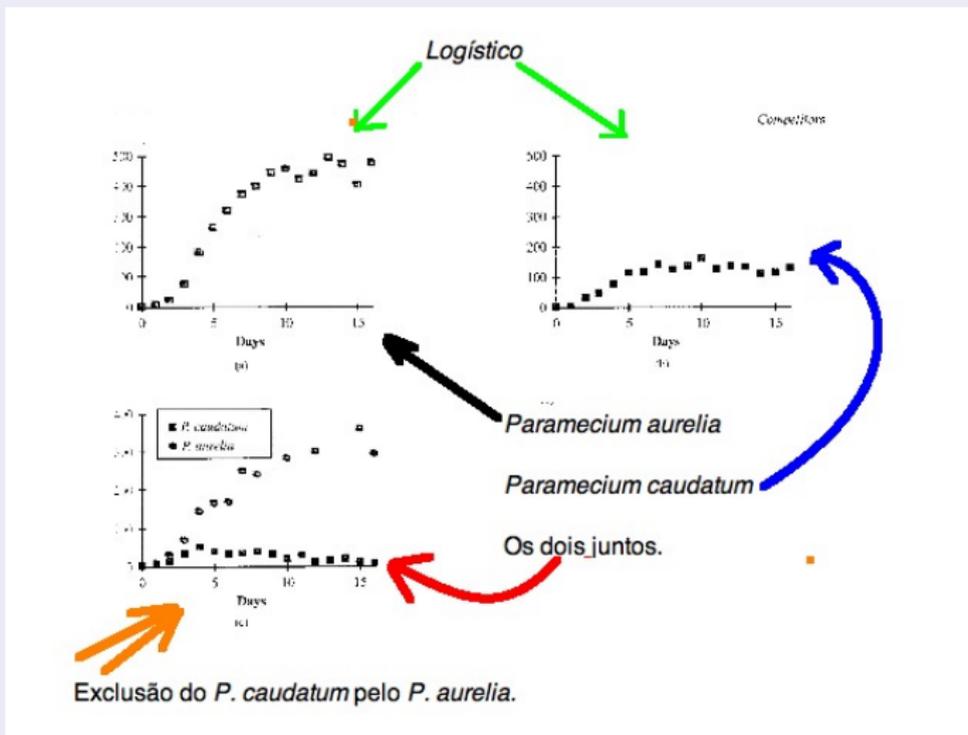
# Paramecium



# Paramecium



# Paramecium



# Ants



**Figura:** The Argentinean ant (*Linepithema humile*) and the Californian one (*Pogonomyrmex californicus*)

- The introduction of the Argentinean ant in California had the effect to exclude *Pogonomyrmex californicus*.
- Here is a plot with data....

## Ants II

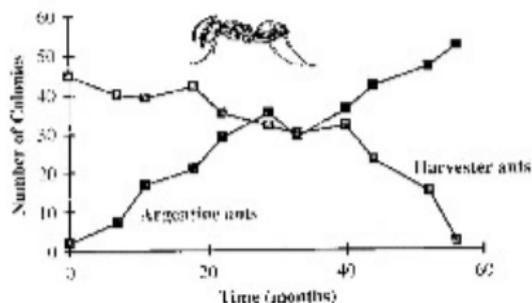
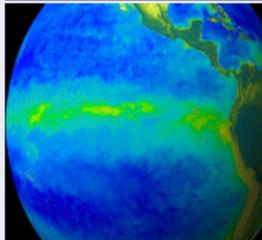


Figura: The introduction of the Argentinean ant in California had the effect of excluding *Pogonomyrmex californicus*

# Plankton

In view of the principle of competitive exclusion, consider the situation of *phytoplankton*.

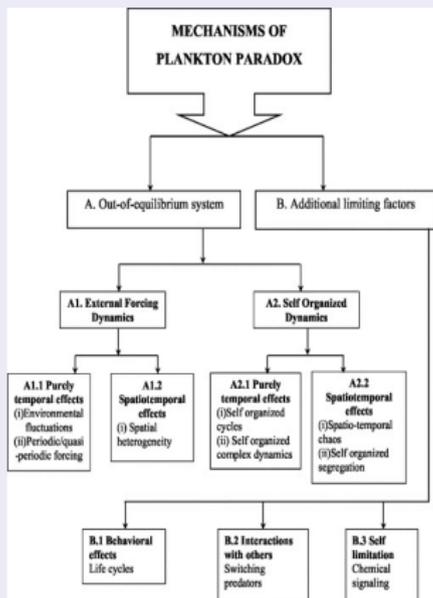


- Phytoplankton are organisms that live in seas and lakes, in the region where there is light.
- You won't see a phytoplankton with naked eye..
- You can see only the visual effect of a large number of them.
- It needs light + inorganic molecules.

# The Plankton Paradox

- The plankton paradox consists of the following:
- There are many species of phytoplankton. It used a very limited number of different resources. Why is there no competitive exclusion?

# One paradox, many possible solutions



- Competitive exclusion is a property of the fixed points. But if the environment changes, the equilibria might not be attained. We are always in transient dynamics.
- We have considered no spatial structure. Different regions could be associated with different limiting factors, and thus could promote diversity.
- Effects of trophic webs.

# References

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# Online Resources

- <http://ecologia.ib.usp.br/ssmb/>

Thank you for your attention