



$$j^\mu = \bar{q}_L q_\mu + j_{SA}^\mu - \frac{g}{\sqrt{2}} W_\mu^+ j_+^\mu + \frac{g}{\sqrt{2}} W_\mu^- j_-^\mu - e A_\mu j_e - \frac{g}{c_W} Z_\mu j_h$$

$$j_{eu}^\mu = Q_u \bar{u}_{iL} \gamma^\mu u_{iL} + Q_d \bar{d}_{iL} \gamma^\mu d_{iL} + \dots Q_u \bar{u}_R i \gamma^\mu u_R + \dots$$

$$= Q_u \bar{u}_{iL} \gamma^\mu u_{iL} \quad (\text{same form})$$

$$j_h^\mu = \sum_{f=u,d,v,e; x=L,R} f_x \bar{\gamma}^\mu (\bar{T}_f - \delta_{\mu 0} Q_f) f_x = \dots \quad (\text{same form})$$

$$j_+^\mu = \bar{Q}_+ \gamma^\mu Q_+ + \bar{l}_+ \gamma^\mu l_+ =$$

$$= \bar{u}_{iL} \gamma^\mu d_{iL} + \bar{e}_{iL} \gamma^\mu e_{iL}$$

$$u_{iL}^I = U_{ij}^{u_L} u_{jL}^I$$

$$= V_{ij} \bar{u}_{iL}^I \gamma^\mu d_{jL}^I + \bar{e}_{iL}^I \gamma^\mu e_{jL}^I$$

$$d_{iL}^I = U_{ij}^{d_L} d_{jL}^I$$

$V = U_{uL} U_{ud}^+$

Cabibbo Kobayashi Maskawa

neutrino flavor eigenstate  $\leftarrow \nu_{iL}^I = U_{ij}^{\nu_L} \nu_{jL}^I$   
 (if  $M_\nu$  to PMNS  $U$ )

$$e_{iL}^I = U_{ij}^{e_L} e_{jL}^I$$

$$H = \begin{pmatrix} i\zeta^+ \\ u + \frac{\varphi - i\zeta^0}{\sqrt{2}} \end{pmatrix} \quad H^I = \begin{pmatrix} i\zeta^+ \\ \frac{\varphi - i\zeta^0}{\sqrt{2}} \end{pmatrix} \quad \varphi \quad \zeta^0 \quad \zeta^+ \quad \zeta^-$$

$$\dots = \frac{\lambda_e}{\sqrt{2}} \overline{e_R} e_L^\dagger \varphi + \frac{\lambda_d}{\sqrt{2}} \overline{d_R} d_L^\dagger \varphi + \frac{\lambda_u}{\sqrt{2}} \overline{u_R} u_L^\dagger \text{the}$$

$$\lambda_G = U_{uR}^\dagger \underbrace{U_{uL}}_{\text{diag}} U_{uL} \quad \mu = v \lambda$$

$$\lambda_e = \frac{m_e}{v}$$

$$\zeta^0 : \varphi \rightarrow i\zeta^0$$

$$\zeta^\pm :$$

$$\lambda_{d_i} V_{ij}^+ \overline{d_{R_i}^T} u_L^j i\zeta^- + \lambda_{u_i} V_{ij} \overline{u_{R_i}^T} d_L^j i\zeta^+ + h.c.$$

**DRGP " "** from now on

$$V = \begin{pmatrix} e^{i\sigma_1} & & \\ & e^{i\sigma_2} & \\ & & e^{i\sigma_3} \end{pmatrix} V_{CKM} \begin{pmatrix} e^{i\sigma_1} & & \\ & e^{i\sigma_2} & \\ & & e^{i\sigma_3} \end{pmatrix} e^{i\sigma_1} = 1$$

$$g = 3 + 4 + 2$$

$$\frac{g}{\sqrt{2}} V_{ij} \overline{u_L^i} \gamma^\mu d_{jL} w_\mu^+ = \frac{g}{\sqrt{2}} V_{ij}^C \overline{u_L^i} \gamma^\mu d_{jL}^T w_\mu^+$$

$$u_{iL}^i = e^{-i\sigma_i} u_{iL}^i$$

$$d_{iL}^i = e^{i\sigma_i} d_{iL}^i$$

P and CP

$$(a, \lambda) \quad n^\mu \rightarrow x^{\mu}, \bar{x}^\nu + a^\lambda$$

$$P: n \rightarrow x_p = (x^0, \vec{x})$$

$$P(a, \lambda) \tilde{P} = (a_p, \lambda^{T-1}) \quad \lambda \rightarrow L \quad L \rightarrow L^{T-1}$$

$$Q \rightarrow Q$$

P

$$4_L \rightarrow 4_R \quad \overline{4}_L$$

$$Q \rightarrow -Q$$

CP

$$4_L \rightarrow \overline{4}_L$$

JCP under which gauge int. are invariant

$$\mathcal{L}_{\text{QCD+QED}} \subseteq \mathcal{L}_{\text{SM}}$$

invariant under CP

$$\psi(x) \rightarrow \underline{\epsilon}^{i\theta_4} \psi^*(x)$$

$$C = \begin{pmatrix} \varepsilon & 0 \\ 0 & -\varepsilon \end{pmatrix}$$

$$\psi = u_L, u_R, d_L, d_R, e_L, e_R$$

$$\varepsilon = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

$$v^\mu(x) \rightarrow -v_\mu^*(x)$$

$$\frac{g}{\sqrt{2}} V_{ij} \overline{u_{iL}} \gamma^\mu u_{jL} w_\mu^+ + \frac{g}{\sqrt{2}} V_{ij}^\dagger \overline{d_{iL}} \gamma^\mu u_{jL} \overline{w_\mu^-} \Rightarrow$$

$$\frac{g}{\sqrt{2}} V_{ij}^\dagger \overline{u_{jL}} \gamma^\mu d_{iL} w_\mu^+ e^{i(\theta_{ui} - \theta_{di})} + \dots =$$

CP conserved  $\Leftrightarrow$

$$e^{-i\theta_{ui}} V_{ij} e^{i\theta_{aj}} \text{ real}$$

1.2 families yes

3 no if  $\sin \delta \neq 0$

$$V_{ij}$$

$$\operatorname{Im}(V_{us} V_{cs}^* V_{cb}^* V_{ub}^*)$$

Jarlskog invariant

$$= \operatorname{Im}(V_{us} V_{cs}^* V_{cb} V_{ub}^*)$$

$$= \underbrace{c_{12} c_{23} c_{13}^2 s_{12} s_{13} s_{23}}_{\neq 0} \sin \delta$$