# Structure Formation Lecture 3 

## Fabian Schmidt MPA

All figures taken from Modern Cosmology, Second Edition, unless otherwise noted

# MODERN COSMOLOGY 

## Outline of lectures

I. The problem: collisionless Boltzmann equation and fluid approximation
I. Linear evolution
2. Nonlinear evolution of matter
I. Perturbation theory
2. Simulations
<- HERE
3. Phenomenology of nonlinear matter distribution
3. Formation and distribution of galaxies
I. Galaxy formation in a nutshell
2. Spherical collapse model
3. Physical clustering of halos and galaxies; bias
4. Observed clustering of galaxies
4. Beyond $\Lambda$ CDM

## Notation

$$
d s^{2}=-(1+2 \Psi(\boldsymbol{x}, t)) d t^{2}+a^{2}(t)(1+2 \Phi(\boldsymbol{x}, t)) d \boldsymbol{x}^{2}
$$

- Comoving coordinates:

$$
d \boldsymbol{r}=a(t) d \boldsymbol{x}
$$

- Conformal time:

$$
d \eta=\frac{d t}{a(t)}=\frac{d a}{a^{2} H(a)}=\frac{d \ln a}{a H(a)} .
$$

- Comoving distance:

$$
d \chi=-d \eta=\frac{d z}{H(z)}
$$

- Particle velocity/momentum: $\boldsymbol{v}=\frac{\boldsymbol{p}}{m}=a \frac{d \boldsymbol{x}}{d t}=\boldsymbol{x}^{\prime}$
- Fluid velocity; divergence:

$$
\boldsymbol{u} ; \quad \theta=\partial_{i} u^{i}
$$

- Gravitational potential:


## Notation

- The linear power spectrum (filling in a gap in Lecture I)
- Almost-scale-invariant power spectrum from inflation: $\quad P_{\mathcal{R}}(k)=2 \pi^{2} \mathcal{A}_{s} k^{-3}\left(\frac{k}{k_{\mathrm{p}}}\right)^{n_{s}-1}$
- Relating $\delta$ to curvature perturbation:

$$
\begin{aligned}
& \delta^{(1)}(\boldsymbol{k}, \eta)=\frac{2 k^{2} a(\eta)}{3 \Omega_{m} H_{0}^{2}} \Phi(\boldsymbol{k}, \eta) ; \quad \Phi(\boldsymbol{k}, \eta)=\frac{3}{5} T(k) \frac{D(a)}{a} \mathcal{R}(\boldsymbol{k}) \\
& R \text { RSUlt: }
\end{aligned} \begin{aligned}
& \text { Note: throughout, } \delta \text { is in synchronous-comoving gauge. Then } \\
& \text { this relation remains valid on all scales. }
\end{aligned}
$$

$$
\begin{gathered}
P_{\mathrm{L}}(k, a)=\frac{8 \pi^{2}}{25} \frac{\mathcal{A}_{s}}{\Omega_{\mathrm{m}}^{2}} D_{+}^{2}(a) T^{2}(k) \frac{k^{n_{s}}}{H_{0}^{4} k_{\mathrm{p}}^{n_{s}-1}} \\
\left(D_{+} \equiv D\right)
\end{gathered}
$$

## Notation

- The linear power spectrum (filling in a gap in Lecture I)
- Almost-scale-invariant power spectrum from inflation: $\quad P_{\mathcal{R}}(k)=2 \pi^{2} \mathcal{A}_{s} k^{-3}\left(\frac{k}{k_{\mathrm{p}}}\right)^{n_{s}-1}$
- Relating $\delta$ to curvature perturbation:

$$
\delta^{(1)}(\boldsymbol{k}, \eta)=\frac{2 k^{2} a(\eta)}{3 \Omega_{m} H_{0}^{2}} \Phi(\boldsymbol{k}, \eta) ; \quad \Phi(\boldsymbol{k}, \eta)=\frac{3}{5} T(k)_{a}^{\left.(D)^{2}\right)} \mathcal{R}(\boldsymbol{k})
$$

- Result:

$$
\begin{gathered}
P_{\mathrm{L}}(k, a)=\frac{8 \pi^{2}}{25} \frac{\mathcal{A}_{s}}{\Omega_{\mathrm{m}}^{2}} D_{+}^{2}(a) T^{2}(k) \frac{k^{n_{s}}}{H_{0}^{4} k_{\mathrm{p}}^{n_{s}-1}} \\
\left(D_{+} \equiv D\right)
\end{gathered}
$$

## Notation

- The linear power spectrum (filling in a gap in Lecture I)
- Almost-scale-invariant power spectrum from inflation: $\quad P_{\mathcal{R}}(k)=2 \pi^{2} \mathcal{A}_{s} k^{-3}\left(\frac{k}{k_{\mathrm{p}}}\right)^{n_{s}-1}$
- Relating $\delta$ to curvature perturbation:

$$
\delta^{(1)}(\boldsymbol{k}, \eta)=\frac{2 k^{2} a(\eta)}{3 \Omega_{m} H_{0}^{2}} \Phi(\boldsymbol{k}, \eta) ; \quad \Phi(\boldsymbol{k}, \eta)=\frac{3}{5} T(k) \frac{D(a)}{a} \mathcal{R}(\boldsymbol{k})
$$

Transfer function: evolution of

- Result: perturbations in early Universe

$$
\begin{gathered}
P_{\mathrm{L}}(k, a)=\frac{8 \pi^{2}}{25} \frac{\mathcal{A}_{s}}{\Omega_{\mathrm{m}}^{2}} D_{+}^{2}(a) T^{2}(k) \frac{k^{n_{s}}}{H_{0}^{4} k_{\mathrm{p}}^{n_{s}-1}} \\
\left(D_{+} \equiv D\right)
\end{gathered}
$$

## Notation

- The linear power spectrum (filling in a gap in Lecture I)
- Almost-scale-invariant power spectrum from inflation: $\quad P_{\mathcal{R}}(k)=2 \pi^{2} \mathcal{A}_{s} k^{-3}\left(\frac{k}{k_{\mathrm{p}}}\right)^{n_{s}-1}$
- Relating $\delta$ to curvature perturbation:

$$
\delta^{(1)}(\boldsymbol{k}, \eta)=\frac{2 k^{2} a(\eta)}{3 \Omega_{m} H_{0}^{2}} \Phi(\boldsymbol{k}, \eta) ; \quad \Phi(\boldsymbol{k}, \eta)=\frac{3}{5} T(k) \frac{D(a)}{a} \mathcal{R}(\boldsymbol{k})
$$

- Result:

$$
\begin{gathered}
P_{\mathrm{L}}(k, a)=\frac{8 \pi^{2}}{25} \frac{\mathcal{A}_{s}}{\Omega_{\mathrm{m}}^{2}} D_{+}^{2}(a) T^{2}(k) \frac{k^{n_{s}}}{H_{0}^{4} k_{\mathrm{p}}^{n_{s}-1}} \text { Time dependence of linear } \mathrm{P}(\mathrm{k}) \sim \mathrm{D}^{2}, \\
\left(D_{+} \equiv D\right)
\end{gathered}
$$

## Structure formation beyond perturbation theory

- In order to take phasespace evolution into account properly, need to go beyond fluid picture and perturbation theory.
- Back to collisionless Boltzmann equation!
- Instead of trying to calculate 6D distribution function, we will discretize the thin phasespace sheet that (dark) matter is localized in

```
                                    Phase-space
                                    sheet
```


## N-body simulations

- Discretize the thin phasespace sheet that (dark) matter is localized in
- Follow the evolution of phasespace elements ("particles") by integrating the geodesic equation (characteristics of the PDE)



## N -body simulations

- Discretize the thin phasespace sheet that (dark) matter is localized in
- Follow the evolution of phasespace elements ("particles") by integrating the geodesic equation (characteristics of the PDE)
- Equations of motion:

$$
\begin{array}{ll}
\frac{d x^{i}}{d t}=\frac{p^{i}}{m a}, & p_{c}^{i}=a p^{i} \\
\frac{d p^{i}}{d t}=-H p^{i}-\frac{m}{a} \frac{\partial \Psi}{\partial x^{i}} . &
\end{array} \begin{aligned}
& \frac{d x^{i}}{d t}=\frac{p_{c}^{i}}{m a^{2}}, \\
& \frac{d p_{c}^{i}}{d t}=-m \frac{\partial \Psi}{\partial x^{i}} . \tag{I2.57}
\end{aligned}
$$

$$
\text { and } \quad \nabla^{2} \Psi=\frac{3}{2} \Omega_{\mathrm{m}}(\eta)(a H)^{2} \delta_{\mathrm{m}}
$$

## N -body simulations in one step

- Structure appears after just one time step!
- Specifically, solve for particle displacement at linear order: Ist order Lagrangian perturbation theory (Zel'dovich approximation)
- Technique used to generate initial conditions for full simulations at high z




## Time integration

- Leapfrog scheme: preserves energy (as well as other constants of motion) to cubic order in time step

1. Compute the gravitational potential generated by the collection of particles, and take its gradient to obtain $\nabla \Psi(\boldsymbol{x}, t)$
2. Change each particle's momentum ("kick") by

$$
\begin{equation*}
\boldsymbol{p}_{c}^{(i)}(t+\Delta t / 2)=\boldsymbol{p}_{c}^{(i)}(t-\Delta t / 2)-m \nabla \Psi\left(\boldsymbol{x}^{(i)}, t\right) \Delta t . \tag{12.59}
\end{equation*}
$$

3. Move each particle position ("drift") by

$$
\begin{equation*}
\boldsymbol{x}^{(i)}(t+\Delta t)=\boldsymbol{x}^{(i)}(t)+\frac{\boldsymbol{p}_{c}^{(i)}(t+\Delta t / 2)}{m a^{2}(t+\Delta t / 2)} \Delta t \tag{12.60}
\end{equation*}
$$

4. Repeat.

## Position: <br> (Drift)



Velocity:
(Kick)


## Solving for the force

- In order to move particles, we need to calculate the force (gradient of the potential) at each particle's position
- As accurately as possible, but with reasonable cost
- Example: could directly sum up forces of all other particles (direct summation or particle-particle algorithm)

$$
\nabla \Psi\left(\boldsymbol{x}_{i}\right)=G m \sum_{j \neq i} \frac{\boldsymbol{x}_{j}-\boldsymbol{x}_{i}}{\left|\boldsymbol{x}_{j}-\boldsymbol{x}_{i}\right|^{3}}
$$

- Problem: computational cost scales as $N^{2}$ for $N$ particles
- Our goal is to use billions of particles, so algorithm has to scale as $N$ or $N \log N$ at most.

Reminder: N -body particles are not actual particles!

## Solving for the force

- Simplest solution: solve potential on a fixed grid: particle-mesh (PM) algorithm
I. Assign particles to grid to obtain density (most commonly using cloud-in-cell [CIC] assignment)

2. Solve Poisson equation on grid, via discrete Fast Fourier Transform (FFT)

$$
\nabla^{2} \Psi=\frac{3}{2} \Omega_{\mathrm{m}}(\eta)(a H)^{2} \delta_{\mathrm{m}}
$$

3. Interpolate gradient of resulting potential to each particle's position (using same interpolation scheme)

- Cost: $N \log N$ due to FFT


## The resolution problem

- Issue: fixed grid means fixed resolution
- Cannot resolve small-scale structure below grid resolution, and increasing resolution is memory- and CPU-intensive $\left(\sim N_{\text {grid }}{ }^{3}\right)$
- On the other hand, we don't need high resolution for a large fraction of the volume



## The resolution problem

- Issue: fixed grid means fixed resolution
- On the other hand, we don't need high resolution for a large fraction of the volume
- Solution: adaptive algorithms which go to higher resolution only where necessary



# Adaptive mesh refinement 

- Start with regular base grid
- Split any cell that crosses a certain particle number threshold into 8 sub-cells; repeat process until particle number sufficiently small in all cells
- Advantage: can use same grid for hydrodynamics

- Disadvantage: need relaxation method to solve Poisson equation on subgrids to incorporate boundary conditions


## Tree algorithm

- Get rid of grid: instead, lump particles together to compute their effect on distant other particles



## Tree algorithm

## - Get rid of grid: instead, lump particles together to compute their effect on distant other particles

At each node in the tree, one inserts a 'meta' particle that carries the mass and sits at the centre of mass of the branch of the tree. The total interaction


If we set $\lambda$ to be the centre of mass, then the dipole vanishes. The trick is now that since we know that $\left|m a t h b f x_{j}-\boldsymbol{\lambda}\right|$ is bounded by the space partitioning cell size, we can directly control the accuracy by accepting a meta particle as a valid approximation for the entire branch if

$$
\begin{equation*}
\theta=\frac{\ell}{|\mathbf{y}|}<\theta_{c} \tag{3.28}
\end{equation*}
$$

On small scales, use force softening to avoid particle "collisions", hard scattering.

## Tree algorithm

- Get rid of grid: instead, lump particles together to compute their effect on distant other particles
- Advantage: elegant and direct, no need for relaxation
- Disadvantage: need top-level grid for periodic boundary conditions, and hence split into grid and tree forces (Tree-PM)



## Brief history of

## cosmological simulations

First N-body calculation: light bulbs, photocells and galvanometers

ON THE CLUSTERING TENDENCIES AMONG THE NEBULAE
II. A STUDY OF ENCOUNTERS BETWEEN LABORATORY MODELS OF STELLAR SYSTEMS BY A NEW INTEGRATION PROCEDURE

ERIK HOLMBERG


## Brief history of

## cosmological simulations

N -body calculation supports the idea of dark Matter


## Brief history of

## cosmological simulations

1985: The CDM model plus gravitational instability can explain qualitatively the observed universe


# Brief history of cosmological simulations 

## 2017: EUCLID Flagship Simulation



Potter et al 2017

## Result of an N -body simulation

- Catalog of "particle" positions and velocities at various points in time
- Basically, position of the phase-space sheet after gravitational evolution
- Use this to degenerate density field, for example



## Result of an N -body simulation

- Catalog of"particle" positions and velocities at various points in time
- Basically, position of the phase-space sheet after gravitational evolution
- Use this to generate density field, for example


## Result of an N -body simulation

- Catalog of "particle" positions and velocities at various points in time
- Basically, position of the phase-space sheet after gravitational evolution
- Use this to generate density field, for example


## Phenomenology of nonlinear structure

- Small-scale density fluctuations are largest: small-scale structure forms first
- Then, structure successively assembles to large-mass objects
- Topologically, we have
- "3D:" voids - large underdense regions
- "2D:" sheets, or "pancakes"
- "ID:" filaments
- "0D:" bound structures - halos



## Phenomenology of nonlinear structure

- Small-scale density fluctuations are largest: small-scale structure forms first
- Then, structure successively assembles to large-mass objects
- Topologically menere
"3D:" voids - large underdense regions
- "2D:" sheets, or "pancakes"
- "ID:" filaments
- "0D:" bound structures - halos



## Phenomenology of nonlinear structure

- Small-scale density fluctuations are largest: small-scale structure forms first
- Then, structure successively assembles to large-mass objects
- Topologically, we have
- "3D:" voids - large underdense regions
- "2D:" sheets, or "pancakes"
- "D."flaments
- "OD:" bound structures - halos

FIGURE 12.6 Slices OTVidth $15 h^{-1} \mathrm{Mpc}$ through the density field at redshift zero in the Minnium N-body simulation which follows $10^{10}$ particles (momesespace elements). From top to motion, the different panels zoom in to show the hierarchical nature of the matter distribution in a $\Lambda C D M$ cosmology. The spatial scale is labeled in each panel. The color scale denotes density in logarithmic units. The simulations shown here are described in Springel et al. (2005).


## Dark matter halos

- Bound structures of dark matter and baryons
- Densest regions in the universe (from a cosmologist's viewpoint...)
- All galaxies are believed to be hosted by dark matter halos
- Strong observational evidence for this from dynamics (velocities of gas, galaxies) and gravitational lensing, both of which probe all matter
- The most massive halos are associated with galaxy clusters
- Still, halos are mostly studied as objects in simulations


## Finding dark matter halos

- Halos are found using tools called halo finders which work on the catalog of particle positions
- Start from density maxima in the density field
- Determine whether particles are bound by comparing velocity w.r.t center of mass with local escape velocity
- Repeat this iteratively, since center of mass changes when particles are added
- Algorithms differ in detail


## The issue of halo mass

- Strict definition, counting all particles that are bound, is not very practical: affected by numerical noise, and we don't observe dark matter anyway
- Definition based on maximum radius is more practical; however, no well-defined radius exists, since halo profiles smoothly transition to surrounding structure
- Instead, define mass and radius which enclose fixed density $\Delta$ times cosmic mean:

$$
\frac{M\left(<R_{\Delta}\right)}{4 \pi R_{\Delta}^{3} / 3}=\Delta \times \rho_{\mathrm{m}}\left(t_{0}\right), \quad M_{\Delta}=M\left(<R_{\Delta}\right)
$$

- Special case $\Delta=\mathrm{I}$ : Lagrangian radius $R_{L}$. Comoving size of region from which particles originated in the initial conditions. Important!

$$
M=\frac{4 \pi}{3} \bar{\rho}_{\mathrm{m}}\left(t_{0}\right) R_{L}^{3}
$$

## Halo abundance

- Mean number density of halos in logarithmic mass bins
- Power-law at small masses
- Exponential cutoff at high masses - reflecting Gaussian statistics of
 initial density field


## Inner structure of halos

- Spherically-averaged density profile: Navarro-Frenk-White (I996) (NFW) form is universal


Springel et al 2008

Eq. (I2.62)

$$
\begin{aligned}
& \rho(r)=\frac{\rho_{s}}{\left(r / r_{s}\right)\left(1+\left(r / r_{s}\right)\right)^{2}} \\
& \ln \rho(r) / \rho_{-2}=(-2 / \alpha)\left(r / r_{-2}\right)^{\alpha}
\end{aligned}
$$



Springel et al 2008

Slide credit:
Raul Angulo

## Inner structure of halos

- However, halos formed from smaller previous formed halos, which survive as substructure (subhalos)


Slide credit:
Raul Angulo

## From halos to galaxies

- We think that galaxies reside in these substructures of halos - but which ones...?
- Galaxy formation and (effective field) theory of galaxy clustering: next lecture!


