Structure Formation Lecture 3

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MODERN

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COSMOLOGY

Second Edition

All figures taken from Modern Cosmology, Second Edition, unless otherwise noted

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Outline of lectures

- I. The problem: collisionless Boltzmann equation and fluid approximation
 - I. Linear evolution
- 2. Nonlinear evolution of matter
 - I. Perturbation theory
 - 2. Simulations

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- 3. Phenomenology of nonlinear matter distribution
- 3. Formation and distribution of galaxies
 - I. Galaxy formation in a nutshell
 - 2. Spherical collapse model
 - 3. Physical clustering of halos and galaxies; bias
 - 4. Observed clustering of galaxies
- 4. Beyond ΛCDM

Notation

$$ds^{2} = -(1 + 2\Psi(\boldsymbol{x}, t))dt^{2} + a^{2}(t)(1 + 2\Phi(\boldsymbol{x}, t))d\boldsymbol{x}^{2}$$

- Comoving coordinates:
- Conformal time:
 - Comoving distance:
- Particle velocity/momentum: $v = \frac{p}{m}$
- Fluid velocity; divergence:
- Gravitational potential:

$$d\chi = -d\eta = \frac{dz}{H(z)}$$

 $d\mathbf{r} = a(t)d\mathbf{x}$

 $d\eta = \frac{dt}{a(t)} = \frac{da}{a^2 H(a)} = \frac{d\ln a}{a H(a)}.$

n:
$$\boldsymbol{v} = \frac{\boldsymbol{p}}{m} = a \frac{d\boldsymbol{x}}{dt} = \boldsymbol{x}'$$

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$$\boldsymbol{u}; \quad \theta = \partial_i u^i$$

- The linear power spectrum (filling in a gap in Lecture I)
- Almost-scale-invariant power spectrum from inflation: $P_{\mathcal{R}}(k) = 2\pi^2 \mathcal{A}_s k^{-3} \left(\frac{k}{k_p}\right)^{n_s - 1}$
- Relating δ to curvature perturbation:

$$\delta^{(1)}(\boldsymbol{k},\eta) = \frac{2k^2 a(\eta)}{3\Omega_m H_0^2} \Phi(\boldsymbol{k},\eta); \quad \Phi(\boldsymbol{k},\eta) = \frac{3}{5}T(k)\frac{D(a)}{a}\mathcal{R}(\boldsymbol{k})$$

Note: throughout, δ is in synchronous-comoving gauge. Then this relation remains valid on all scales.

$$P_{\rm L}(k,a) = \frac{8\pi^2}{25} \frac{\mathcal{A}_s}{\Omega_{\rm m}^2} D_+^2(a) T^2(k) \frac{k^{n_s}}{H_0^4 k_{\rm p}^{n_s - 1}}$$

Result:

 $(D_+ \equiv D)$

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Transfer function: evolution of perturbations in early Universe

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 Time dependence of linear P(k) ~ D²,
$$(D_+ \equiv D)$$

Structure formation beyond perturbation theory

- In order to take phasespace evolution into account properly, need to go beyond fluid picture and perturbation theory.
- Back to collisionless Boltzmann equation!
- Instead of trying to calculate 6D distribution function, we will discretize the thin phasespace sheet that (dark) matter is localized in

N-body simulations

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- Follow the evolution of phasespace elements ("particles") by integrating the geodesic equation (characteristics of the PDE)



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• Equations of motion:

Eq. (12.57)

N-body simulations in one step

- Structure appears after just one time step!
- Specifically, solve for particle displacement at linear order: 1st order Lagrangian perturbation theory (Zel'dovich approximation)
- Technique used to generate initial conditions for full simulations at high z





Time integration

- Leapfrog scheme: preserves energy (as well as other constants of motion) to cubic order in time step
 - **1.** Compute the gravitational potential generated by the collection of particles, and take its gradient to obtain $\nabla \Psi(\mathbf{x}, t)$
- 2. Change each particle's momentum ("kick") by

$$\boldsymbol{p}_{c}^{(i)}(t + \Delta t/2) = \boldsymbol{p}_{c}^{(i)}(t - \Delta t/2) - m\nabla\Psi(\boldsymbol{x}^{(i)}, t)\Delta t.$$
(12.59)

3. Move each particle position ("drift") by

$$\mathbf{x}^{(i)}(t + \Delta t) = \mathbf{x}^{(i)}(t) + \frac{\mathbf{p}_c^{(i)}(t + \Delta t/2)}{ma^2(t + \Delta t/2)}\Delta t.$$
 (12.60)

4. Repeat.



Credit: Raul Angulo

Solving for the force

- In order to move particles, we need to calculate the force (gradient of the potential) at each particle's position
- As accurately as possible, but with reasonable cost
- Example: could directly sum up forces of all other particles (direct summation or particle-particle algorithm)

$$abla \Psi(oldsymbol{x}_i) = Gm \sum_{j \neq i} rac{oldsymbol{x}_j - oldsymbol{x}_i}{|oldsymbol{x}_j - oldsymbol{x}_i|^3}$$

- Problem: computational cost scales as N^2 for N particles
- Our goal is to use billions of particles, so algorithm has to scale as N or N log N at most.

Reminder: N-body particles are not actual particles!

Solving for the force

- Simplest solution: solve potential on a fixed grid: *particle-mesh (PM) algorithm*
- I. Assign particles to grid to obtain density/(most commonly using cloud-in-cell [CIC] assignment)
- 2. Solve Poisson equation on grid, via discrete Fast Fourier Transform (FFT) $\nabla^2 \Psi = \nabla^2 \Psi$
- 3. Interpolate gradient of resulting potential to each particle's position (using same interpolation scheme)
 - Cost: N log N due to FFT



$$\Psi^2 \Psi = \frac{3}{2} \Omega_{\rm m}(\eta) (aH)^2 \delta_{\rm m}.$$

The resolution problem

- Issue: fixed grid means fixed resolution
- Cannot resolve small-scale structure below grid resolution, and increasing resolution is memory- and CPU-intensive ($\sim N_{grid}^3$)
- On the other hand, we don't need high resolution for a large fraction of the volume



The resolution problem

- Issue: fixed grid means fixed resolution
- On the other hand, we don't need high resolution for a large fraction of the volume
- Solution: adaptive algorithms which go to higher resolution only where necessary



Adaptive mesh refinement

- Start with regular base grid
- Split any cell that crosses a certain particle number threshold into 8 sub-cells; repeat process until particle number sufficiently small in all cells
- Advantage: can use same grid for hydrodynamics
- Disadvantage: need relaxation method to solve Poisson equation on subgrids to incorporate boundary conditions



Tree algorithm

• Get rid of grid: instead, lump particles together to compute their effect on distant other particles



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At each node in the tree, one inserts a 'meta' particle that carries the mass and sits at the centre of mass of the branch of the tree. The total interaction

$$\phi(\mathbf{x}) \propto \sum_{j} \frac{1}{|\mathbf{x} - \mathbf{x}_{j}|} = \sum_{j} \frac{1}{|(\mathbf{x} - \mathbf{\lambda}) - (\mathbf{x}_{j} - \mathbf{\lambda})|}$$
sum can be multipole expanded using
$$\frac{1}{|\mathbf{y} + \mathbf{\lambda} - \mathbf{x}_{j}|} \simeq \frac{1}{|y|} - \mathbf{y} \cdot \frac{\mathbf{\lambda} - \mathbf{x}_{j}}{|\mathbf{y}|^{3}} + \dots$$

If we set λ to be the centre of mass, then the dipole vanishes. The trick is now that since we know that $|mathbfx_j - \lambda|$ is bounded by the space partitioning cell size, we can directly control the accuracy by accepting a meta particle as a valid approximation for the entire branch if

$$\theta = \frac{\ell}{|\mathbf{y}|} < \theta_c, \tag{3.28}$$

On small scales, use force softening to avoid particle "collisions", hard scattering.

Credit: Oliver Hahn's lecture notes

- actual particle

Tree algorithm

- Get rid of grid: instead, lump particles together to compute their effect on distant other particles
- Advantage: elegant and direct, no need for relaxation
- Disadvantage: need top-level grid for periodic boundary conditions, and hence split into grid and tree forces (<u>Tree-PM</u>)



Examples: Gadget, PKDgrav

First N-body calculation: light bulbs, photocells and galvanometers

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ON THE CLUSTERING TENDENCIES AMONG THE NEBULAE

II. A STUDY OF ENCOUNTERS BETWEEN LABORATORY MODELS OF STELLAR SYSTEMS BY A NEW INTEGRATION PROCEDURE

ERIK HOLMBERG



21

N-body calculation supports the idea of dark Matter

A rotating group of 300 bodies ends up *too* concentrated.

1970-1974, Princeton



Dark matter (M/L=10) is needed to stabilize the system



Credit: Raul Angulo

1985: The CDM model plus gravitational instability can explain qualitatively the observed universe



Credit: Raul Angulo

2017: EUCLID Flagship Simulation



Credit: Raul Angulo

Result of an N-body simulation

- Catalog of "particle" positions and velocities at various points in time
- Basically, position of the phase-space sheet after gravitational evolution
- Use this to degenerate density field, for example

FIGURE 12.6 Slices of width $15 h^{-1}$ Mpc through the density field at redshift zero in the *Millennium* N-body simulation which follows 10^{10} particles (i.e., phase-space elements). From top to bottom, the different panels zoom in to show the hierarchical nature of the matter distribution in a Λ CDM cosmology. The spatial scale is labeled in each panel. The color scale denotes density in logarithmic units. The simulations shown here are described in Springel et al. (2005).



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<u>Millennium simulation</u> (Volker Springel) Logarithmic color scale, comoving length units

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Phenomenology of nonlinear structure

- Small-scale density fluctuations are largest: small-scale structure forms first
- Then, structure successively assembles to large-mass objects
- Topologically, we have
 - "3D:" voids large underdense regions
 - "2D:" sheets, or "pancakes"
 - "ID:" filaments
 - "0D:" bound structures halos

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Dark matter halos

- Bound structures of dark matter and baryons
- Densest regions in the universe (from a cosmologist's viewpoint...)
- All galaxies are believed to be hosted by dark matter halos
 - Strong observational evidence for this from <u>dynamics</u> (velocities of gas, galaxies) and <u>gravitational lensing</u>, both of which probe all matter
- The most massive halos are associated with galaxy clusters
- Still, halos are mostly studied as objects in simulations

Finding dark matter halos

- Halos are found using tools called *halo finders* which work on the catalog of particle positions
- Start from density maxima in the density field
- Determine whether particles are bound by comparing velocity w.r.t center of mass with local escape velocity
- Repeat this iteratively, since center of mass changes when particles are added
- Algorithms differ in detail

The issue of halo mass

- Strict definition, counting all particles that are bound, is not very practical: affected by numerical noise, and we don't observe dark matter anyway
- Definition based on maximum radius is more practical; however, no well-defined radius exists, since halo profiles smoothly transition to surrounding structure
- Instead, define mass and radius which enclose fixed density Δ times cosmic mean:

$$\frac{M(\langle R_{\Delta})}{4\pi R_{\Delta}^3/3} = \Delta \times \rho_{\rm m}(t_0), \qquad M_{\Delta} = M(\langle R_{\Delta})$$

• Special case $\Delta = 1$: Lagrangian radius R_L . Comoving size of region from which particles originated in the initial conditions. Important! $M = \frac{4\pi}{3} \bar{\rho}_m(t_0) R_L^3$

Halo abundance

- Mean number density of halos in logarithmic mass bins
- Power-law at small masses
- Exponential cutoff at high masses - reflecting Gaussian statistics of initial density field



Angulo et al 2012

Inner structure of halos

 Spherically-averaged density profile: Navarro-Frenk-White (1996) (NFW) form is universal



Springel et al 2008

Eq. (12.62)

$$\rho(r) = \frac{\rho_s}{(r/r_s)(1 + (r/r_s))^2}$$
$$\ln \rho(r) / \rho_{-2} = (-2/\alpha) (r/r_{-2})^{\alpha}$$

Smooth distribution

Density profile is described by NFW/Einasto functional form, independent of mass, Cosmology, etc



Slide credit: Raul Angulo

Inner structure of halos

• However, halos formed from smaller previous formed halos, which survive as substructure (subhalos)



Slide credit: Raul Angulo

From halos to galaxies

- We think that galaxies reside in these substructures of halos - but which ones...?
- Galaxy formation and (effective field) theory of galaxy clustering: next lecture!



Springel et al 2008