A continuous-opinion model inspired by the physics of granular gases

Nagi Khalil nagi.khalil@urjc.es

Universidad Rey Juan Carlos

Workshop on Sociophysics: Social Phenomena from a Physics Perspective October 18-22, 2021

Physica A 572, 125902 (2021)

▲ロ ▶ ▲周 ▶ ▲ 国 ▶ ▲ 国 ▶ ● の Q @

## Motivation

Analogy between continuous-opinion models & granular gases in 1D

Evolution toward consensus is important

(ロ)、(型)、(E)、(E)、 E) のQ(()

# **Opinion model**

#### System:

- N agents on a network with adjacency matrix  $A_{ij}$
- The state/opinion of agent i is  $s_i \in (-\infty,\infty)$
- The state of the system at a given time is  $S \equiv \{s_i\}_{i=1}^N$

# Opinion model

#### System:

- N agents on a network with adjacency matrix  $A_{ij}$
- The state/opinion of agent i is  $s_i \in (-\infty, \infty)$
- The state of the system at a given time is  $S \equiv \{s_i\}_{i=1}^N$

#### Dynamics:

- Choose two agents i and j with a rate

$$\pi(s_i, s_j) = rA_{ij}\rho(s_i - s_j)$$

where r > 0,  $\rho(x) \ge 0$ 

- Interaction/collision:

$$\begin{array}{rcl} s_i & \rightarrow & b_{ij}s_i \equiv s_i' \equiv s_i + \mu(s_j - s_i) \\ s_j & \rightarrow & b_{ij}s_j \equiv s_j' \equiv s_j - \mu(s_j - s_i) \end{array}$$

where  $\mu \in [0,1]$  is the persuasibility

・ロト・西・・日・・日・・日・

### Relation with other models

Deffuant model is recovered when:

- $A_{ij} = 1$
- $\mu \in [0,1/2]$
- Initially  $s_i \in [0,1]$  for all i
- And

$$ho(s_i-s_j) = egin{cases} 1 & ext{if} & |s_i-s_j| \leq \epsilon \ 0 & ext{if} & |s_i-s_j| > 0 \end{cases}$$

▲□▶ ▲□▶ ▲ 三▶ ▲ 三▶ 三三 - のへぐ

 $\epsilon\equiv$  bound of confidence

## Relation with other models

Deffuant model is recovered when:

- $A_{ij} = 1$
- $\mu \in [0,1/2]$
- Initially  $s_i \in [0,1]$  for all i
- And

$$ho(s_i - s_j) = egin{cases} 1 & ext{if} & |s_i - s_j| \leq \epsilon \ 0 & ext{if} & |s_i - s_j| > 0 \end{cases}$$

▲□▶ ▲□▶ ▲ 三▶ ▲ 三▶ 三 のへぐ

 $\epsilon\equiv$  bound of confidence

#### "Voter" model

- $\mu = 1$
- $\rho = 1$
- Trivial limit: both agents copy simultaneously

## Properties

(i) Conservation of the "total opinion":

$$s_i' + s_j' = s_i + s_j$$

▲□▶ ▲□▶ ▲ 三▶ ▲ 三▶ 三三 - のへぐ

### Properties

(i) Conservation of the "total opinion":

$$s_i' + s_j' = s_i + s_j$$

(ii) One consensus state:

$$s_i = \overline{s} \equiv \frac{1}{N} \sum_{k=1}^N s_k, \qquad i = 1, \dots, N$$

◆□▶ ◆□▶ ◆ 臣▶ ◆ 臣▶ ○ 臣 ○ の Q @

### Properties

(i) Conservation of the "total opinion":

$$s_i' + s_j' = s_i + s_j$$

(ii) One consensus state:

$$s_i = \overline{s} \equiv rac{1}{N} \sum_{k=1}^N s_k, \qquad i = 1, \dots, N$$

(iii) Dissipation of "opinion energy":

$$(s_i'^2 + s_j'^2) - (s_i^2 + s_j^2) = -2\mu(1-\mu)(s_i - s_j)^2 \le 0$$

▲□▶ ▲□▶ ▲ 三▶ ▲ 三▶ 三三 - のへぐ

# Analogy/difference with a 1D granular gas

- One-dimensional granular gas with

 $s \longrightarrow$  velocity  $\mu = rac{1+lpha}{2}; \quad lpha \in [-1,1]$  coefficient of normal restitution

# Analogy/difference with a 1D granular gas

- One-dimensional granular gas with

 $s \longrightarrow$  velocity  $\mu = rac{1+lpha}{2}; \quad lpha \in [-1,1]$  coefficient of normal restitution

・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・

- Properties:
  - (i) Conservation of linear momentum
  - (ii) Zero-temperature state
  - (iii) Dissipation of energy

# Analogy/difference with a 1D granular gas

- One-dimensional granular gas with

 $s \longrightarrow$  velocity  $\mu = rac{1+lpha}{2}; \quad lpha \in [-1,1]$  coefficient of normal restitution

- Properties:
  - (i) Conservation of linear momentum
  - (ii) Zero-temperature state
  - (iii) Dissipation of energy
- But "stochastic dynamics"

### Master equation

-  $p(S, t) \equiv$  the probability density of state S at time t

$$\partial_t p = \sum_{i>j} (|lpha|^{-1} b_{ij}^{-1} - 1) \pi(s_i, s_j) p$$

where  $b_{ij}^{-1}$  is the inverse of  $b_{ij}$ 

#### Master equation

-  $p(S, t) \equiv$  the probability density of state S at time t

$$\partial_t p = \sum_{i>j} (|lpha|^{-1} b_{ij}^{-1} - 1) \pi(s_i, s_j) p$$

where  $b_{ij}^{-1}$  is the inverse of  $b_{ij}$ 

-  $p_i(s, t) \equiv \langle \delta(s - s_i) \rangle$  probability density of  $s_i$  at time t:

$$\partial_t p_i(s_i, t) = \sum_{\{j | j \neq i\}} \int ds_j \; (|\alpha|^{-1} b_{ij}^{-1} - 1) \pi(s_i, s_j) p_{ij}(s_i, s_j, t)$$

### **Opinion temperature**

Mean opinion is conserved:

$$\overline{s} \equiv \frac{1}{N} \sum_{i} \langle s_i \rangle \qquad \Rightarrow \qquad \frac{d}{dt} \overline{s} = 0$$

**Opinion temperature**:

$$T \equiv \frac{1}{N} \sum_{i} \langle (s_i - \overline{s})^2 \rangle \qquad \Rightarrow \qquad \frac{d}{dt} T = -\zeta T$$

with  $\zeta\equiv$  cooling rate

$$\zeta\equivrac{\mu(1-\mu)}{NT}\sum_{\{i,j|i
eq j\}}\int ds_i ds_j \;(s_i-s_j)^2\pi(s_i,s_j)p_{ij}(s_i,s_j,t)\geq 0$$

◆□ ▶ ◆□ ▶ ◆ 臣 ▶ ◆ 臣 ▶ ○ 臣 ○ のへで

## Absorbing and consensus states

-  $\ensuremath{\mathcal{T}}$  is a decreasing function of time

# Absorbing and consensus states

-  $\mathcal{T}$  is a decreasing function of time

- *S* is a consensus state  $\Leftrightarrow T = 0$ 

## Absorbing and consensus states

- T is a decreasing function of time

- *S* is a consensus state  $\Leftrightarrow T = 0$ 

- An absorbing state  $(\frac{d}{dt}T = 0)$  is not necessarily a consensus state (T = 0)

\* If  $\pi(s_i, s_j) > 0$  when  $s_i \neq s_j$ , then S is a consensus state  $\Leftrightarrow S$  is an absorbing state

・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・

# Mean field

#### Two approximations:

1. Homogeneity (exact for fully-connected networks):

 $egin{aligned} A_{ij} &= 1, \ p_i(s,t) \simeq p(s,t) \end{aligned}$ 

2. Mean-field approximation ("Molecular chaos"):

 $p_{ij}(s_i,s_j,t)\simeq p_i(s_i,t)p_j(s_j,t)$ 

# Mean field

#### Two approximations:

1. Homogeneity (exact for fully-connected networks):

 $egin{aligned} A_{ij} &= 1, \ p_i(s,t) \simeq p(s,t) \end{aligned}$ 

2. Mean-field approximation ("Molecular chaos"):

 $p_{ij}(s_i, s_j, t) \simeq p_i(s_i, t)p_j(s_j, t)$ 

**Boltzmann** kinetic equation for  $f(s, t) \equiv Np(s, t)$ :

$$\partial_t f(s_i,t)\simeq \int ds_j \; (|lpha|^{-1}b_{ij}^{-1}-1)\pi(s_i,s_j)f(s_i,t)f(s_j,t)$$

# Mean field

#### Two approximations:

1. Homogeneity (exact for fully-connected networks):

 $egin{aligned} A_{ij} &= 1, \ p_i(s,t) \simeq p(s,t) \end{aligned}$ 

2. Mean-field approximation ("Molecular chaos"):

 $p_{ij}(s_i, s_j, t) \simeq p_i(s_i, t)p_j(s_j, t)$ 

**Boltzmann** kinetic equation for  $f(s, t) \equiv Np(s, t)$ :

$$\partial_t f(s_i,t)\simeq \int ds_j \; (|lpha|^{-1}b_{ij}^{-1}-1)\pi(s_i,s_j)f(s_i,t)f(s_j,t)$$

1D granular gas and the opinion model have the same **mesoscopic description** 

- The system reaches consensus for any eta > 0 and  $lpha \in (-1,1)$ 

 $f(s,t) \rightarrow N\delta(s-\overline{s})$ 

- The system reaches consensus for any eta > 0 and  $lpha \in (-1,1)$ 

 $f(s,t) \rightarrow N\delta(s-\overline{s})$ 

- Approach to consensus:

- The system reaches consensus for any eta > 0 and  $lpha \in (-1,1)$ 

 $f(s,t) \rightarrow N\delta(s-\overline{s})$ 

- Approach to consensus:
  - Scaling solution:

$$f(s,t) = Ns_0^{-1}\phi(c);$$
  $s_0 \equiv \sqrt{2T(t)};$   $c \equiv \frac{s}{s_0}$ 

- The system reaches consensus for any eta > 0 and  $lpha \in (-1,1)$ 

 $f(s,t) \rightarrow N\delta(s-\overline{s})$ 

- Approach to consensus:
  - Scaling solution:

$$f(s,t) = N s_0^{-1} \phi(c); \qquad s_0 \equiv \sqrt{2T(t)}; \qquad c \equiv \frac{s}{s_0}$$

- For 
$$eta=0$$
: 
$$\phi(c)=\frac{2\sqrt{2}}{\pi\left[1+2c^2
ight]^2}$$

- The system reaches consensus for any eta>0 and  $lpha\in(-1,1)$ 

 $f(s,t) \rightarrow N\delta(s-\overline{s})$ 

- Approach to consensus:
  - Scaling solution:

$$f(s,t) = N s_0^{-1} \phi(c); \qquad s_0 \equiv \sqrt{2T(t)}; \qquad c \equiv \frac{s}{s_0}$$

▲□▶ ▲□▶ ▲□▶ ▲□▶ ■ ●の00

- For 
$$\beta = 0$$
: 
$$\phi(c) = \frac{2\sqrt{2}}{\pi \left[1 + 2c^2\right]^2}$$

– For  $\beta > 0$ ,  $\phi$  can be approximated by the sum of **two Gaussian distributions** 

# Theory & simulations



<ロト <回ト < 注ト < 注ト æ

# Phase diagram



◆□ ▶ ◆□ ▶ ◆ □ ▶ ◆ □ ▶ ● □ ● ● ● ●

# Conclusions

- 1. The **opinion temperature** is an useful concept (absorbing and consensus states)
- 2. If the probability of two voters having different opinions is nonzero then the absorbing state coincides with the unique consensus state
- 3. For  $\pi(s_i, s_j) = r|s_i s_j|^{\beta}$  the system always reaches consensus
  - For  $|lpha| \leq |lpha_{c}|(eta)$ : 1 group of voters reaches consensus
  - For  $|\alpha| \geq |\alpha_c|(\beta)$ : 2 groups of voters reach consensus
  - **Coexistence** dominates consensus when  $|\alpha|$  is big enough (weak interaction)
  - Steady state if agents tend to be more radical with time
- 4. Straightforward generalization to higher dimensions